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## CENTRO DE INVESTIGACIÓN EN INGENIERÍA MATEMÁTICA (CI<sup>2</sup>MA)



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equations in heterogeneous media

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# An adaptive and quasi-periodic HDG method for Maxwell's equations in heterogeneous media

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## Abstract

With the aim to continue developing a hybridizable discontinuous Galerkin (HDG) method for problems arisen from photovoltaic cells modeling, in this manuscript we consider the time harmonic Maxwell's equations in an inhomogeneous bounded bi-periodic domain with quasi-periodic conditions on part of the boundary. We propose an HDG scheme where quasi-periodic boundary conditions are imposed on the numerical trace space. Under regularity assumptions and a proper choice of the stabilization parameter, we prove that the approximations of the electric and magnetic fields converge, in the  $L^2$ -norm, to the exact solution with order  $h^{k+1}$  and  $h^{k+1/2}$ , resp., where  $h$  is the meshsize and  $k$  the polynomial degree of the discrete spaces. Although, numerical evidence suggests optimal order of convergence for both variables. An *a posteriori* error estimator for an energy norm is also proposed. We show that it is reliable and locally efficient under certain conditions. Numerical examples are provided to illustrate the performance of the quasi-periodic HDG method and the adaptive scheme based on the proposed error indicator.

## 1 Introduction

Photovoltaic cells have been intensively studied in nanoscience and nanotechnology researchs, due to the possibility of obtaining electrical energy from the sunlight, which is consider as a green energy choice. This renewable resource of energy can be used in place of fossil fuels, in order to achieve lower harmful emissions into the atmosphere, a reduced carbon footprint and fewer air pollutants.

For some decades, the search of new sustainable sources of electrical energy has encouraged projects whose main goals consist on improving the capability to collect sunlight of the photovoltaic cells with periodic surface-relief gratings and increasing the electrical energy generation. In fact, one of the strategies to increase the efficiency of light harvesting by solar cells, is the use of plasmonic structures that enhance the intensity of the electromagnetic field [32]. The key idea is to texture the surface of the metallic back-reflector of a thin-film solar cell by periodic corrugations of size proportional to the wavelength. Under some conditions [32], this configuration produces an excitement of the electrons

placed on the surface of the metal, generating a wave that propagates through the surface called surface plasmon polariton (SPP) wave. For instance, this occurs when the propagation constant  $\beta^{SPP}$  of a SPP wave and the propagation constant  $\beta^{inc}$  of the incident wave satisfy  $\beta^{SPP} = \beta^{inc} + 2n\pi$ , for some  $n \in \mathbb{Z}$  in the transverse magnetic (TM) polarization, see Sections 2.1 and 2.2 of [32]. In the same direction, multiple SPP waves can be generated by placing a periodic multi-layered isotropic dielectric material on top of the metallic back-reflector [19]. Furthermore, structures involving different type of materials have been considered in order to optimize the performance of the cells, see for example [46] and references therein. In those cases, it is possible to maximize the spectrally averaged electron hole pair density and the solar-spectrum-integrated power-flux density [4, 19, 37, 45]. This optimization process is expensive from the computational point of view since the functionals to maximize depend on the solution to Maxwell's equations and also on geometric and optical parameters. This fact motivates the development and analysis of new methods able to lower the computational costs. In this regards, some authors have used numerical techniques in order to state and approximate the solution of boundary value problems, in which the effect of unpolarized or polarized incident plane waves on the surface of the cell and a wide range of geometrical and optical parameters in the frequency-domain Maxwell's equations, have been considered. Among them, we highlight the exact modal method [23], the moment method (MoM) [33], the rigorous coupled-wave approach (RCWA) [37, 46], the finite-difference time-domain (FDTD) method [27], the finite element method (FEM) [5, 26, 35, 36, 42, 46], and hybridizable discontinuous Galerkin (HDG) methods [10, 11, 13, 14, 20, 39, 47]. We focus our study in the latter.

Perhaps, from the numerical analysis point of view, three main challenges arise from the model: the complex-valued electric permittivity, the quasi-periodic boundary condition and the outgoing radiation condition above and below the solar cell structure. Most of the known studies assume a positive electric permittivity and consider prescribed boundary data. Under that assumption, in [20] an HDG method to study the three-dimensional time harmonic Maxwell's equations coupled with the impedance boundary condition was proposed, in the case of high wave numbers. The stability and error estimates for the method were deduced by employing the constraint  $\kappa h \leq 1$ . Based on the reliable results showed in the above work and in [14, 39], some authors considered complex-valued permittivities [10, 35, 47] and not perfect conducting boundary conditions. More precisely, in [47] a high-order HDG scheme for Maxwell's equations augmented with the hydrodynamic model, for the conduction-band electrons in noble metals, is stated. The radiation conditions can be handled by boundary element methods [24], absorbing boundary conditions (ABCs) [38], Dirichlet-to-Neumann (DtN) techniques, based on Fourier expansions [1] and by the perfectly matched layer (PML) technique, [8, 15, 41].

Inspired in the application described above, in this work we consider a problem in which the time harmonic Maxwell's equations are defined in a bounded domain  $\Omega \subset \mathbb{R}^3$  occupied by one period of a bi-periodic structure, illuminated by an incident electromagnetic wave. Our heterogeneous domain  $\Omega$  corresponds to the disjoint union between the region  $\Omega_d$ , occupied by an isotropic dielectric material with positive real relative permittivity and a metallic region denoted  $\Omega_m$ , whose relative permittivity is a complex-valued number with negative real part, see [10]. On the top and bottom boundaries of the unit cell, we consider Dirichlet type conditions and impose quasi-periodic conditions on the vertical walls of  $\Omega$ . Quasi-periodic conditions can be added to the system of equations defined in symmetric or asymmetric domains with periodic characteristics, see Sections 3.1 and 3.3 of [26] and Section 2 of [48]. These kind of boundary conditions differ by a complex exponential factor or Bloch phase, on the parallel walls of the domain. In order to carry out an a priori error analysis of our 3D problem subjected to Dirichlet and quasi-periodic conditions, we based on the analysis developed in [10]. Even though we are not considering exactly the original model since we impose boundary



condition at the top and bottom walls instead of dealing with the outgoing radiation condition, this “simplified” problem poses several challenges that must be addressed first. Therefore, we consider the analysis that we will present in this manuscript constitutes as a key stepping stone towards the goal of studying the full model.

On the other hand, the change of material across the non-smooth metallic interface, might produce singularities near the corners. Moreover, as previously discussed, the magnitude of electromagnetic field is high near the metal surface due to the plasmonic effect. Therefore, in that region, the finite element mesh must be fine enough to capture this phenomena accurately. This can be efficiently achieved by an adaptive scheme able to detect where to localize the mesh refinement based on an error indicator.

In the case of an *a posteriori* error indicator for Maxwell’s equations, one of the main challenges are the non-coercivity of the bilinear form and the low regularity of the exact solution. Residual based *a posteriori* error estimates for Maxwell’s equations in electromagnetic scattering problems were introduced in [7, 34]. The author in [34] showed how an *a posteriori* error indicator can be derived using an adjoint equation approach and also the fact that there is a limit on the maximum diameter of the elements in a grid, imposed by the non-coercivity of the bilinear form. Later, [43] proved the reliability of the residual error estimators on Lipschitz domains, which had been proposed and analyzed in [7]. In [28], the authors derived an *hp*-type *a posteriori* error estimate for the time-harmonic Maxwell’s equations and, in [31], carried out an *a posteriori* error analysis for the time-dependent Maxwell’s equations. For the steady state coercive Maxwell’s equations, the authors in [13] provided a computable residual-based *a posteriori* error estimator, which is independent of the regularity parameter of the solution and it is based on the error measured in terms of a mesh-dependent energy norm. On the other hand, by using hierarchical basis, [6] proposed a hierarchical error estimator for quasi-magnetostatic eddy current problem discretized by means of lowest order curl-conforming finite elements on tetrahedral meshes. They provided a saturation assumption in order to guarantee the reliability and efficiency of the estimator.

In this manuscript, we extend the residual-based *a posteriori* error estimator for the coercive Maxwell’s equations, developed in [13]. We will establish reliability and local efficiency of the error estimator proposed for our HDG scheme, by using approximation properties of continuous functions, Helmholtz decompositions, the Scott-Zhang interpolation operator and a standard localization technique, based on element and face bubble functions [2]. Moreover, in the context of discontinuous Galerkin methods, it is crucial the use of a continuous approximation of a discontinuous piecewise polynomial function [29, 30], sometimes called Oswald interpolant inspired in the work by [40] for piecewise linear approximations. This interpolant has been employed in the deduction of *a posteriori* error estimator for HDG methods [3, 12, 16, 17]. In our case, we modify this operator in such a way that it preserves quasi-periodic boundary conditions (see Appendix A.2).

The rest of this paper is organized as follows. In Section 2 we define the truncated domain and introduce the boundary value problem. In Section 3, we propose an HDG method and prove it is well posed. Then, we briefly describe the stability analysis and the error analysis for the method. The residual-based *a posteriori* error estimator for our HDG method is developed and analyzed in the fourth section. Finally, in Section 5 we show some numerical results by using uniform refined meshes and adaptive refined meshes.

## 2 Problem statement

Through the manuscript we will use standard simplified terminology for Sobolev spaces and norms, where vector-valued functions are bold-faced. In particular, if  $\mathcal{O}$  is a domain in  $\mathbb{R}^3$ ,  $\Sigma$  is an open or closed Lipschitz curve, and  $s \in \mathbb{R}$ , we set  $\mathbf{H}^s(\mathcal{O}) := [\mathbf{H}^s(\mathcal{O})]^3$ ,  $\mathbf{H}^s(\Sigma) := [\mathbf{H}^s(\Sigma)]^3$  and their corresponding norms  $\|\cdot\|_{s,\mathcal{O}}$  for  $\mathbf{H}^s(\mathcal{O})$  and  $\mathbf{H}^s(\Sigma)$ ; and  $\|\cdot\|_{s,\Sigma}$  for  $\mathbf{H}^s(\Sigma)$  and  $\mathbf{H}^s(\Sigma)$ . In the case  $s = 0$ , we write  $L^2(\mathcal{O})$ ,  $\mathbf{L}^2(\mathcal{O})$ ,  $L^2(\Sigma)$  and  $\mathbf{L}^2(\Sigma)$  instead of  $H^0(\mathcal{O})$ ,  $\mathbf{H}^0(\mathcal{O})$ ,  $H^0(\Sigma)$  and  $\mathbf{H}^0(\Sigma)$ , respectively; and in the notation for their norms, the first subindex will not be included. For  $s > 0$ , we write  $|\cdot|_{s,\mathcal{O}}$  for the  $H^s$ - and  $\mathbf{H}^s$ -seminorms. From ahead,  $\mathbb{P}_k(\mathcal{O})$  denotes the space of complex-valued polynomials of degree less or equal than  $k \geq 0$ ,  $\mathbf{P}_k(\mathcal{O}) := [\mathbb{P}_k(\mathcal{O})]^3$  and by  $(\cdot, \cdot)_{\mathcal{O}}$  and  $\langle \cdot, \cdot \rangle_{\partial\mathcal{O}}$ , we denote the  $L^2(\mathcal{O})$  and  $L^2(\partial\mathcal{O})$  inner products, respectively.

In addition, we introduce the following spaces

$$\begin{aligned} \mathbf{H}(\operatorname{div}_{\epsilon}; \mathcal{O}) &:= \{\mathbf{w} \in \mathbf{L}^2(\mathcal{O}) : \nabla \cdot (\epsilon \mathbf{w}) \in L^2(\mathcal{O})\}, \\ \mathbf{H}(\operatorname{div}_{\epsilon}^0; \mathcal{O}) &:= \{\mathbf{w} \in \mathbf{L}^2(\mathcal{O}) : \nabla \cdot (\epsilon \mathbf{w}) = 0\}, \\ \mathbf{H}_0(\operatorname{div}; \mathcal{O}) &:= \{\mathbf{w} \in \mathbf{H}(\operatorname{div}; \mathcal{O}) : \mathbf{w} \cdot \mathbf{n}|_{\partial\mathcal{O}} = 0\}, \\ \mathbf{H}_{\vartheta}(\operatorname{div}; \mathcal{O}) &:= \{\mathbf{w} \in \mathbf{H}(\operatorname{div}; \mathcal{O}) : \mathbf{w} \cdot \mathbf{n}|_{\vartheta} = 0\}, \\ \mathbf{H}(\mathbf{curl}; \mathcal{O}) &:= \{\mathbf{w} \in \mathbf{L}^2(\mathcal{O}) : \nabla \times \mathbf{w} \in \mathbf{L}^2(\mathcal{O})\}, \\ \mathbf{H}_0(\mathbf{curl}; \mathcal{O}) &:= \{\mathbf{w} \in \mathbf{H}(\mathbf{curl}; \mathcal{O}) : \mathbf{w} \times \mathbf{n}|_{\partial\mathcal{O}} = 0\}, \\ \mathbf{H}_{\vartheta}(\mathbf{curl}; \mathcal{O}) &:= \{\mathbf{w} \in \mathbf{H}(\mathbf{curl}; \mathcal{O}) : \mathbf{w} \times \mathbf{n}|_{\vartheta} = 0\}, \end{aligned}$$

where  $\vartheta \subset \partial\mathcal{O}$  and  $\mathbf{n}$  denotes the outward unit normal vector to  $\partial\mathcal{O}$ . For a vector-valued function  $\mathbf{w}$  defined on a face  $F$ , we denote by  $\mathbf{w}^t := (\mathbf{n} \times \mathbf{w}) \times \mathbf{n}$  and  $\mathbf{w}^n := (\mathbf{w} \cdot \mathbf{n})\mathbf{n}$  its tangential and normal components, respectively. It follows that  $\mathbf{w} := \mathbf{w}^t + \mathbf{w}^n$  and  $\mathbf{w}^t \times \mathbf{n} = \mathbf{w} \times \mathbf{n}$ .

Furthermore, to avoid proliferation of unimportant constants, the expression  $A \leq CB$ , for some  $C > 0$  independent of the meshsize, will be replaced by  $A \lesssim B$ .

Now, let us characterize our simply connected domain  $\Omega := (0, L) \times (0, L) \times (0, M)$ , with  $L, M > 0$  with polyhedral connected boundary  $\Gamma := \Gamma_1 \cup \Gamma_2 \cup \Gamma_3 \cup \Gamma_4 \cup \Gamma_B \cup \Gamma_T$ . Here,

$$\begin{aligned} \Gamma_1 &:= \{(0, y, z) : y \in (0, L), z \in (0, M)\}, & \Gamma_2 &:= \{(L, y, z) : y \in (0, L), z \in (0, M)\}, \\ \Gamma_3 &:= \{(x, 0, z) : x \in (0, L), z \in (0, M)\}, & \Gamma_4 &:= \{(x, L, z) : x \in (0, L), z \in (0, M)\}, \\ \Gamma_B &:= \{(x, y, 0) : x \in (0, L), y \in (0, L)\}, & \Gamma_T &:= \{(x, y, M) : x \in (0, L), y \in (0, L)\}. \end{aligned}$$

In applications arising from solar cell modeling,  $\Omega$  corresponds to one period of a bi-periodic array, where the unit cells are joined through quasi-periodic boundary conditions, which are imposed on the vertical walls of  $\Omega$ ,  $\Gamma_1$ - $\Gamma_2$  and  $\Gamma_3$ - $\Gamma_4$ . In this phenomenon, after the sunlight illuminates the top boundary  $\Gamma_T$ , outgoing and evanescent waves are generated, below the bottom boundary  $\Gamma_B$  and above  $\Gamma_T$ , as well. In this work we assume that the data on  $\Gamma_B$  and  $\Gamma_T$  are prescribed, but we consider quasi-periodic boundary conditions on  $\Gamma_1$ - $\Gamma_2$  and  $\Gamma_3$ - $\Gamma_4$ .

The domain  $\Omega$  is divided in two subdomains. A dielectric region  $\Omega_d$  with permittivity  $\epsilon_d \in \mathbb{R}^+$  and a metallic region  $\Omega_m$  with electric permittivity  $\epsilon_m \in \mathbb{C}$ , satisfying  $\operatorname{Re}(\epsilon_m) < 0$  and  $\operatorname{Im}(\epsilon_m) > 0$ , as it was shown in Figure 1.

Given  $\mathbf{J} \in \mathbf{H}(\operatorname{div}^0; \Omega)$  and  $\hat{\mathbf{g}} \in \gamma_t \left( \mathbf{H}(\mathbf{curl}; \Omega) \cap \mathbf{H}(\operatorname{div}_{\epsilon}^0; \Omega) \right)$ , where  $\gamma_t$  denotes the tangential trace

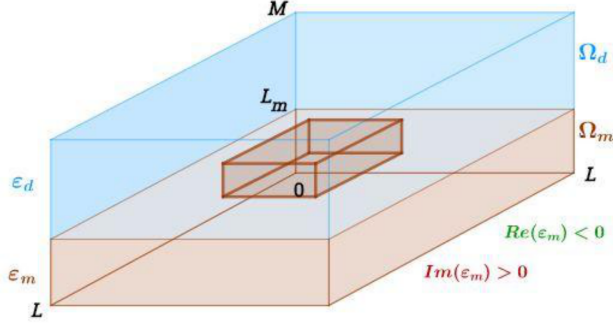


Figure 1: Example of a domain  $\Omega$ : a dielectric region  $\Omega_d$  placed on top of a metallic backreflector  $\Omega_m$ .

operator, we look for  $\mathbf{E}$  and  $\mathbf{H}$  such that

$$\nabla \times \mathbf{E} = i\omega\mu_0\mathbf{H}, \quad \text{in } \Omega, \quad (1a)$$

$$\nabla \times \mathbf{H} = \mathbf{J} - i\omega\epsilon_0\epsilon\mathbf{E}, \quad \text{in } \Omega, \quad (1b)$$

$$\mathbf{E} \times \mathbf{n} = \hat{\mathbf{g}}, \quad \text{on } \Gamma_B \cup \Gamma_T, \quad (1c)$$

$$\mathbf{E}(L, y, z) = e^{i\alpha L}\mathbf{E}(0, y, z), \quad y \in (0, L), z \in (0, M), \quad (1d)$$

$$\mathbf{E}(x, L, z) = e^{i\beta L}\mathbf{E}(x, 0, z), \quad x \in (0, L), z \in (0, M), \quad (1e)$$

where  $\mathbf{E}$  denotes the electric field,  $\mathbf{H}$  the magnetic field and  $\mathbf{J}$  the current density, which satisfy an implicit  $e^{-i\omega t}$  dependence of time at frequency  $\omega > 0$ . The other parameters are the permeability of free space  $\mu_0$ , the electric permittivity of free space  $\epsilon_0$ , the electric permittivity  $\epsilon$ , the relative permittivity  $\epsilon_0\epsilon$ , the free-space wavenumber  $\kappa := \omega\sqrt{\epsilon_0\mu_0}$ , the free-space wavelength  $\lambda_0 := 2\pi/\kappa$  and the intrinsic impedance of the free space  $\eta_0 := \sqrt{\mu_0/\epsilon_0}$ . Furthermore,  $\mu_0 = 4\pi \times 10^{-7} \text{ Hm}^{-1}$ ,  $\epsilon_0 = 8.854 \times 10^{-12} \text{ Fm}^{-1}$ ,  $\mathbf{n}$  denotes the outward unit normal to  $\Gamma$  and the permittivity is defined as  $\epsilon = \epsilon_m$  in  $\Omega_m$  and  $\epsilon = \epsilon_d$  in  $\Omega_d$ . According to the theory that appears in Section 1.3 of [35], the solutions of (1) exist and have the form of a plane wave. A plane wave is defined as an electromagnetic wave whose polarization,  $\mathbf{A}$ , satisfies the property  $\mathbf{A} \cdot (\alpha, \beta, \gamma) = 0$ , for  $\alpha := \kappa \sin \theta \cos \phi$ ,  $\beta := \kappa \sin \theta \sin \phi$  and  $\gamma := \kappa \cos \theta$ , with  $\theta \in [0, \pi]$  and  $\phi \in [0, 2\pi]$ . Based on the form of the solutions it is possible to characterize the *quasi-periodic boundary conditions*, which in this problem were added by the equations (1d) and (1e).

Let us introduce in (1) the change of variable  $\mathbf{u} := \epsilon_0^{1/2}\mathbf{E}$ ,  $\mathbf{v} := i\kappa\mu_0^{1/2}\mathbf{H}$ . By a Lagrange multiplier  $p$ , we impose the incompressibility condition  $\nabla \cdot (\epsilon\mathbf{E}) = 0$ , which can be deduced from the second equation. For a more detailed description of (1), we refer to [35]. Then, we obtain the following problem: Find  $\mathbf{u}$ ,  $\mathbf{v}$  and  $p$  such that

$$\mathbf{v} - \nabla \times \mathbf{u} = 0, \quad \text{in } \Omega, \quad (2a)$$

$$\nabla \times \mathbf{v} - \kappa^2\epsilon\mathbf{u} + \bar{\epsilon}\nabla p = \mathbf{f}, \quad \text{in } \Omega, \quad (2b)$$

$$\nabla \cdot (\epsilon\mathbf{u}) = 0, \quad \text{in } \Omega, \quad (2c)$$

$$\mathbf{u} \times \mathbf{n} = \mathbf{g}, \quad \text{on } \Gamma_B \cup \Gamma_T, \quad (2d)$$

$$\mathbf{u}(L, y, z) = e^{i\alpha L}\mathbf{u}(0, y, z), \quad y \in (0, L), z \in (0, M), \quad (2e)$$

$$\mathbf{u}(x, L, z) = e^{i\beta L}\mathbf{u}(x, 0, z), \quad y \in (0, L), z \in (0, M), \quad (2f)$$

$$p = 0, \quad \text{on } \Gamma, \quad (2g)$$

where  $\mathbf{f} := i\kappa\mu_0^{1/2}\mathbf{J}$ ,  $\mathbf{g} := \epsilon_0^{1/2}\hat{\mathbf{g}}$  and  $\bar{\epsilon}$  is the complex conjugate of  $\epsilon$ . In order to simplify notation, we define  $\Gamma_0 := \Gamma_B \cup \Gamma_T$  and  $\Gamma_{QP} := \Gamma_1 \cup \Gamma_2 \cup \Gamma_3 \cup \Gamma_4$ .

Now, let us introduce the spaces

$$\begin{aligned} H^{QP}(\mathbf{curl}; \Omega) &:= \left\{ \mathbf{w} \in H(\mathbf{curl}; \Omega) : \mathbf{w}|_{\Gamma_2} = e^{i\alpha L} \mathbf{w}|_{\Gamma_1}, \mathbf{w}|_{\Gamma_4} = e^{i\beta L} \mathbf{w}|_{\Gamma_3} \right\}, \\ H_{\Gamma_0}^{QP}(\mathbf{curl}; \Omega) &:= \left\{ \mathbf{w} \in H^{QP}(\mathbf{curl}; \Omega) : \mathbf{w} \times \mathbf{n}|_{\Gamma_0} = 0 \right\}, \\ \mathbf{X}_{QP} &:= H_{\Gamma_0}^{QP}(\mathbf{curl}; \Omega) \cap H(\text{div}_\epsilon^0; \Omega), \\ \mathbf{X}_{QP}^{\mathbf{g}} &:= \left\{ \mathbf{w} \in H^{QP}(\mathbf{curl}; \Omega) \cap H(\text{div}_\epsilon^0; \Omega) : \mathbf{w} \times \mathbf{n}|_{\Gamma_0} = \mathbf{g} \right\}, \end{aligned}$$

endowed with the  $H(\mathbf{curl}; \Omega)$ -norm,  $\|\mathbf{w}\|_{H(\mathbf{curl}; \Omega)} := (\|\mathbf{w}\|_\Omega^2 + \|\nabla \times \mathbf{w}\|_\Omega^2)^{1/2}$ . With respect to the existence and uniqueness of the solutions of (2), we have the following Lemma.

**Lemma 2.1.** *If  $\kappa^2\epsilon_d$  is not an eigenvalue of  $\nabla \times \nabla \times$  in  $\Omega_d$ , then (2) has a unique solution  $(\mathbf{v}, \mathbf{u}, p) \in H(\mathbf{curl}; \Omega) \times \mathbf{X}_{QP}^{\mathbf{g}} \times H_0^1(\Omega)$ .*

*Proof.* By tailoring the proofs showed in Section 5 of [9], we can guarantee the existence of a unique solution, when  $\mathbf{g} = \mathbf{0}$ , for the following variational formulation: Find  $(\mathbf{u}, p) \in \mathbf{X}_{QP} \times H_0^1(\Omega)$  such that

$$\begin{aligned} (\nabla \times \mathbf{u}, \nabla \times \mathbf{w})_\Omega - \kappa^2(\epsilon \mathbf{u}, \mathbf{w})_\Omega &= (\mathbf{f}, \mathbf{w})_\Omega, \\ (\bar{\epsilon} \nabla p, \nabla q)_\Omega &= (\mathbf{f}, \nabla q)_\Omega, \end{aligned} \tag{3}$$

for all  $(\mathbf{w}, q) \in \mathbf{X}_{QP} \times H_0^1(\Omega)$ .

In the case  $\mathbf{g} \neq \mathbf{0}$ , we have that if  $\mathbf{g} \in \gamma_t(H(\mathbf{curl}; \Omega) \cap H(\text{div}_\epsilon^0; \Omega))$  then, there exists a unique  $\boldsymbol{\varphi} \in H(\mathbf{curl}; \Omega) \cap H(\text{div}_\epsilon^0; \Omega)$ , such that  $\gamma_t(\boldsymbol{\varphi}) = \mathbf{g}$ . Moreover, by noting that  $\mathbf{u} - \boldsymbol{\varphi} \in \mathbf{X}_{QP}$  is a solution of (3), we can conclude the uniqueness of  $\mathbf{u}$ ; from which the existence and uniqueness of the solution of (2) is deduced.  $\square$

### 3 The HDG method

Let us begin by setting a shape-regular simplicial tetrahedrization  $\mathcal{T}_h$  of  $\Omega$ , such that each  $\overset{\circ}{K} \in \mathcal{T}_h$  is completely contained in  $\Omega_m$  or  $\Omega_d$ . Then,  $\mathcal{T}_h^m$  and  $\mathcal{T}_h^d$  will denote the sets of tetrahedra lying in  $\Omega_m$  and  $\Omega_d$ , respectively. Furthermore, we define  $\partial\mathcal{T}_h := \{\partial K : K \in \mathcal{T}_h\}$  and  $\mathcal{E}_h := \mathcal{E}_I \cup \mathcal{E}_\Gamma$ , where  $\mathcal{E}_I$  and  $\mathcal{E}_\Gamma$  denote the interior and boundary faces induced by  $\mathcal{T}_h$ , respectively. Due to the definition of  $\Gamma$ , we will denote by  $\mathcal{E}_0$  and  $\mathcal{E}_{QP}$  the set of faces lying on  $\Gamma_0$  and  $\Gamma_{QP}$ , respectively. We assume  $\mathcal{T}_h$  does not have hanging nodes. Moreover, let us also suppose conformity between the discretization of the periodic boundaries  $\Gamma_1$ - $\Gamma_2$  and  $\Gamma_3$ - $\Gamma_4$ . More precisely, if  $F_1 = \{(0, y, z)\}$  is a face of  $\Gamma_1$ , we assume that  $F_2 := \{(L, y, z)\}$  is a face of  $\Gamma_2$ . Similarly for  $\Gamma_3$  and  $\Gamma_4$ . In addition, we set  $\|\cdot\|_{\mathcal{T}_h} := (\cdot, \cdot)_{\mathcal{T}_h}^{1/2}$  and  $\|\cdot\|_{\partial\mathcal{T}_h} := \langle \cdot, \cdot \rangle_{\partial\mathcal{T}_h}^{1/2}$ , with

$$(\cdot, \cdot)_{\mathcal{T}_h} := \sum_{K \in \mathcal{T}_h} (\cdot, \cdot)_K, \quad \langle \cdot, \cdot \rangle_{\partial\mathcal{T}_h} := \sum_{K \in \mathcal{T}_h} \langle \cdot, \cdot \rangle_{\partial K},$$

where  $(\cdot, \cdot)_D$  and  $\langle \cdot, \cdot \rangle_G$  denote standard  $L^2$ -complex inner products over regions  $D \subset \mathbb{R}^3$  and  $G \subset \mathbb{R}^2$ , respectively.

For a vector-valued function  $\mathbf{w}$ , we define the tangential jump across  $F \in \mathcal{E}_I$  by  $\llbracket \mathbf{w} \rrbracket_F := \mathbf{w}^+ \times \mathbf{n}^+ + \mathbf{w}^- \times \mathbf{n}^-$ . If  $F \in \mathcal{E}_0$ , we set  $\llbracket \mathbf{w} \rrbracket_F := \mathbf{w} \times \mathbf{n}$ . We will drop the subscript  $F$ , when there is no

confusion. Let us now explain the jump operator acting on a face of a quasi-periodic boundary. If  $F \subset \Gamma_1$ , we define  $[\![\mathbf{w}]\!]_{\text{QP}} := (e^{i\alpha L} \mathbf{w} \times \mathbf{n})|_{\Gamma_1} + (\mathbf{w} \times \mathbf{n})|_{\Gamma_2}$ . In other words, if  $\mathbf{w}$  is quasi-periodic on  $\Gamma_1$ , then  $[\![\mathbf{w}]\!]_{\text{QP}} = 0$ . Similarly, if  $F \subset \Gamma_3$ , we define  $[\![\mathbf{w}]\!]_{\text{QP}} := (e^{i\beta L} \mathbf{w} \times \mathbf{n})|_{\Gamma_3} + (\mathbf{w} \times \mathbf{n})|_{\Gamma_4}$ . For a scalar-valued function  $p$ , the jump across a face  $F \in \mathcal{E}_I$  is denoted by  $[\![q]\!] := q^+ - q^-$ , whereas for a boundary face  $F \in \mathcal{E}_\Gamma$ , we write  $[\![q]\!] := q$ .

Considering the above tetrahedrization of  $\bar{\Omega}$ , we define the following approximation spaces

$$\begin{aligned} \mathbf{Q}_h &:= \{q \in L^2(\Omega) : q|_K \in \mathbb{P}_k(K), \forall K \in \mathcal{T}_h\}, \\ \mathbf{M}_h &:= \{\varrho \in L^2(\mathcal{E}_h) : \varrho|_F \in \mathbb{P}_k(F), \forall F \in \mathcal{E}_h\}, \\ \mathbf{V}_h &:= \{\mathbf{w} \in \mathbf{L}^2(\Omega) : \mathbf{w}|_K \in \mathbf{P}_k(K), \forall K \in \mathcal{T}_h\}, \\ \mathbf{M}_h^t &:= \{\boldsymbol{\rho} \in \mathbf{L}^2(\mathcal{E}_h) : \boldsymbol{\rho}|_F \in \mathbf{P}_k(F), (\boldsymbol{\rho} \cdot \mathbf{n})|_F = 0, \forall F \in \mathcal{E}_h\}, \\ \mathbf{M}_{\text{QP}}^{\mathbf{g}} &:= \left\{ \boldsymbol{\rho} \in \mathbf{M}_h^t : \boldsymbol{\rho}|_{\Gamma_2} = e^{i\alpha L} \boldsymbol{\rho}|_{\Gamma_1}, \boldsymbol{\rho}|_{\Gamma_4} = e^{i\beta L} \boldsymbol{\rho}|_{\Gamma_3}, \boldsymbol{\rho}|_{\Gamma_0} \times \mathbf{n} = \mathbf{P}_{\mathbf{M}_h^t} \mathbf{g} \right\} \end{aligned}$$

where  $\mathbf{P}_{\mathbf{M}_h^t}$  is  $\mathbf{L}^2$ -projections over  $\mathbf{M}_h^t$ .

The HDG scheme associated to (2) seeks the approximation  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times \mathbf{Q}_h \times \mathbf{M}_{\text{QP}}^{\mathbf{g}} \times \mathbf{M}_h$  of the exact solution  $(\mathbf{v}, \mathbf{u}, p, \mathbf{u}^t|_{\mathcal{E}_h}, p|_{\mathcal{E}_h})$ , satisfying

$$(\mathbf{v}_h, \mathbf{w})_{\mathcal{T}_h} - (\mathbf{u}_h, \nabla \times \mathbf{w})_{\mathcal{T}_h} - \langle \hat{\mathbf{u}}_h^t, \mathbf{w} \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} = 0, \quad (4a)$$

$$(\mathbf{v}_h, \nabla \times \mathbf{z})_{\mathcal{T}_h} + \langle \hat{\mathbf{v}}_h^t, \mathbf{z} \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} - \kappa^2 (\epsilon \mathbf{u}_h, \mathbf{z})_{\mathcal{T}_h} - (p_h, \nabla \cdot (\epsilon \mathbf{z}))_{\mathcal{T}_h} + \langle \epsilon \mathbf{z} \cdot \mathbf{n}, \hat{p}_h \rangle_{\partial \mathcal{T}_h} = (\mathbf{f}, \mathbf{z})_{\mathcal{T}_h}, \quad (4b)$$

$$- (\epsilon \mathbf{u}_h, \nabla q)_{\mathcal{T}_h} + \langle \epsilon \widehat{\mathbf{u}}_h^n \cdot \mathbf{n}, q \rangle_{\partial \mathcal{T}_h} = 0, \quad (4c)$$

$$\langle \mathbf{n} \times \hat{\mathbf{v}}_h^t, \boldsymbol{\rho} \rangle_{\partial \mathcal{T}_h} = 0, \quad (4d)$$

$$\langle \epsilon \widehat{\mathbf{u}}_h^n \cdot \mathbf{n}, \varrho \rangle_{\partial \mathcal{T}_h \setminus \Gamma} = 0, \quad (4e)$$

$$\langle \hat{p}_h, \varrho \rangle_\Gamma = 0, \quad (4f)$$

for all  $(\mathbf{w}, \mathbf{z}, q, \boldsymbol{\rho}, \varrho) \in \mathbf{V}_h \times \mathbf{V}_h \times \mathbf{Q}_h \times \mathbf{M}_{\text{QP}}^0 \times \mathbf{M}_h$ , where the *numerical fluxes*  $\hat{\mathbf{v}}_h^t$  and  $\widehat{\epsilon \mathbf{u}}_h^n$  defined on  $\partial \mathcal{T}_h$  are given by

$$\mathbf{n} \times \hat{\mathbf{v}}_h^t := \mathbf{n} \times \mathbf{v}_h^t + \tau (\mathbf{u}_h^t - \hat{\mathbf{u}}_h^t), \quad (4g)$$

$$\widehat{\epsilon \mathbf{u}}_h^n \cdot \mathbf{n} := \epsilon \mathbf{u}_h^n \cdot \mathbf{n} + \tau_n (p_h - \hat{p}_h). \quad (4h)$$

The stabilization parameters  $\tau$  and  $\tau_n$  are complex-valued that satisfy  $\text{Re}(\tau) \geq 0$ ,  $\text{Im}(\tau) \leq 0$ ,  $\text{Re}(\tau_n) \geq 0$  and  $\text{Im}(\tau_n) \geq 0$ . These conditions ensure well-posedness of the scheme in agreement with Section 3 of [10].

We notice that, since the test function  $\boldsymbol{\rho}$  belongs to  $\mathbf{M}_{\text{QP}}^0$ , (4d) implies the quasi-periodicity of the numerical flux  $\hat{\mathbf{v}}_h^t$ . In fact, taking  $\boldsymbol{\rho} \neq 0$  on  $\Gamma_1 \cup \Gamma_2$  and  $\boldsymbol{\rho} = 0$  otherwise, we have that

$$\langle \mathbf{n} \times \hat{\mathbf{v}}_h^t, \boldsymbol{\rho} \rangle_{\Gamma_1} + \langle \mathbf{n} \times \hat{\mathbf{v}}_h^t, \boldsymbol{\rho} \rangle_{\Gamma_2} = 0,$$

for all  $\boldsymbol{\rho} \in \mathbf{P}_k(\Gamma_1)$ , due to the fact that  $\boldsymbol{\rho}|_{\Gamma_2} = e^{i\alpha L} \boldsymbol{\rho}|_{\Gamma_1}$ . Now, if we denote by  $\varphi$  the bijective mapping that transforms a face in  $\Gamma_2$  into its corresponding face in  $\Gamma_1$ , it holds

$$0 = \langle \mathbf{n} \times \hat{\mathbf{v}}_h^t, \boldsymbol{\rho} \rangle_{\Gamma_1} + \langle (\mathbf{n} \times \hat{\mathbf{v}}_h^t) \circ \varphi, e^{i\alpha L} \boldsymbol{\rho} \rangle_{\Gamma_1} = \langle \mathbf{n} \times \hat{\mathbf{v}}_h^t + (\mathbf{n} \times \hat{\mathbf{v}}_h^t) \circ \varphi e^{-i\alpha L}, \boldsymbol{\rho} \rangle_{\Gamma_1},$$

for all  $\boldsymbol{\rho} \in \mathbf{P}_k(\Gamma_1)$ , from which,

$$0 = (\mathbf{n} \times \hat{\mathbf{v}}_h^t + (\mathbf{n} \times \hat{\mathbf{v}}_h^t) \circ \varphi e^{-i\alpha L})|_{\Gamma_1} = \mathbf{n} \times \hat{\mathbf{v}}_h^t|_{\Gamma_1} + \mathbf{n} \times \hat{\mathbf{v}}_h^t e^{-i\alpha L}|_{\Gamma_2}.$$

**Remark 3.1.** We emphasize that  $\hat{\mathbf{u}}_h^t$  and  $\hat{\mathbf{v}}_h^t$  are “single-valued” on any face  $F \in \mathcal{E}_h \setminus \mathcal{E}_{\text{QP}}$ . Moreover, for faces in  $\mathcal{E}_{\text{QP}}$ , the numerical fluxes are also single-valued, but in a “quasi-periodic sense”, namely,  $[\![\hat{\mathbf{u}}_h^t]\!]_{\text{QP}} = 0$  and  $[\![\hat{\mathbf{v}}_h^t]\!]_{\text{QP}} = 0$ .

The authors in [10] analyzed the well-posedness and provided the error estimates for an HDG scheme similar to (4), but considered a prescribed boundary data  $\mathbf{g}$  in the entire boundary  $\Gamma$ . In our case, quasi-periodic boundary conditions are imposed on the vertical walls. This quasi-periodicity is imposed strongly on the space  $\mathbf{M}_{\text{QP}}^{\mathbf{g}}$  for the numerical trace  $\hat{\mathbf{u}}_h^t$  and implies the quasi-periodicity of the flux  $\hat{\mathbf{v}}_h^t$ , as it was explained before. These facts make possible to cancel out the contribution of the terms on  $\Gamma_1$  and  $\Gamma_2$  ( $\Gamma_3$  and  $\Gamma_4$ ), during the deduction of the stability estimates of the scheme. Therefore, the same error analysis performed in [10] holds for (4). Even more, the analysis in it implies the following result for  $s \in (0, 1)$  and  $s \leq t$  chosen as in section 3.2 of the same reference.

**Corollary 3.1.** Let  $(\mathbf{v}, \mathbf{u}, p) \in \mathbf{H}^{l_v+1}(\mathcal{T}_h) \times \mathbf{H}^{l_u+1}(\mathcal{T}_h) \times H^{l_p+1}(\mathcal{T}_h)$  and  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times Q_h \times \mathbf{M}_{\text{QP}}^{\mathbf{g}} \times M_h$  be the solutions of (2) and (4), respectively, for  $l_v, l_u, l_p \in [0, k]$ . If  $\tau$  and  $\tau_n$  are purely imaginary,  $s \in (0, 1)$  and  $s \leq t$ , there hold

$$\begin{aligned} \|\mathbf{v} - \mathbf{v}_h\|_{\mathcal{T}_h} &\lesssim h^{\min\{s, 1/2\}} \left( h^{l_v} |\mathbf{v}|_{l_v+1, \mathcal{T}_h} + h^{l_u} |\mathbf{u}|_{l_u+1, \mathcal{T}_h} + h^{l_p} |p|_{l_p+1, \mathcal{T}_h} \right) \\ \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} &\lesssim h^s \left( h^{l_v} |\mathbf{v}|_{l_v+1, \mathcal{T}_h} + h^{l_u} |\mathbf{u}|_{l_u+1, \mathcal{T}_h} + h^{l_p} |p|_{l_p+1, \mathcal{T}_h} \right), \end{aligned}$$

when  $|\tau|$  and  $|\tau_n|$  are of order one. If  $|\tau|$  is of order  $h^{-1}$  and  $|\tau_n|$  is of order  $h$ , then

$$\begin{aligned} \|\mathbf{v} - \mathbf{v}_h\|_{\mathcal{T}_h} &\lesssim h^{l_v + \min\{1, t\}} |\mathbf{v}|_{l_v+1, \mathcal{T}_h} + h^{l_u + \min\{0, t-1\}} |\mathbf{u}|_{l_u+1, \mathcal{T}_h} + h^{l_p + \min\{s+1, t\}} |p|_{l_p+1, \mathcal{T}_h} \\ \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} &\lesssim h^{l_v + \min\{1, t\}} |\mathbf{v}|_{l_v+1, \mathcal{T}_h} + h^{l_u + \min\{s, t-1\}} |\mathbf{u}|_{l_u+1, \mathcal{T}_h} + h^{l_p+1 + \min\{s, t-1\}} |p|_{l_p+1, \mathcal{T}_h}. \end{aligned}$$

In addition, if  $\tau$  and  $\tau_n$  are not purely imaginary, then there exists  $h_0 > 0$  such that for all  $h < h_0$ , the same result holds.

**Remark 3.2.** The numerical experiments reported in [10] show an experimental order of convergence better than the one predicted by the theory. More precisely, for smooth solutions and stabilization parameters with modulus proportional to one, the experimental rate of convergence is  $h^{k+1}$  for the  $L^2$ -error of the approximations of  $\mathbf{u}$ ,  $\mathbf{v}$  and  $p$ .

## 4 A posteriori error analysis

In this section assuming that  $|\tau|$  and  $|\tau_n|$  with modulus proportional to one, we propose ‘under some circumstances’ a reliable and locally efficient error estimator for the energy-type error

$$\begin{aligned} E_h &:= \|\mathbf{v} - \mathbf{v}_h\|_{\mathcal{T}_h} + \|\nabla \times (\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} + h^{-1/2} \|\tau^{1/2} (\mathbf{u}_h^t - \hat{\mathbf{u}}_h^t)\|_{\partial \mathcal{T}_h} \\ &\quad + h^{-1/2} \|\tau_n^{1/2} (p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h} + \|\nabla(p - p_h)\|_{\mathcal{T}_h} + \|\mathbf{u} - \mathbf{u}_h\|_{\mathcal{T}_h} + \|p - p_h\|_{\mathcal{T}_h}. \end{aligned} \quad (5)$$

According to Remark 3.2, the order of convergence of  $E_h$  is  $h^k$  when the solution is sufficiently smooth.

We base our analysis on the techniques presented in [13], but keeping in mind that, in our context  $\Omega$  is occupied by a heterogeneous material because the relative permittivity is a complex-valued function.

Let us begin by defining the global error indicator:

$$\eta := \sum_{K \in \mathcal{T}_h} \left( \eta_K^2 + \sum_{F \subset \partial K} \eta_{F,1}^2 + \eta_{F,2}^2 + \eta_{F,3}^2 \right) + \sum_{F \in \mathcal{E}_I} \eta_{F,4}^2,$$

where  $\eta_K$ ,  $\eta_{F,1}$ ,  $\eta_{F,2}$ ,  $\eta_{F,3}$  and  $\eta_{F,4}$  correspond to the local *a posteriori* error indicators, specified as follows.

For each  $K \in \mathcal{T}_h$ ,

$$\eta_{K,1} := h_K \|\mathbf{f} - \bar{\epsilon} \nabla p_h + \kappa^2 \epsilon \mathbf{u}_h - \nabla \times (\nabla \times \mathbf{u}_h)\|_K, \quad (6a)$$

$$\eta_{K,2} := h_K \|\nabla \cdot \mathbf{f} + \kappa^2 \epsilon \nabla \cdot \mathbf{u}_h - \nabla \cdot (\bar{\epsilon} \nabla p_h)\|_K, \quad (6b)$$

and for  $F \subset \partial K$ ,

$$\eta_{F,1} := h_F^{-1/2} \|\tau^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_F, \quad (6c)$$

$$\eta_{F,2} := h_F^{-1/2} \|\tau_n^{1/2}(p_h - \hat{p}_h)\|_F, \quad (6d)$$

$$\eta_{F,3} := h_F^{1/2} \|(\mathbf{v}_h - \nabla \times \mathbf{u}_h) \times \mathbf{n}\|_F. \quad (6e)$$

Moreover, for each  $F \in \mathcal{E}_I$ ,

$$\eta_{F,4} := h_F^{1/2} \left\| \left[ \bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}} \right] \right\|_F. \quad (6f)$$

In order to state the main result, we denote by  $\Pi_{\mathbf{V}}$  and  $\Pi_Q$  the  $L^2$ -projections over  $\mathbf{V}_h$  and  $Q_h$ , see [18].

**Theorem 4.1.** *Let  $(\mathbf{v}, \mathbf{u}, p) \in \mathbf{H}(\mathbf{curl}; \Omega) \times \mathbf{X}_{\text{QP}}^{\mathbf{g}} \times H_0^1(\Omega)$  and  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times Q_h \times \mathbf{M}_{\text{QP}}^{\mathbf{g}} \times M_h$  be the solutions of (2) and (4), respectively. Then, there exist  $C_1, C_2 > 0$  such that*

$$E_h \leq C_1 \eta \quad \wedge \quad C_2 \eta \leq E_h + \text{osc}_{\mathbf{f}} + \text{osc}_{\nabla \cdot \mathbf{f}},$$

where  $\text{osc}_{\mathbf{f}} := \sum_{K \in \mathcal{T}_h} \text{osc}(\mathbf{f}, K)$ ,  $\text{osc}(\mathbf{f}, K) := h_K \|\mathbf{f} - \Pi_{\mathbf{V}} \mathbf{f}\|_K$ ,  $\text{osc}_{\nabla \cdot \mathbf{f}} := \sum_{K \in \mathcal{T}_h} \text{osc}(\nabla \cdot \mathbf{f}, K)$  and  $\text{osc}(\nabla \cdot \mathbf{f}, K) := h_K \|\nabla \cdot \mathbf{f} - \Pi_Q(\nabla \cdot \mathbf{f})\|_K$ .

In the forthcoming sections we will derive a sequence of results that will lead to the proof of Theorem 4.1. We will employ approximation properties for discontinuous functions and bubble functions.

## 4.1 Reliability

One of the main tools, usually employed in the context of DG methods is the conforming approximation of a piecewise polynomial function. In this direction, we obtained the following lemmas by using Proposition 4.5 of [25] and Theorem 2.2 of [29].

**Lemma 4.1.** *Let  $\mathbf{w} \in \mathbf{V}_h$  and  $\tilde{\mathbf{g}}$  be the tangential trace of a function in  $\mathbf{V}_h^c := \mathbf{V}_h \cap \mathbf{H}(\mathbf{curl}; \Omega)$ . Then, there exists  $\mathbf{w}^c \in \mathbf{V}_h^c$  with  $\mathbf{w}^c \times \mathbf{n}|_{\Gamma_0} = \tilde{\mathbf{g}}$ , such that*

$$\|\mathbf{w} - \mathbf{w}^c\|_{\mathcal{T}_h} \lesssim \|h^{1/2} \llbracket \mathbf{w} \rrbracket\|_{\mathcal{E}_h \setminus \mathcal{E}_0} + \|h^{1/2}(\mathbf{w} \times \mathbf{n} - \tilde{\mathbf{g}})\|_{\mathcal{E}_0}, \quad (7a)$$

$$\|\nabla \times (\mathbf{w} - \mathbf{w}^c)\|_{\mathcal{T}_h} \lesssim \|h^{-1/2} \llbracket \mathbf{w} \rrbracket\|_{\mathcal{E}_h \setminus \mathcal{E}_0} + \|h^{-1/2}(\mathbf{w} \times \mathbf{n} - \tilde{\mathbf{g}})\|_{\mathcal{E}_0}. \quad (7b)$$

Moreover, there exists  $\mathbf{w}^{\text{QP}} \in \mathbf{V}_h^c$  with tangential trace  $\tilde{\mathbf{g}}$  on  $\Gamma_0$  and quasi-periodic conditions on  $\Gamma_{\text{QP}}$ , such that

$$\|\mathbf{w} - \mathbf{w}^{\text{QP}}\|_{\mathcal{T}_h} \lesssim \|h^{1/2} \llbracket \mathbf{w} \rrbracket\|_{\mathcal{E}_I} + \|h^{1/2} \llbracket \mathbf{w} \rrbracket_{\text{QP}}\|_{\mathcal{E}_{\text{QP}}} + \|h^{1/2}(\mathbf{w} \times \mathbf{n} - \tilde{\mathbf{g}})\|_{\mathcal{E}_0}, \quad (7c)$$

$$\|\nabla \times (\mathbf{w} - \mathbf{w}^{\text{QP}})\|_{\mathcal{T}_h} \lesssim \|h^{-1/2} \llbracket \mathbf{w} \rrbracket\|_{\mathcal{E}_I} + \|h^{-1/2} \llbracket \mathbf{w} \rrbracket_{\text{QP}}\|_{\mathcal{E}_{\text{QP}}} + \|h^{-1/2}(\mathbf{w} \times \mathbf{n} - \tilde{\mathbf{g}})\|_{\mathcal{E}_0}. \quad (7d)$$

In addition, let  $q \in Q_h$ . There exists  $q^c \in Q_h^c := Q_h \cap H_0^1(\Omega)$ , such that

$$\|\nabla(q - q^c)\|_{\mathcal{T}_h} \lesssim \|h^{-1/2} \llbracket q \rrbracket\|_{\mathcal{E}_I} \lesssim \|h^{-1/2}(q - \varrho)\|_{\partial\mathcal{T}_h}, \quad (7e)$$

for any singled-valued function  $\varrho$  defined over  $\mathcal{E}_h$ , such that  $\varrho|_\Gamma = 0$ .

The estimates (7a) and (7b) were proven in Proposition 4.5 of [25], whereas the proof of (7e) can be found in Theorem 2.2 of [29]. The results in (7c)–(7d) are consequence of (7a) and its proof will be postponed to the appendix (Appendix (A.2)).

In addition, we will employ the Scott-Zhang interpolant  $\Pi_{SZ} : H_\vartheta^1(\Omega) \rightarrow Q_h \cap H_\vartheta^1(\Omega)$ , where  $H_\vartheta^1(\Omega) := \{\phi \in H^1(\Omega) : \phi|_\vartheta = 0\}$  with  $\vartheta \subseteq \Gamma$ . Note that if  $\phi \in H_0^1(\Omega)$  then  $\Pi_{SZ}\phi \in Q_h^c$ . In the literature, it is known that it satisfies the following approximation properties (cf. [44]).

**Lemma 4.2.** *Let  $K \in \mathcal{T}_h$  and  $F \in \mathcal{E}_h$ . For any  $\phi \in H_\vartheta^1(\Omega)$ , there hold*

$$\begin{aligned} \|\phi - \Pi_{SZ}\phi\|_K &\lesssim h_K |\phi|_{1, \omega_K}, \\ \|\phi - \Pi_{SZ}\phi\|_F &\lesssim h_F^{1/2} |\phi|_{1, \omega_F}, \end{aligned}$$

where  $\omega_K := \cup\{K' \in \mathcal{T}_h : \overline{K'} \cap \overline{K} \neq \emptyset\}$  and  $\omega_F := \cup\{K' \in \mathcal{T}_h : \overline{K'} \cap \overline{F} \neq \emptyset\}$ .

Now, we are in position to prove an upper bound for the  $L^2$  and broken  $H^1$ - error on the pressure. As we will see, this bound depends on some of the terms of the error estimator and also on the  $L^2$ -error of the electric field. For the sake of simplicity in the exposition, from now on we assume that  $\mathbf{g}$  is the tangential trace of a function in  $\mathbf{V}_h^c$ . Otherwise, oscillatory terms related to  $\mathbf{g}$  would appear.

**Lemma 4.3.** *For  $(\mathbf{v}, \mathbf{u}, p) \in H(\mathbf{curl}; \Omega) \times \mathbf{X}_{QP}^g \times H_0^1(\Omega)$  and  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times Q_h \times \mathbf{M}_{QP}^g \times M_h$  the solutions of (2) and (4), respectively, there hold*

$$\|p - p_h\|_{\mathcal{T}_h} \lesssim \|\nabla(p - p_h)\|_{\mathcal{T}_h} + \|h^{-1/2}(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}, \quad (8a)$$

$$\|\nabla(p - p_h)\|_{\mathcal{T}_h} \lesssim \sum_{K \in \mathcal{T}_h} \eta_{K,2} + \sum_{F \in \mathcal{E}_I} \eta_{F,4} + \kappa^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} + \|h^{-1/2}(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}. \quad (8b)$$

*Proof.* By the discrete Poincaré inequality ([18], Corollary 5.4) and the fact that  $\hat{p}_h$  is single-valued and vanishes at the boundary, we have that

$$\begin{aligned} \|p - p_h\|_{\mathcal{T}_h} &\lesssim \|\nabla(p - p_h)\|_{\mathcal{T}_h} + \|h^{-1/2} \llbracket p_h \rrbracket\|_{\mathcal{E}_I} + \|h^{-1/2} p_h\|_{\mathcal{E}_\Gamma} \\ &\lesssim \|\nabla(p - p_h)\|_{\mathcal{T}_h} + \|h^{-1/2} \llbracket p_h - \hat{p}_h \rrbracket\|_{\mathcal{E}_I} + \|h^{-1/2}(p_h - \hat{p}_h)\|_{\mathcal{E}_\Gamma} \\ &\lesssim \|\nabla(p - p_h)\|_{\mathcal{T}_h} + \|h^{-1/2}(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}, \end{aligned}$$

from which (8a) follows. Now, in order to bound  $\|\nabla(p - p_h)\|_{\mathcal{T}_h}$ , we employ the result in Lemma 4.1. More precisely, for  $p_h \in Q_h$  there exists  $p_h^c \in Q_h^c$  such that

$$\|\nabla(p_h - p_h^c)\|_{\mathcal{T}_h} \lesssim \|h^{-1/2}(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}. \quad (9)$$

On the other hand, by substituting  $\mathbf{f}$  (cf. (2b)) in (4b) we obtain the next error equation

$$\begin{aligned} (\mathbf{v} - \mathbf{v}_h, \nabla \times \mathbf{z})_{\mathcal{T}_h} + \langle \mathbf{v}^t - \hat{\mathbf{v}}_h^t, \mathbf{z} \times \mathbf{n} \rangle_{\partial\mathcal{T}_h} - \kappa^2 (\epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{z})_{\mathcal{T}_h} \\ + (\bar{\epsilon} \nabla(p - p_h), \mathbf{z})_{\mathcal{T}_h} + \langle \epsilon \mathbf{z} \cdot \mathbf{n}, p_h - \hat{p}_h \rangle_{\partial\mathcal{T}_h} = 0 \quad \forall \mathbf{z} \in \mathbf{V}_h. \end{aligned} \quad (10)$$



Let  $\phi := p - p_h^c \in H_0^1(\Omega)$ , by taking  $\mathbf{z} := \nabla \Pi_{SZ} \phi$  in (10), it follows that

$$-\kappa^2(\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla \Pi_{SZ} \phi)_{\mathcal{T}_h} + (\bar{\epsilon} \nabla(p - p_h), \nabla \Pi_{SZ} \phi)_{\mathcal{T}_h} + \langle \epsilon \nabla \Pi_{SZ} \phi \cdot \mathbf{n}, p_h - \hat{p}_h \rangle_{\partial \mathcal{T}_h} = 0,$$

since  $\nabla \times \nabla \Pi_{SZ} \phi = 0$  and  $\langle \mathbf{v}^t - \hat{\mathbf{v}}_h^t, \nabla \Pi_{SZ} \phi \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} = 0$ . Then, if we rewrite  $(\nabla(p - p_h), \epsilon \nabla \phi)_{\mathcal{T}_h}$  by using the above expression and the Green's identity of  $H(\text{div}_\epsilon; \mathcal{T}_h)$ , we obtain that

$$\begin{aligned} (\nabla(p - p_h), \epsilon \nabla \phi)_{\mathcal{T}_h} &= (\nabla(p - p_h), \epsilon \nabla(\phi - \Pi_{SZ} \phi))_{\mathcal{T}_h} + (\nabla(p - p_h), \epsilon \nabla \Pi_{SZ} \phi)_{\mathcal{T}_h} \\ &= (\nabla(p - p_h), \epsilon \nabla(\phi - \Pi_{SZ} \phi))_{\mathcal{T}_h} + \kappa^2(\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla \Pi_{SZ} \phi)_{\mathcal{T}_h} - \langle \epsilon \nabla \Pi_{SZ} \phi \cdot \mathbf{n}, p_h - \hat{p}_h \rangle_{\partial \mathcal{T}_h} \\ &= -(\nabla \cdot (\bar{\epsilon} \nabla(p - p_h)), \phi - \Pi_{SZ} \phi)_{\mathcal{T}_h} + \langle \bar{\epsilon} \nabla(p - p_h) \cdot \mathbf{n}, \phi - \Pi_{SZ} \phi \rangle_{\partial \mathcal{T}_h} \\ &\quad - \kappa^2(\nabla \cdot (\epsilon(\mathbf{u} - \mathbf{u}_h)), \Pi_{SZ} \phi)_{\mathcal{T}_h} + \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \Pi_{SZ} \phi \rangle_{\partial \mathcal{T}_h} - \langle \nabla \Pi_{SZ} \phi \cdot \mathbf{n}, \bar{\epsilon}(p_h - \hat{p}_h) \rangle_{\partial \mathcal{T}_h}. \end{aligned}$$

Moreover, by equation (2b), we deduce that

$$\begin{aligned} (\nabla(p - p_h), \epsilon \nabla \phi)_{\mathcal{T}_h} &= (\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h), \Pi_{SZ} \phi - \phi)_{\mathcal{T}_h} \\ &\quad + \langle \bar{\epsilon} \nabla(p - p_h) \cdot \mathbf{n}, \phi - \Pi_{SZ} \phi \rangle_{\partial \mathcal{T}_h} - \kappa^2(\nabla \cdot \epsilon(\mathbf{u} - \mathbf{u}_h), \phi)_{\mathcal{T}_h} \\ &\quad + \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \Pi_{SZ} \phi - \phi \rangle_{\partial \mathcal{T}_h} + \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \phi \rangle_{\partial \mathcal{T}_h} - \langle \nabla \Pi_{SZ} \phi \cdot \mathbf{n}, \bar{\epsilon}(p_h - \hat{p}_h) \rangle_{\partial \mathcal{T}_h} \\ &= (\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h), \Pi_{SZ} \phi - \phi)_{\mathcal{T}_h} \\ &\quad + \langle \bar{\epsilon} \nabla(p - p_h) \cdot \mathbf{n}, \phi - \Pi_{SZ} \phi \rangle_{\partial \mathcal{T}_h} + \kappa^2(\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla \phi)_{\mathcal{T}_h} \\ &\quad + \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \Pi_{SZ} \phi - \phi \rangle_{\partial \mathcal{T}_h} - \langle \nabla \Pi_{SZ} \phi \cdot \mathbf{n} - \nabla \Pi_Q^0 \phi \cdot \mathbf{n}, \bar{\epsilon}(p_h - \hat{p}_h) \rangle_{\partial \mathcal{T}_h}, \end{aligned} \tag{11}$$

where  $\Pi_Q^0$  is the  $L^2$ -projection over  $\mathbb{P}_0(\mathcal{T}_h)$ .

Now, let us bound each terms of the right hand side of (11). We apply the Cauchy-Schwarz inequality, the approximation properties in Lemma 4.2, inverse inequality and the continuity of  $\bar{\epsilon} \nabla p \cdot \mathbf{n}$ , which is derived from the second equation of (2) and the fact that  $\mathbf{f} \in H(\text{div}^0; \Omega)$ . More precisely, for the first term, it holds

$$(\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h), \Pi_{SZ} \phi - \phi)_{\mathcal{T}_h} \lesssim h \|\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h)\|_{\mathcal{T}_h} \|\phi\|_{1, \mathcal{T}_h}$$

and for the second term,

$$\langle \bar{\epsilon} \nabla(p - p_h) \cdot \mathbf{n}, \phi - \Pi_{SZ} \phi \rangle_{\partial \mathcal{T}_h} \lesssim h^{1/2} \|\bar{\epsilon} \nabla(p - p_h) \cdot \mathbf{n}\|_{\partial \mathcal{T}_h} \|\phi\|_{1, \mathcal{T}_h} \lesssim \|h^{1/2} [\bar{\epsilon} \nabla p_h \cdot \mathbf{n}]\|_{\mathcal{E}_I} \|\phi\|_{1, \mathcal{T}_h}.$$

Similarly, we derive the following bounds for the third, fourth and fifth terms

$$\begin{aligned} \kappa^2(\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla \phi)_{\mathcal{T}_h} &\lesssim \kappa^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \|\phi\|_{1, \mathcal{T}_h}, \\ \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \Pi_{SZ} \phi - \phi \rangle_{\partial \mathcal{T}_h} &\lesssim \kappa^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \|\phi\|_{1, \mathcal{T}_h}, \\ \langle (\nabla \Pi_{SZ} \phi - \nabla \Pi_Q^0 \phi) \cdot \mathbf{n}, \bar{\epsilon}(p_h - \hat{p}_h) \rangle_{\partial \mathcal{T}_h} &\lesssim \sum_{K \in \mathcal{T}_h} \|\bar{\epsilon}(p_h - \hat{p}_h)\|_{\partial K} \|(\nabla \Pi_{SZ} \phi - \nabla \Pi_Q^0 \phi) \cdot \mathbf{n}\|_{\partial K} \\ &\lesssim \sum_{K \in \mathcal{T}_h} \|\bar{\epsilon}(p_h - \hat{p}_h)\|_{\partial K} h_K^{-1/2} \|\nabla \Pi_{SZ} \phi - \nabla \Pi_Q^0 \phi\|_K \\ &\lesssim \sum_{K \in \mathcal{T}_h} h_K^{-3/2} \|\bar{\epsilon}(p_h - \hat{p}_h)\|_{\partial K} \|\Pi_{SZ} \phi - \Pi_Q^0 \phi\|_K \\ &\lesssim \|h^{-1/2} \bar{\epsilon}(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h} \|\phi\|_{1, \mathcal{T}_h}. \end{aligned}$$

By replacing all the above bounds in (11), noticing that

$$\|\nabla(p - p_h^c)\|_{\mathcal{T}_h}^2 \lesssim (\nabla(p - p_h), \epsilon \nabla \phi)_{\mathcal{T}_h} + (\nabla(p_h - p_h^c), \nabla \phi)_{\mathcal{T}_h},$$

and using Poincaré inequality, we deduce that

$$\begin{aligned} \|\nabla(p - p_h^c)\|_{\mathcal{T}_h} &\lesssim h \|\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h)\|_{\mathcal{T}_h} + \|h^{1/2} \llbracket \bar{\epsilon} \nabla p_h \cdot \mathbf{n} \rrbracket\|_{\mathcal{E}_I} \\ &\quad + \kappa^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} + \|h^{-1/2}(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h} + \|\nabla(p_h - p_h^c)\|_{\mathcal{T}_h}. \end{aligned}$$

Finally, writing  $\nabla(p - p_h) = \nabla(p - p_h^c) + \nabla(p_h^c - p_h)$ , using triangle inequality, (9) and the last expression, we obtain (8b).  $\square$

In the next result, it is presented an upper bound for the  $L^2$ -error of the electric field that depends on the  $L^2$ -error of an approximation of its curl and the penalty terms. The former will be bounded later, by a computable quantity.

**Lemma 4.4.** *Let  $(\mathbf{v}, \mathbf{u}, p) \in H(\mathbf{curl}; \Omega) \times \mathbf{X}_{\text{QP}}^{\mathbf{g}} \times H_0^1(\Omega)$  and  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times Q_h \times \mathbf{M}_{\text{QP}}^{\mathbf{g}} \times M_h$  be the solutions of (2) and (4), respectively. There holds*

$$\|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \lesssim \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h} + h^{1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h} + \|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h} \quad (12)$$

where  $\mathbf{u}_h^{\text{QP}}$  is given by Lemma 4.1 for  $\mathbf{u}_h \in \mathbf{V}_h$ .

*Proof.* First of all, thanks to Lemma 4.1, for  $\mathbf{u}_h \in \mathbf{V}_h$  there exists  $\mathbf{u}_h^{\text{QP}} \in \mathbf{V}_h^c$  with  $\mathbf{u}_h^{\text{QP}} \times \mathbf{n}|_{\Gamma_0} = \mathbf{g}$  such that

$$\|\mathbf{u}_h - \mathbf{u}_h^{\text{QP}}\|_{\mathcal{T}_h} \lesssim \|h^{1/2} \llbracket \mathbf{u}_h \rrbracket\|_{\mathcal{E}_I} + \|h^{1/2} \llbracket \mathbf{u}_h \rrbracket_{\text{QP}}\|_{\mathcal{E}_{\text{QP}}} + \|h^{1/2}(\mathbf{u}_h \times \mathbf{n} - \mathbf{g})\|_{\mathcal{E}_0},$$

Even more, the facts that  $\llbracket \hat{\mathbf{u}}_h^t \rrbracket = \mathbf{0}$  on  $\mathcal{E}_I$ ,  $\llbracket \hat{\mathbf{u}}_h^t \rrbracket_{\text{QP}} = \mathbf{0}$  on  $\Gamma_{\text{QP}}$  (cf. Remark 3.1) and  $\hat{\mathbf{u}}_h^t \times \mathbf{n}|_{\Gamma_0} = \mathbf{g}$ , imply that

$$\|\mathbf{u}_h - \mathbf{u}_h^{\text{QP}}\|_{\mathcal{T}_h} \lesssim \|h^{1/2} \llbracket \mathbf{u}_h - \hat{\mathbf{u}}_h^t \rrbracket\|_{\mathcal{E}_I} + \|h^{1/2} \llbracket \mathbf{u}_h - \hat{\mathbf{u}}_h^t \rrbracket_{\text{QP}}\|_{\mathcal{E}_{\text{QP}}} + \|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\mathcal{E}_0},$$

therefore, since  $\epsilon$  is a bounded function, we have that

$$\|\epsilon(\mathbf{u}_h - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h} \lesssim \|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}. \quad (13)$$

and, by the triangle inequality

$$\|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \lesssim \|\epsilon(\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h} + \|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}. \quad (14)$$

Now, let us see the deduction of a bound for the term  $\|\epsilon(\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}$ . For this purpose, we will use a Helmholtz decomposition, which will be demonstrated in the Appendix A.1. For  $\mathbf{u} - \mathbf{u}_h^{\text{QP}} \in \mathbf{L}^2(\Omega)$  there exist  $\psi \in H_{\Gamma_0}^{1, \text{QP}}(\Omega)$  and  $\mathbf{u}_s \in H_{\Gamma_{\text{QP}}}(\text{div}^0; \Omega)$ , such that

$$\mathbf{u} - \mathbf{u}_h^{\text{QP}} = \nabla \psi + \mathbf{u}_s \quad (15)$$

and  $\|\mathbf{u} - \mathbf{u}_h^{\text{QP}}\|_{\Omega}^2 = \|\nabla \psi\|_{\Omega}^2 + \|\mathbf{u}_s\|_{\Omega}^2$  (see Proposition A.1). Moreover, according with [21, Theorem 8.4], since  $\Omega$  is simply connected and  $\mathbf{u}_s \in H_{\Gamma_{\text{QP}}}(\text{div}^0; \Omega)$  there exists a unique  $\tilde{\mathbf{z}} \in H_{\Gamma_0}(\text{div}^0; \Omega) \cap H_{\Gamma_{\text{QP}}}(\mathbf{curl}; \Omega)$  such that  $\nabla \times \tilde{\mathbf{z}} = \mathbf{u}_s$  and it satisfies

$$\|\tilde{\mathbf{z}}\|_{H(\mathbf{curl}; \Omega)} \lesssim \|\mathbf{u}_s\|_{\Omega}. \quad (16)$$

In the next part of the proof, we bound  $\|\mathbf{u}_s\|_\Omega$  and  $\|\nabla\psi\|_\Omega$ . First, we note that  $(\mathbf{u} - \mathbf{u}_h^{\text{QP}}) \times \mathbf{n}|_{\Gamma_0} = \mathbf{0}$ , since  $\mathbf{u} \in \mathbf{X}_{\text{QP}}^{\mathbf{g}}$  and  $\mathbf{g}$  is the tangential trace of  $\mathbf{u}_h^{\text{QP}}$ . By considering the orthogonal decomposition (15) and integrating by parts, we note that

$$\begin{aligned} \|\mathbf{u}_s\|_\Omega^2 &= (\mathbf{u}_s, \mathbf{u} - \mathbf{u}_h^{\text{QP}} - \nabla\psi)_\Omega = (\nabla \times \tilde{\mathbf{z}}, \mathbf{u} - \mathbf{u}_h^{\text{QP}})_\Omega - (\mathbf{u}_s, \nabla\psi)_\Omega \\ &= (\tilde{\mathbf{z}}, \nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}}))_\Omega + \langle (\mathbf{u} - \mathbf{u}_h^{\text{QP}}) \times \mathbf{n}, \tilde{\mathbf{z}}^t \rangle_\Gamma + (\nabla \cdot \mathbf{u}_s, \psi)_\Omega - \langle \mathbf{u}_s \cdot \mathbf{n}, \psi \rangle_\Gamma = (\tilde{\mathbf{z}}, \nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}}))_\Omega \end{aligned}$$

where the first boundary term vanishes due to the fact that  $\mathbf{u} - \mathbf{u}_h^{\text{QP}} \in H_{\Gamma_0}(\mathbf{curl}; \Omega)$ ,  $\tilde{\mathbf{z}} \in H_{\Gamma_{\text{QP}}}(\mathbf{curl}; \Omega)$  and the other terms because  $\mathbf{u}_s \in H_{\Gamma_{\text{QP}}}(\text{div}^0; \Omega)$  and  $\psi|_{\Gamma_0} = 0$ . Therefore, by the Cauchy-Schwarz inequality and (16), it holds

$$\|\mathbf{u}_s\|_\Omega^2 \lesssim \|\mathbf{u}_s\|_\Omega \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_\Omega,$$

thus

$$\|\mathbf{u}_s\|_\Omega \lesssim \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}. \quad (17)$$

Now, in order to bound  $\|\nabla\psi\|_\Omega$ , we also employ the aforementioned orthogonal decomposition and the addition and subtraction of  $\mathbf{u}_h$ , as follows

$$\|\nabla\psi\|_\Omega^2 = (\mathbf{u} - \mathbf{u}_h^{\text{QP}} - \mathbf{u}_s, \nabla\psi)_\Omega = (\mathbf{u} - \mathbf{u}_h^{\text{QP}}, \nabla\psi)_\Omega = (\epsilon^{-1}\epsilon(\mathbf{u} - \mathbf{u}_h + \mathbf{u}_h - \mathbf{u}_h^{\text{QP}}), \nabla\psi)_{\mathcal{T}_h},$$

in order to conclude that,

$$\|\nabla\psi\|_\Omega^2 \lesssim |(\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla\psi)_{\mathcal{T}_h}| + |(\epsilon(\mathbf{u}_h - \mathbf{u}_h^{\text{QP}}), \nabla\psi)_{\mathcal{T}_h}|. \quad (18)$$

Then, taking into account (2c) and (4c), we deduce the following error equation

$$-(\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla q)_{\mathcal{T}_h} + \langle (\epsilon\mathbf{u} - \widehat{\epsilon\mathbf{u}_h^n}) \cdot \mathbf{n}, q \rangle_{\partial\mathcal{T}_h} = 0$$

from which, after applying the Green's identity of  $H(\text{div}; \mathcal{T}_h)$ , it is obtained that

$$(\nabla \cdot \epsilon(\mathbf{u} - \mathbf{u}_h), q)_{\mathcal{T}_h} + \langle (\epsilon\mathbf{u}_h - \widehat{\epsilon\mathbf{u}_h^n}) \cdot \mathbf{n}, q \rangle_{\partial\mathcal{T}_h} = 0 \quad \forall q \in Q_h \quad (19)$$

Now, if we integrate by parts in the first term of (18), add and subtract  $(\nabla \cdot \epsilon(\mathbf{u} - \mathbf{u}_h), \Pi_{\text{SZ}}\psi)_{\mathcal{T}_h}$ , integrate by parts  $(\nabla \cdot \epsilon(\mathbf{u} - \mathbf{u}_h), \Pi_{\text{SZ}}\psi)_{\mathcal{T}_h}$ , use the fact that  $\mathbf{u} \in H(\text{div}_\epsilon^0; \Omega)$  and choose  $q = \Pi_{\text{SZ}}\psi \in Q_h$  in (19), we can get that

$$\begin{aligned} (\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla\psi)_{\mathcal{T}_h} &= -(\nabla \cdot \epsilon(\mathbf{u} - \mathbf{u}_h), \psi)_{\mathcal{T}_h} + \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \psi \rangle_{\partial\mathcal{T}_h} \\ &= (\nabla \cdot \epsilon(\mathbf{u} - \mathbf{u}_h), \Pi_{\text{SZ}}\psi - \psi)_{\mathcal{T}_h} - (\nabla \cdot \epsilon(\mathbf{u} - \mathbf{u}_h), \Pi_{\text{SZ}}\psi)_{\mathcal{T}_h} + \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \psi \rangle_{\partial\mathcal{T}_h} \\ &= (\nabla \cdot (\epsilon\mathbf{u}_h), \psi - \Pi_{\text{SZ}}\psi)_{\mathcal{T}_h} + \langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \psi - \Pi_{\text{SZ}}\psi \rangle_{\partial\mathcal{T}_h \setminus (\mathcal{E}_{\text{QP}} \cup \mathcal{E}_0)} + \langle (\epsilon\mathbf{u} - \widehat{\epsilon\mathbf{u}_h^n}) \cdot \mathbf{n}, \Pi_{\text{SZ}}\psi \rangle_{\mathcal{E}_{\text{QP}}}, \end{aligned}$$

where in the last step we have made use of the fact that  $\langle (\epsilon\mathbf{u} - \widehat{\epsilon\mathbf{u}_h^n}) \cdot \mathbf{n}, \Pi_{\text{SZ}}\psi \rangle_{\partial\mathcal{T}_h \setminus \mathcal{E}_{\text{QP}}} = 0$ , due to  $\Pi_{\text{SZ}}\psi \in H_{\Gamma_0}^1(\Omega)$ , the continuity of the normal trace of  $\epsilon\mathbf{u}$  and the fact that  $\widehat{\epsilon\mathbf{u}_h^n}$  is a single-valued function. We also used the fact that  $\Pi_{\text{SZ}}\psi - \psi = 0$  on  $\mathcal{E}_{\text{QP}} \cup \mathcal{E}_0$ . By the Cauchy-Schwarz inequality, the definition of  $\llbracket \cdot \rrbracket_{\text{QP}}$  and the approximation properties of the Scott-Zhang projector in Lemma 4.2, it follows that

$$\begin{aligned} |(\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla\psi)_{\mathcal{T}_h}| &\leq |(\nabla \cdot (\epsilon\mathbf{u}_h), \psi - \Pi_{\text{SZ}}\psi)_{\mathcal{T}_h}| + |\langle \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}, \psi - \Pi_{\text{SZ}}\psi \rangle_{\partial\mathcal{T}_h \setminus (\mathcal{E}_{\text{QP}} \cup \mathcal{E}_0)}| \\ &\quad + |\langle (\epsilon\mathbf{u} - \widehat{\epsilon\mathbf{u}_h^n}) \cdot \mathbf{n}, \Pi_{\text{SZ}}\psi - \psi \rangle_{\mathcal{E}_{\text{QP}}}| + |\langle (\epsilon\mathbf{u} - \widehat{\epsilon\mathbf{u}_h^n}) \cdot \mathbf{n}, \psi \rangle_{\mathcal{E}_{\text{QP}}}| \\ &\leq \|\nabla \cdot (\epsilon\mathbf{u}_h)\|_{\mathcal{T}_h} \|\psi - \Pi_{\text{SZ}}\psi\|_{\mathcal{T}_h} + \|\epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}\|_{\partial\mathcal{T}_h \setminus (\mathcal{E}_{\text{QP}} \cup \mathcal{E}_0)} \|\psi - \Pi_{\text{SZ}}\psi\|_{\partial\mathcal{T}_h} \\ &\quad + \|\llbracket (\epsilon\mathbf{u} - \widehat{\epsilon\mathbf{u}_h^n}) \cdot \mathbf{n} \rrbracket_{\text{QP}}\|_{\mathcal{E}_{\text{QP}}} \|\llbracket \psi \rrbracket_{\text{QP}}\|_{\mathcal{E}_{\text{QP}}} \\ &\lesssim \left( h \|\nabla \cdot (\epsilon\mathbf{u}_h)\|_{\mathcal{T}_h} + h^{1/2} \|\epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n}\|_{\partial\mathcal{T}_h \setminus (\mathcal{E}_{\text{QP}} \cup \mathcal{E}_0)} \right) |\psi|_{1, \Omega} \\ &\lesssim \left( h \|\nabla \cdot (\epsilon\mathbf{u}_h)\|_{\mathcal{T}_h} + h^{1/2} \|\llbracket \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n} \rrbracket_{\mathcal{E}_I} \right) |\psi|_{1, \Omega}, \end{aligned} \quad (20)$$

where we have made use of the fact that  $\llbracket \psi \rrbracket_{\text{QP}} = 0$  because  $\psi \in H_{\Gamma_0}^{1,\text{QP}}(\Omega)$ . Taking into account that  $\epsilon \mathbf{u} \in H(\text{div}; \Omega)$ ,  $\widehat{\epsilon \mathbf{u}_h^n}$  is single-valued and (4h), we have

$$\begin{aligned} \|\llbracket \epsilon(\mathbf{u} - \mathbf{u}_h) \cdot \mathbf{n} \rrbracket\|_{\mathcal{E}_I} &= \|\llbracket (\epsilon \mathbf{u}_h - \widehat{\epsilon \mathbf{u}_h^n}) \cdot \mathbf{n} \rrbracket\|_{\mathcal{E}_I} = \sum_{F \in \mathcal{E}_I} \left\| \llbracket (\epsilon \mathbf{u}_h - \widehat{\epsilon \mathbf{u}_h^n}) \cdot \mathbf{n} \rrbracket \right\|_F \\ &= \sum_{F \in \mathcal{E}_I} \|\llbracket \tau_n(p_h - \hat{p}_h) \rrbracket\|_F \leq \|\tau_n(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h}. \end{aligned} \quad (21)$$

Recalling that  $\nabla \cdot (\epsilon \mathbf{u}) = 0$ , taking  $q := \nabla \cdot (\epsilon \mathbf{u}_h)$  in (19), by using the Cauchy-Schwarz inequality, the discrete trace inequality and (4h), there holds

$$\begin{aligned} \|\nabla \cdot (\epsilon \mathbf{u}_h)\|_{\mathcal{T}_h}^2 &= \langle (\epsilon \mathbf{u}_h - \widehat{\epsilon \mathbf{u}_h^n}) \cdot \mathbf{n}, \nabla \cdot (\epsilon \mathbf{u}_h) \rangle_{\partial \mathcal{T}_h} \leq \|(\epsilon \mathbf{u}_h - \widehat{\epsilon \mathbf{u}_h^n}) \cdot \mathbf{n}\|_{\partial \mathcal{T}_h} \|\nabla \cdot (\epsilon \mathbf{u}_h)\|_{\partial \mathcal{T}_h} \\ &\leq \|(\epsilon \mathbf{u}_h - \widehat{\epsilon \mathbf{u}_h^n}) \cdot \mathbf{n}\|_{\partial \mathcal{T}_h} h^{-1/2} \|\nabla \cdot (\epsilon \mathbf{u}_h)\|_{\mathcal{T}_h} \leq h^{-1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h} \|\nabla \cdot (\epsilon \mathbf{u}_h)\|_{\mathcal{T}_h} \end{aligned}$$

thus

$$\|\nabla \cdot (\epsilon \mathbf{u}_h)\|_{\mathcal{T}_h} \lesssim h^{-1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h}. \quad (22)$$

Therefore, by using the Cauchy-Schwarz inequality in (18), from (20), (21), (22) and (13), it follows that

$$\|\nabla \psi\|_{\Omega} \lesssim h^{1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h} + \|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial \mathcal{T}_h}. \quad (23)$$

Finally, (12) follows by combining (14), (15), (23) and (17).  $\square$

In the following lemma, let us proceed to obtain a computable upper bound for the  $L^2$ -error of the curl of the electric field and its quasi-periodic approximation.

**Lemma 4.5.** *Let  $(\mathbf{v}, \mathbf{u}, p) \in H(\mathbf{curl}; \Omega) \times \mathbf{X}_{\text{QP}}^g \times H_0^1(\Omega)$  and  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times Q_h \times \mathbf{M}_{\text{QP}}^g \times M_h$  be the solutions of (2) and (4), respectively. Then,*

$$\begin{aligned} \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h} &\lesssim \|h^{-1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial \mathcal{T}_h} + h^{\ell-1} \sum_{K \in \mathcal{T}_h} \eta_{K,1} + h^{\ell-1} \|\tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t)\|_{\partial \mathcal{T}_h} \\ &\quad + h^{\ell-1} \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,3} + h^{1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h} + h^{\ell-1/2} \|p_h - \hat{p}_h\|_{\partial \mathcal{T}_h} \end{aligned} \quad (24)$$

where  $\mathbf{u}_h^{\text{QP}}$  is given by Lemma 4.1 for  $\mathbf{u}_h \in \mathbf{V}_h$  and  $\ell \in (0, 1)$  such that the continuous embedding

$$H_{\Gamma_{\text{QP}}}(\text{div}_\epsilon^0; \Omega) \cap H_{\Gamma_0}(\mathbf{curl}; \Omega) \hookrightarrow \mathbf{H}^\ell(\Omega) \quad (25)$$

holds.

*Proof.* Let  $\mathbf{u}_h^{\text{QP}} \in \mathbf{V}_h^c$  be the quasi-periodic approximation of  $\mathbf{u}_h$  with  $\mathbf{u}_h^{\text{QP}} \times \mathbf{n}|_{\Gamma_0} = \mathbf{g}$  provided in Lemma 4.1. Let us consider the Helmholtz decomposition of  $\mathbf{u} - \mathbf{u}_h^{\text{QP}} \in \mathbf{L}^2(\Omega)$  (Appendix A.1):

$$\mathbf{u} - \mathbf{u}_h^{\text{QP}} = \nabla \varphi + \mathbf{v}_s, \quad (26)$$

with  $\|\mathbf{u} - \mathbf{u}_h^{\text{QP}}\|_{\Omega}^2 = \|\nabla \varphi\|^2 + \|\mathbf{v}_s\|^2$ , where  $\varphi \in H_{\Gamma_0}^{1,\text{QP}}(\Omega)$  and  $\mathbf{v}_s \in H_{\Gamma_{\text{QP}}}(\text{div}_\epsilon^0; \Omega)$ . In addition, since  $(\mathbf{u} - \mathbf{u}_h^{\text{QP}}) \times \mathbf{n} = \mathbf{0}$  on  $\Gamma_0$  and  $\nabla \varphi \times \mathbf{n}|_{\Gamma_0} = \text{curl}|_{\Gamma_0} \varphi = \mathbf{0}$ , we conclude that  $\mathbf{v}_s \in H_{\Gamma_0}(\mathbf{curl}; \Omega)$ . Thus, for  $\mathbf{v}_s \in H_{\Gamma_{\text{QP}}}(\text{div}_\epsilon^0; \Omega) \cap H_{\Gamma_0}(\mathbf{curl}; \Omega)$  there exists  $\ell \in (0, 1)$  such that  $\mathbf{v}_s \in \mathbf{H}^\ell(\Omega)$  and  $\|\mathbf{v}_s\|_{\ell, \Omega} \lesssim \|\mathbf{v}_s\|_{H(\mathbf{curl}; \Omega)}$ , thanks the continuous embedding  $H_{\Gamma_{\text{QP}}}(\text{div}_\epsilon^0; \Omega) \cap H_{\Gamma_0}(\mathbf{curl}; \Omega) \hookrightarrow \mathbf{H}^\ell(\Omega)$  (see Remark 8.7 in [21]).

Then, adding and subtracting  $\mathbf{u}_h$ , it follows that

$$\begin{aligned}\|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2 &= (\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}}), \nabla \times (\nabla \varphi + \mathbf{v}_s))_{\mathcal{T}_h} \\ &= (\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} + (\nabla \times (\mathbf{u}_h - \mathbf{u}_h^{\text{QP}}), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h}.\end{aligned}$$

For the second term, according to (7d), we have that

$$\begin{aligned}(\nabla \times (\mathbf{u}_h - \mathbf{u}_h^{\text{QP}}), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &\leq \|\nabla \times (\mathbf{u}_h - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h} \|\nabla \times \mathbf{v}_s\|_{\mathcal{T}_h} \\ &\lesssim \left( \|h^{-1/2} \llbracket \mathbf{u}_h \rrbracket \|_{\mathcal{E}_I} + \|h^{-1/2} \llbracket \mathbf{u}_h \rrbracket_{\text{QP}} \|_{\mathcal{E}_{\text{QP}}} + \|h^{-1/2} (\mathbf{u}_h \times \mathbf{n} - \mathbf{g})\|_{\mathcal{E}_0} \right) \|\nabla \times \mathbf{v}_s\|_{\mathcal{T}_h} \\ &\lesssim \|h^{-1/2} (\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial \mathcal{T}_h} \|\nabla \times \mathbf{v}_s\|_{\mathcal{T}_h},\end{aligned}\tag{27}$$

where in the last step, we have used the facts that  $\llbracket \hat{\mathbf{u}}_h^t \rrbracket = 0$  on  $\mathcal{E}_I$ ,  $\llbracket \hat{\mathbf{u}}_h^t \rrbracket_{\text{QP}} = 0$  on  $\mathcal{E}_{\text{QP}}$  (Remark 3.1) and  $\hat{\mathbf{u}}_h^t \times \mathbf{n} = \mathbf{g}$  on  $\Gamma_0$ . Thus, since  $\nabla \times \mathbf{v}_s = \nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})$  and apply the Young inequality, as follows

$$\|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2 \lesssim (\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} + \|h^{-1/2} (\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial \mathcal{T}_h}^2.\tag{28}$$

Now, if we use the  $\mathbf{L}^2$ -projector over  $\mathbf{P}_0(\mathcal{T}_h)$ ,  $\Pi_{\mathbf{V}}^0$  (see [35]), in the first term of (28), apply the Green's identity of  $\mathbf{H}(\mathbf{curl}; \mathcal{T}_h)$ , use (2a) and (2b), it follows that

$$\begin{aligned}(\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &= (\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s))_{\mathcal{T}_h} \\ &= (\nabla \times \nabla \times (\mathbf{u} - \mathbf{u}_h), \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} - \langle (\nabla \times (\mathbf{u} - \mathbf{u}_h))^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} \\ &= (\mathbf{f} - \bar{\epsilon} \nabla p + \kappa^2 \epsilon \mathbf{u} - \nabla \times \nabla \times \mathbf{u}_h, \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} - \langle (\mathbf{v} - \nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h}.\end{aligned}\tag{29}$$

Now, by taking  $\mathbf{z} := \Pi_{\mathbf{V}}^0 \mathbf{v}_s$  in (10) and applying the Green's identity of  $\mathbf{H}(\text{div}; \mathcal{T}_h)$  to the fourth term of the obtained equation, we have

$$\begin{aligned}0 &= (\mathbf{v} - \mathbf{v}_h, \nabla \times \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} + \langle \mathbf{v}^t - \hat{\mathbf{v}}_h^t, \Pi_{\mathbf{V}}^0 \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} - \kappa^2 (\epsilon (\mathbf{u} - \mathbf{u}_h), \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} \\ &\quad - (p - p_h, \nabla \cdot (\epsilon \Pi_{\mathbf{V}}^0 \mathbf{v}_s))_{\mathcal{T}_h} + \langle \epsilon \Pi_{\mathbf{V}}^0 \mathbf{v}_s \cdot \mathbf{n}, p - \hat{p}_h \rangle_{\partial \mathcal{T}_h},\end{aligned}$$

from which,

$$0 = \langle \mathbf{v}^t - \hat{\mathbf{v}}_h^t, \Pi_{\mathbf{V}}^0 \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} - \kappa^2 (\epsilon (\mathbf{u} - \mathbf{u}_h), \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} + \langle \epsilon \Pi_{\mathbf{V}}^0 \mathbf{v}_s \cdot \mathbf{n}, p - \hat{p}_h \rangle_{\partial \mathcal{T}_h},\tag{30}$$

thanks to the fact that  $\epsilon$  is a piecewise constant. Then, by using (30), let us rewrite the second term on the right hand side of (29), thus

$$\begin{aligned}\langle (\mathbf{v} - \nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} &= \langle \mathbf{v}^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} - \langle \mathbf{v}^t, \Pi_{\mathbf{V}}^0 \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} - \langle (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} \\ &= \langle \mathbf{v}^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} - \langle \hat{\mathbf{v}}_h^t, \Pi_{\mathbf{V}}^0 \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} - \kappa^2 (\epsilon (\mathbf{u} - \mathbf{u}_h), \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} \\ &\quad + \langle \epsilon \Pi_{\mathbf{V}}^0 \mathbf{v}_s \cdot \mathbf{n}, p - \hat{p}_h \rangle_{\partial \mathcal{T}_h} - \langle (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h}.\end{aligned}$$

Let us note that the first term on the right hand side vanishes, since  $\mathbf{v}_s \in \mathbf{H}_{\Gamma_0}(\mathbf{curl}; \Omega)$ ,  $\mathbf{u}$ ,  $\mathbf{u}_h^{\text{QP}}$  and  $\varphi$  satisfies quasi-periodic conditions. In fact, by using the definitions of  $\mathbf{v}$  (cf. (2a)) and  $\mathbf{v}_s$  (cf. (26)),

we have that

$$\begin{aligned}
\langle \mathbf{v}^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} &= \langle \mathbf{v}^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h \setminus \Gamma} + \langle \mathbf{v}^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\Gamma_0} + \langle \mathbf{v}^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\Gamma_{QP}} \\
&= \langle \mathbf{v}^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\Gamma_{QP}} = \langle (\nabla \times \mathbf{u})^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\Gamma_{QP}} \\
&= \langle (\nabla \times \mathbf{u})^t, (\mathbf{u} - \mathbf{u}_h^{QP}) \times \mathbf{n} \rangle_{\Gamma_{QP}} - \langle (\nabla \times \mathbf{u})^t, \nabla \varphi \times \mathbf{n} \rangle_{\Gamma_{QP}} \\
&= \langle (\nabla \times \mathbf{u})^t, (\mathbf{u} - \mathbf{u}_h^{QP}) \times \mathbf{n} \rangle_{\Gamma_1 \cup \Gamma_2} + \langle (\nabla \times \mathbf{u})^t, (\mathbf{u} - \mathbf{u}_h^{QP}) \times \mathbf{n} \rangle_{\Gamma_3 \cup \Gamma_4} \\
&= \langle (\nabla \times \mathbf{u})^t, (\mathbf{u} - \mathbf{u}_h^{QP}) \times \mathbf{n} \rangle_{\Gamma_1} - |e^{i\alpha L}| \langle (\nabla \times \mathbf{u})^t, (\mathbf{u} - \mathbf{u}_h^{QP}) \times \mathbf{n} \rangle_{\Gamma_1} \\
&\quad + \langle (\nabla \times \mathbf{u})^t, (\mathbf{u} - \mathbf{u}_h^{QP}) \times \mathbf{n} \rangle_{\Gamma_3} - |e^{i\beta L}| \langle (\nabla \times \mathbf{u})^t, (\mathbf{u} - \mathbf{u}_h^{QP}) \times \mathbf{n} \rangle_{\Gamma_3} = 0.
\end{aligned}$$

In addition, if we add  $0 = \langle \hat{\mathbf{v}}_h^t, \mathbf{v}_s \times \mathbf{n} \rangle_{\partial \mathcal{T}_h}$  in the second term, it is obtained that

$$\begin{aligned}
\langle (\mathbf{v} - \nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} &= -\langle \hat{\mathbf{v}}_h^t, (\Pi_{\mathbf{V}}^0 \mathbf{v}_s - \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} \\
&\quad - \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \Pi_{\mathbf{V}}^0 \mathbf{v}_s \rangle_{\mathcal{T}_h} + \langle \epsilon \Pi_{\mathbf{V}}^0 \mathbf{v}_s \cdot \mathbf{n}, p - \hat{p}_h \rangle_{\partial \mathcal{T}_h} - \langle (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h}.
\end{aligned}$$

Then, after replacing the above expression in (29), add  $0 = \langle \epsilon \mathbf{v}_s \cdot \mathbf{n}, p - \hat{p}_h \rangle_{\partial \mathcal{T}_h}$  and by adding and subtracting  $\kappa^2 \epsilon \mathbf{u}_h$  and  $\bar{\epsilon} \nabla p_h$  in the first term, we can form the residual associated to (2b), as follows

$$\begin{aligned}
(\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &= (\mathbf{f} - \bar{\epsilon} \nabla p_h + \kappa^2 \epsilon \mathbf{u}_h - \nabla \times \nabla \times \mathbf{u}_h, \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} - \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{v}_s \rangle_{\mathcal{T}_h} \\
&\quad - \langle \hat{\mathbf{v}}_h^t - (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} + \langle \epsilon(\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \cdot \mathbf{n}, p - \hat{p}_h \rangle_{\partial \mathcal{T}_h} - (\nabla(p - p_h), \epsilon(\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s))_{\mathcal{T}_h},
\end{aligned}$$

using Green's identity and recalling that  $\epsilon(\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)$  is divergence free on each element, it is obtained that

$$\begin{aligned}
(\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &= (\mathbf{f} - \bar{\epsilon} \nabla p_h + \kappa^2 \epsilon \mathbf{u}_h + \nabla \times \nabla \times \mathbf{u}_h, \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} - \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{v}_s \rangle_{\mathcal{T}_h} \\
&\quad - \langle \hat{\mathbf{v}}_h^t - (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} + \langle \epsilon(\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \cdot \mathbf{n}, p_h - \hat{p}_h \rangle_{\partial \mathcal{T}_h}
\end{aligned}$$

Now, if we use (26) to rewrite  $\mathbf{v}_s$  in the second term, adding and subtracting  $\mathbf{v}_h^t$  in the third term and taking account the numerical flux (4h), it holds

$$\begin{aligned}
(\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &= (\mathbf{f} - \bar{\epsilon} \nabla p_h + \kappa^2 \epsilon \mathbf{u}_h - \nabla \times \nabla \times \mathbf{u}_h, \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} - \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{u} - \mathbf{u}_h^{QP} \rangle_{\mathcal{T}_h} \\
&\quad + \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \nabla \varphi \rangle_{\mathcal{T}_h} + \langle \epsilon(\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \cdot \mathbf{n}, p_h - \hat{p}_h \rangle_{\partial \mathcal{T}_h} \\
&\quad + \langle \tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t), \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s \rangle_{\partial \mathcal{T}_h} + \langle \mathbf{v}_h^t - (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h}.
\end{aligned}$$

Since  $-\kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{u} - \mathbf{u}_h^{QP} \rangle_{\mathcal{T}_h} = -\kappa^2 \|\epsilon^{1/2}(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 - \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{u}_h - \mathbf{u}_h^{QP} \rangle_{\mathcal{T}_h}$ , from the above equality we obtain that

$$\begin{aligned}
\kappa^2 \|\epsilon^{1/2}(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 + (\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &= (\mathbf{f} - \bar{\epsilon} \nabla p_h + \kappa^2 \epsilon \mathbf{u}_h - \nabla \times \nabla \times \mathbf{u}_h, \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} \\
&\quad - \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{u}_h - \mathbf{u}_h^{QP} \rangle_{\mathcal{T}_h} + \kappa^2 \langle \epsilon(\mathbf{u} - \mathbf{u}_h), \nabla \varphi \rangle_{\mathcal{T}_h} + \langle \epsilon(\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \cdot \mathbf{n}, p_h - \hat{p}_h \rangle_{\partial \mathcal{T}_h} \\
&\quad + \langle \tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t), \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s \rangle_{\partial \mathcal{T}_h} + \langle \mathbf{v}_h^t - (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h}.
\end{aligned} \tag{31}$$

In what follows, we bound each term on the right hand side of (31), by applying the Cauchy-Schwarz inequality, the definitions of the error indicators (6a), (6e), the relation (4g), the approximation properties of  $\Pi_{\mathbf{V}}^0$  and the inverse inequality, we have

$$\begin{aligned}
\star \quad (\mathbf{f} - \bar{\epsilon} \nabla p_h + \kappa^2 \epsilon \mathbf{u}_h - \nabla \times \nabla \times \mathbf{u}_h, \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s)_{\mathcal{T}_h} &\leq \sum_{K \in \mathcal{T}_h} h_K^{-1} \eta_{K,1} \|\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s\|_K \\
&\lesssim \sum_{K \in \mathcal{T}_h} h_K^{-1} \eta_{K,1} h_K^\ell \|\mathbf{v}_s\|_{\ell,K} \\
&\leq h^{\ell-1} \|\mathbf{v}_s\|_{\ell,\Omega} \sum_{K \in \mathcal{T}_h} \eta_{K,1},
\end{aligned}$$

$$\star \quad \langle \tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t), \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s \rangle_{\partial \mathcal{T}_h} \lesssim h^{\ell-1} \|\mathbf{v}_s\|_{\ell,\Omega} \|\tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t)\|_{\partial \mathcal{T}_h}$$

$$\begin{aligned}
\star \quad \langle \mathbf{v}_h^t - (\nabla \times \mathbf{u}_h)^t, (\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s) \times \mathbf{n} \rangle_{\partial \mathcal{T}_h} &= \langle \mathbf{n} \times (\mathbf{v}_h - \nabla \times \mathbf{u}_h), \mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s \rangle_{\partial \mathcal{T}_h} \\
&\leq \sum_{K \in \mathcal{T}_h} \|\mathbf{n} \times (\mathbf{v}_h - \nabla \times \mathbf{u}_h)\|_{\partial K} \|\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s\|_{\partial K} \\
&\leq \sum_{K \in \mathcal{T}_h} \|\mathbf{n} \times (\mathbf{v}_h - \nabla \times \mathbf{u}_h)\|_{\partial K} h_K^{-1/2} \|\mathbf{v}_s - \Pi_{\mathbf{V}}^0 \mathbf{v}_s\|_K \\
&\lesssim \sum_{K \in \mathcal{T}_h} \left( h_K^{\ell-1/2} \|\mathbf{v}_s\|_{\ell,K} \sum_{F \in \partial K} \|\mathbf{n} \times (\mathbf{v}_h - \nabla \times \mathbf{u}_h)\|_F \right) \\
&\leq \sum_{K \in \mathcal{T}_h} \left( h_K^{\ell-1/2} \|\mathbf{v}_s\|_{\ell,K} \sum_{F \in \partial K} h_F^{-1/2} \eta_{F,3} \right) \\
&\lesssim h^{\ell-1} \|\mathbf{v}_s\|_{\ell,\Omega} \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,3}
\end{aligned}$$

$$\begin{aligned}
\star \quad (\epsilon(\mathbf{u} - \mathbf{u}_h), \mathbf{u}_h - \mathbf{u}_h^{\text{QP}})_{\mathcal{T}_h} &\leq \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \|\mathbf{u}_h - \mathbf{u}_h^{\text{QP}}\|_{\mathcal{T}_h} \\
&\lesssim h^{1/2} \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \|(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial \mathcal{T}_h},
\end{aligned}$$

$$\star \quad \langle \epsilon(\Pi_{\mathbf{V}}^0 \mathbf{v}_s \cdot \mathbf{n} - \mathbf{v}_s \cdot \mathbf{n}), p_h - \hat{p}_h \rangle_{\partial \mathcal{T}_h} \lesssim h^{\ell-1/2} \|\mathbf{v}_s\|_{\ell,\Omega} \|p_h - \hat{p}_h\|_{\partial \mathcal{T}_h}.$$

$$\begin{aligned}
\star \quad (\epsilon(\mathbf{u} - \mathbf{u}_h), \nabla \varphi)_{\mathcal{T}_h} &\leq \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \|\nabla \varphi\|_{\mathcal{T}_h} \\
&\lesssim \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h} \left( h^{1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h} + \|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial \mathcal{T}_h} \right),
\end{aligned}$$

Where in the last inequality, we have used (23) for  $\psi$  in place of  $\varphi$ . Using Young's inequality in the above equations and replacing in (31), we get

$$\begin{aligned}
\kappa^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 + (\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &\lesssim \delta^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 + \left( h^{\ell-1} \sum_{K \in \mathcal{T}_h} \eta_{K,1} \right)^2 \\
&\quad + \left( h^{\ell-1} \|\tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t)\|_{\partial \mathcal{T}_h} \right)^2 + \left( h^{\ell-1} \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,3} \right)^2 + \left( h^{1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial \mathcal{T}_h} \right)^2 \\
&\quad + \left( \|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial \mathcal{T}_h} \right)^2 + \left( h^{\ell-1/2} \|p_h - \hat{p}_h\|_{\partial \mathcal{T}_h} \right)^2 + \|\mathbf{v}_s\|_{\ell,\Omega}^2.
\end{aligned}$$

According with the continuous embedding, we rewrite  $\mathbf{v}_s$  by using (26) and (23), we have

$$\begin{aligned}
\|\mathbf{v}_s\|_{\ell,\Omega}^2 &\lesssim \|\mathbf{v}_s\|_{\Omega}^2 + \|\nabla \times \mathbf{v}_s\|_{\Omega}^2 = \|\mathbf{u} - \mathbf{u}_h^{\text{QP}} - \nabla \varphi\|_{\mathcal{T}_h}^2 + \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2 \\
&\lesssim \|\nabla \varphi\|_{\Omega}^2 + \|\mathbf{u} - \mathbf{u}_h^{\text{QP}}\|_{\mathcal{T}_h}^2 + \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2 \\
&\lesssim \left(h^{1/2}\|\tau_n(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}\right)^2 + \left(\|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}\right)^2 \\
&\quad + \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 + \|\epsilon(\mathbf{u}_h - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2 + \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2 \\
&\lesssim \left(h^{1/2}\|\tau_n(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}\right)^2 + \left(\|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}\right)^2 + \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 + \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2
\end{aligned}$$

thus

$$\begin{aligned}
\|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 + (\nabla \times (\mathbf{u} - \mathbf{u}_h), \nabla \times \mathbf{v}_s)_{\mathcal{T}_h} &\lesssim \delta^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2 + \left(h^{\ell-1} \sum_{K \in \mathcal{T}_h} \eta_{K,1}\right)^2 \\
&\quad + \left(h^{\ell-1} \|\tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t)\|_{\partial\mathcal{T}_h}\right)^2 + \left(h^{\ell-1} \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,3}\right)^2 + \left(h^{1/2}\|\tau_n(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}\right)^2 \\
&\quad + \left(\|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}\right)^2 + \left(h^{\ell-1/2}\|p_h - \hat{p}_h\|_{\partial\mathcal{T}_h}\right)^2 + \|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2.
\end{aligned}$$

Finally, replacing in (28), we conclude

$$\begin{aligned}
\|\nabla \times (\mathbf{u} - \mathbf{u}_h^{\text{QP}})\|_{\mathcal{T}_h}^2 &\lesssim \|h^{-1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}^2 + \left(h^{\ell-1} \sum_{K \in \mathcal{T}_h} \eta_{K,1}\right)^2 + \left(h^{\ell-1} \|\tau(\hat{\mathbf{u}}_h^t - \mathbf{u}_h^t)\|_{\partial\mathcal{T}_h}\right)^2 \\
&\quad + \left(h^{\ell-1} \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,3}\right)^2 + \left(h^{1/2}\|\tau_n(p_h - \hat{p}_h)\|_{\partial\mathcal{T}_h}\right)^2 \\
&\quad + \left(\|h^{1/2}(\mathbf{u}_h - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}\right)^2 + \left(h^{\ell-1/2}\|p_h - \hat{p}_h\|_{\partial\mathcal{T}_h}\right)^2 + \delta^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\mathcal{T}_h}^2.
\end{aligned}$$

Then, choosing  $\delta$  small enough and using the fact that  $0 < h < 1$ , (24) is deduced from the last inequality.  $\square$

**Lemma 4.6.** *Let  $(\mathbf{v}, \mathbf{u}, p) \in \mathbf{H}(\text{curl}; \Omega) \times \mathbf{X}_{\text{QP}}^{\mathbf{g}} \times H_0^1(\Omega)$  and  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times Q_h \times \mathbf{M}_{\text{QP}}^{\mathbf{g}} \times M_h$  be the solutions of (2) and (4), respectively. There holds*

$$\|\nabla \times \mathbf{u}_h - \mathbf{v}_h\|_{\mathcal{T}_h} \lesssim h^{-1/2} \|(\mathbf{u}_h^t - \hat{\mathbf{u}}_h^t) \times \mathbf{n}\|_{\partial\mathcal{T}_h}. \quad (32)$$

*Proof.* By testing (2a) with  $\mathbf{w}$ , apply the Green's identity and subtracting (4a), we obtain the next error equation

$$(\mathbf{v} - \mathbf{v}_h, \mathbf{w}) - (\mathbf{u} - \mathbf{u}_h, \nabla \times \mathbf{w})_{\mathcal{T}_h} - \langle \mathbf{u}^t - \hat{\mathbf{u}}_h^t, \mathbf{w} \times \mathbf{n} \rangle_{\partial\mathcal{T}_h} = 0 \quad \forall \mathbf{w} \in \mathbf{V}_h$$

apply the Green's identity to the second term and using again (2a), it follows

$$\begin{aligned}
(\mathbf{v} - \mathbf{v}_h, \mathbf{w})_{\mathcal{T}_h} - (\nabla \times (\mathbf{u} - \mathbf{u}_h), \mathbf{w})_{\mathcal{T}_h} + \langle (\mathbf{u} - \mathbf{u}_h)^t, \mathbf{w} \times \mathbf{n} \rangle_{\partial\mathcal{T}_h} - \langle \mathbf{u}^t - \hat{\mathbf{u}}_h^t, \mathbf{w} \times \mathbf{n} \rangle_{\partial\mathcal{T}_h} &= 0 \\
(\nabla \times \mathbf{u}_h - \mathbf{v}_h, \mathbf{w})_{\mathcal{T}_h} - \langle (\mathbf{u}_h^t - \hat{\mathbf{u}}_h^t) \times \mathbf{n}, \mathbf{w} \rangle_{\partial\mathcal{T}_h} &= 0.
\end{aligned}$$

Afterwards, by defining  $\mathbf{w} := \nabla \times \mathbf{u}_h - \mathbf{v}_h$ , applying the Cauchy-Schwarz inequality and the inverse inequality ([18], Lemma 1.46), we obtain (32).  $\square$



Finally, gathering together all the previous results, we deduce the following upper bound for the error in terms of the error estimator and the index  $\ell$  appearing in the continuous embedding (25).

**Corollary 4.1.** *Let  $(\mathbf{v}, \mathbf{u}, p) \in \mathbf{H}(\text{curl}; \Omega) \times \mathbf{X}_{\text{QP}}^{\mathbf{g}} \times H_0^1(\Omega)$  and  $(\mathbf{v}_h, \mathbf{u}_h, p_h, \hat{\mathbf{u}}_h^t, \hat{p}_h) \in \mathbf{V}_h \times \mathbf{V}_h \times Q_h \times \mathbf{M}_{\text{QP}}^{\mathbf{g}} \times M_h$  be the solutions of (2) and (4), respectively. If the stabilization parameters satisfy  $|\tau|$  and  $|\tau_n|$  to be proportional to one, then*

$$E_h \lesssim h^{\ell-1} \eta_1 + \eta_2 + h^{\ell-1/2} \eta_1^\partial + \eta_2^\partial + h^{\ell-1} \eta_3^\partial + \eta_4^\partial,$$

where the terms on the right hand side have the following form  $\eta_1 := \sum_{K \in \mathcal{T}_h} \eta_{K,1}$ ,  $\eta_2 := \sum_{K \in \mathcal{T}_h} \eta_{K,2}$ ,  $\eta_1^\partial := \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,1}$ ,  $\eta_2^\partial := \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,2}$ ,  $\eta_3^\partial := \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,3}$  and  $\eta_4^\partial := \sum_{F \in \mathcal{E}_I \setminus \Gamma} \eta_{F,4}$ .

The above estimates imply that error estimator is reliable, i.e.,  $E_h \lesssim \eta$  when  $\ell = 1$ . This happens, for instance, when  $\Gamma = \Gamma_0$  (see for instance Section 3.4 [22]). In our setting  $\Gamma$  is the union of two disjoint sets  $\Gamma_{QP}$  and  $\Gamma_0$ , therefore it is not possible to guarantee  $\ell = 1$  in (25). However, the numerical experiments in Section 5 suggest that the estimator is still reliable even in this case.

## 4.2 Local efficiency

In this section we want to study whether or not our a posteriori error estimator shows local efficiency, based on the techniques devised by Verfürth, applying some properties of the bubble functions. Given an element  $K$ , a bubble function is defined as  $B_K := (d+1)^{d+1} \prod_{i=1}^{d+1} \lambda_i$ , where  $\lambda_i$  is a linear nodal function in the  $i$  vertex of  $K$ . Hence,  $\text{supp}(B_K) \subset K$ ,  $B_K = 0$  on  $\partial K$  and  $B_K \in [0, 1]$ . If the function is builded on a face  $F$ , then  $B_F := d^d \prod_{i=1}^d \lambda_i$ , for  $i$  vertex of  $F$ . In this case,  $\text{supp}(B_F) \subset \{K \in \mathcal{T}_h : F \subset \partial K\}$ ,  $B_F = 0$  on  $\partial K \setminus F$  and  $B_F \in [0, 1]$ . Now, let us introduce the properties of the bubble functions, which were proved in [2], Theorems 2.2 and 2.4.

**Lemma 4.7.** *For given  $K \in \mathcal{T}_h$ ,  $F \subset \partial K$ ,  $\phi \in \mathbb{P}(K)$  and  $\psi \in \mathbb{P}(F)$ , it holds*

$$\begin{aligned} C^{-1} \|\phi\|_K^2 &\leq \|B_K^{1/2} \phi\|_K^2 \leq C \|\phi\|_K^2, \\ C^{-1} \|\psi\|_F^2 &\leq \|B_F^{1/2} \psi\|_F^2 \leq C \|\psi\|_F^2, \\ C \|\psi\|_F^2 &\leq \|B_F^{1/2} \mathcal{L}(\psi)\|_K^2 \leq C \|\psi\|_F^2, \end{aligned}$$

where  $\mathcal{L} : \mathcal{C}(F) \rightarrow \mathcal{C}(K)$ ,  $\mathcal{L}(\varphi) \in \mathbb{P}(K)$  and  $\mathcal{L}(\varphi)|_F = \varphi$ , for all  $\varphi \in \mathbb{P}(F)$ .

In the following Lemma we will employ the properties stated in Lemma 4.7, in order to study the efficiency of our estimator.

**Lemma 4.8.** *For all  $K \in \mathcal{T}_h$ , it holds*

$$\eta_{K,1} \lesssim \text{osc}(\mathbf{f}, K) + \|p - p_h\|_K + \kappa^2 h_K \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_K + \|\nabla \times (\mathbf{u} - \mathbf{u}_h)\|_K, \quad (33a)$$

$$\eta_{K,2} \lesssim \text{osc}(\nabla \cdot \mathbf{f}, K) + \|\nabla(p - p_h)\|_K + \kappa^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_K. \quad (33b)$$

*Proof.* If we define  $R_h := \mathbf{f} - \bar{\epsilon} \nabla p_h + \kappa^2 \epsilon \mathbf{u}_h - \nabla \times \nabla \times \mathbf{u}_h$ , the proof follows the same steps as the proof of Lemma 6.4 in [13].  $\square$

**Lemma 4.9.** *For all  $K \in \mathcal{T}_h$  and  $F \in \partial K$ , there holds*

$$\eta_{F,3} \lesssim \|\mathbf{v}_h - \nabla \times \mathbf{u}_h\|_K.$$

*Proof.* The bound is deduced by the definition of  $\eta_{F,3}$  and the discrete trace inequality.  $\square$

**Lemma 4.10.** *For all  $F \in \mathcal{E}_I$ , there holds*

$$\eta_{F,4} \lesssim \text{osc}(\nabla \cdot \mathbf{f}, \omega_F) + \text{osc}(\mathbf{f}, \omega_F) + \kappa^2 \|\epsilon(\mathbf{u} - \mathbf{u}_h)\|_{\omega_F} + \kappa^2 h_{\omega_F} \|\tau_n(p_h - \hat{p}_h)\|_{\partial\omega_F} + \|\nabla(p - p_h)\|_{\omega_F}$$

where  $\omega_F := \cup\{K \in \mathcal{T}_h : \bar{K} \cap \bar{F} \neq \emptyset\}$ .

*Proof.* Let  $F \in \mathcal{E}_I$ , for a given  $w \in H_0^1(\omega_F)$ , we consider the product between  $\left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right]$  and  $w$ . Then, after applying integration by parts and using the divergence of (2b), we obtain that

$$\begin{aligned} \left\langle \left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right], w \right\rangle_F &= (\nabla \cdot \mathbf{f} - \Pi_Q \nabla \cdot \mathbf{f}, w)_{\omega_F} + (\Pi_Q(\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h)), w)_{\omega_F} \\ &\quad - \kappa^2 (\nabla \cdot (\epsilon \mathbf{u}_h), w)_{\omega_F} + (\bar{\epsilon} \nabla(p - p_h), \nabla w)_{\omega_F}, \end{aligned}$$

from which, using the Lemma 4.7, the properties of the extension operator  $\mathcal{L}$ , choosing  $w := B_F \mathcal{L} \left( \left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right] \right)$ , applying Cauchy-Schwarz inequality and inverse inequality it follows that

$$\begin{aligned} \left\| \left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right] \right\|_F^2 &\lesssim \left( \|\nabla \cdot \mathbf{f} - \Pi_Q \nabla \cdot \mathbf{f}\|_{\omega_F} + \|\Pi_Q(\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h))\|_{\omega_F} \right. \\ &\quad \left. + \kappa^2 \|\nabla \cdot (\epsilon \mathbf{u}_h)\|_{\omega_F} + h_{\omega_F}^{-1} \|\bar{\epsilon} \nabla(p - p_h)\|_{\omega_F} \right) \left\| B_F \mathcal{L} \left( \left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right] \right) \right\|_{\omega_F} \end{aligned}$$

where, by using the Lemma 4.7 again, we get

$$\left\| B_F \mathcal{L} \left( \left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right] \right) \right\|_{\omega_F} \lesssim h_F^{1/2} \left\| \left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right] \right\|_F.$$

Thus, from (22)

$$\begin{aligned} h_F^{1/2} \left\| \left[\left[\bar{\epsilon} \frac{\partial p_h}{\partial \mathbf{n}}\right]\right] \right\|_F &\lesssim h_F \|\nabla \cdot \mathbf{f} - \Pi_Q \nabla \cdot \mathbf{f}\|_{\omega_F} + h_F \|\nabla \cdot \mathbf{f} + \kappa^2 \nabla \cdot (\epsilon \mathbf{u}_h) - \nabla \cdot (\bar{\epsilon} \nabla p_h)\|_{\omega_F} \\ &\quad + \kappa^2 h_F^{1/2} h_{\omega_F}^{1/2} \|\tau_n(p_h - \hat{p}_h)\|_{\partial\omega_F} + h_F^{1/2} h_{\omega_F}^{-1/2} \|\bar{\epsilon} \nabla(p - p_h)\|_{\omega_F}. \end{aligned}$$

Hence, we conclude the proof from definitions of  $\eta_{F,4}$ ,  $\eta_{K,2}$  and from (33b).  $\square$

*Proof of Theorem 4.1.* It follows from Corollary 4.1, Lemma 4.8 and Lemma 4.10.

## 5 Numerical results

The numerical experiments were carry out by adapting the routines that we used for the implementation of the proposed HDG method in [10]. In our examples, we consider a unit cube  $\Omega := [0, 1]^3$  divided in two regions  $\Omega_d$  and  $\Omega_m$ , which are discretized by a sequence of quasi-uniform tetrahedral meshes. Each element of the meshes satisfies that its interior belongs to either  $\Omega_d$  or  $\Omega_m$ . Based on [19], we choose the wavelength  $\lambda_0 := 4.5$  (450 nm) and recall that  $\kappa := 2\pi/\lambda_0$ , that is,  $\kappa = 1.3963$ . Moreover, we use the following values for the relative electric permittivities,  $\epsilon_d := 2.7124$  and  $\epsilon_m := -5.8828 + i0.6650$ , which corresponds to the silicon oxynitride and evaporated silver, respectively.

The stabilization parameters are set to be  $\tau = -i$ ,  $\tau_n = i$  in all the experiments and therefore, a rate of convergence of order  $h^{k+1}$  in the  $L^2$  norm is expected for smooth solutions.

For an unknown  $w \in \{\mathbf{v}, \mathbf{u}, p\}$  the experimental order of convergence is defined as

$$r(w) = -3 \frac{\|w - w_{h_1}\|_{\Omega} / \|w - w_{h_2}\|_{\Omega}}{N_1 / N_2}, \quad (34)$$

where  $N_1$  and  $N_2$  are the number of elements of two consecutive meshes of sizes  $h_1$  and  $h_2$  ( $h_1 > h_2$ ), respectively. In the same way we define the experimental order of convergence  $r(E_h)$  for the global error  $E_h$  (cf. (5)). In addition, we recall the global contribution of each of the local error indicators specified in (6), as follows

$$\begin{aligned} \eta_1 &:= \left( \sum_{K \in \mathcal{T}_h} \eta_{K,1}^2 \right)^{1/2}, & \eta_2 &:= \left( \sum_{K \in \mathcal{T}_h} \eta_{K,2}^2 \right)^{1/2}, & \eta_1^\partial &:= \left( \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,1}^2 \right)^{1/2}, \\ \eta_2^\partial &:= \left( \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,2}^2 \right)^{1/2}, & \eta_3^\partial &:= \left( \sum_{K \in \mathcal{T}_h} \sum_{F \in \partial K} \eta_{F,3}^2 \right)^{1/2}, & \eta_4^\partial &:= \left( \sum_{F \in \mathcal{E}_I} \eta_{F,4}^2 \right)^{1/2}. \end{aligned}$$

Their respective experimental order of convergence are defined as in (34), where now the error estimator takes the place of the error.

## 5.1 Uniform refinement

**Example 5.1.** The domain  $\Omega$  is divided in  $\Omega_d := [0, 1] \times [0, 1] \times [0, 1/2]$  and  $\Omega_m := [0, 1] \times [0, 1] \times [1/2, 1]$ . We consider the exact solution  $\mathbf{u}(x, y, z) := (0, u_2(x, y, z), 0)^T$ , where

$$u_2(x, y, z) := \begin{cases} \exp(-i\kappa\sqrt{\epsilon_d}(z - 0.5)) + \exp(i\kappa\sqrt{\epsilon_d}(z - 0.5)), & \text{if } z \geq 0.5, \\ \exp(-i\kappa\sqrt{\epsilon_m}(z - 0.5)) + \exp(i\kappa\sqrt{\epsilon_m}(z - 0.5)), & \text{if } z < 0.5, \end{cases}$$

assume that  $p(x, y, z) := 0$  and calculate the values of  $\mathbf{f}$  and  $\mathbf{g}$ , taking into account the exact solution. We impose quasi-periodic boundary conditions on the vertical walls.

$k$	Nelts	$\ \mathbf{v} - \mathbf{v}_h\ _{\mathcal{T}_h}$	$\ \mathbf{u} - \mathbf{u}_h\ _{\mathcal{T}_h}$	$\ p - p_h\ _{\mathcal{T}_h}$	$r(\mathbf{v})$	$r(\mathbf{u})$	$r(p)$	$E_h$	$r(E_h)$
1	48	8.99e-01	3.72e-01	2.23e-02	-	-	-	7.53e+00	-
	384	2.88e-01	1.08e-01	6.42e-03	1.64	1.79	1.79	4.66e+00	0.69
	3072	7.84e-02	2.83e-02	1.71e-03	1.88	1.93	1.91	2.51e+00	0.89
	24576	2.02e-02	7.15e-03	4.46e-04	1.96	1.98	1.94	1.29e+00	0.96
2	48	1.77e-01	6.50e-02	5.12e-03	-	-	-	1.55e+00	-
	384	2.49e-02	9.04e-03	5.51e-04	2.83	2.84	3.22	4.31e-01	1.85
	3072	3.21e-03	1.14e-03	6.97e-05	2.96	2.99	2.98	1.11e-01	1.95
3	48	1.28e-02	6.15e-03	4.96e-04	-	-	-	1.42e-01	-
	384	1.01e-03	4.56e-04	3.06e-05	3.67	3.75	4.02	2.15e-02	2.72
	3072	6.74e-05	3.03e-05	2.02e-06	3.90	3.91	3.92	2.87e-03	2.90

Table 1: Rate of convergence and errors of Example 5.1 with  $\tau = -i$  and  $\tau_n = i$ . Error estimator and its rate of convergence.

$k$	Nelts	$\eta_1^\partial$	$\eta_2^\partial$	$\eta_3^\partial$	$\eta_4^\partial$	$r(\eta_1^\partial)$	$r(\eta_2^\partial)$	$r(\eta_3^\partial)$	$r(\eta_4^\partial)$
1	48	2.43e+00	2.62e-01	1.41e+01	1.23e+00	-	-	-	-
	384	1.43e+00	1.61e-01	7.78e+00	6.55e-01	0.76	0.70	0.86	0.91
	3072	7.58e-01	8.70e-02	4.00e+00	3.15e-01	0.92	0.89	0.96	1.06
	24576	3.86e-01	4.50e-02	2.01e+00	1.52e-01	0.97	0.95	0.99	1.05
2	48	4.72e-01	5.21e-02	3.76e+00	6.65e-01	-	-	-	-
	384	1.33e-01	1.39e-02	1.02e+00	1.89e-01	1.83	1.90	1.88	1.81
	3072	3.43e-02	3.70e-03	2.54e-01	5.23e-02	1.96	1.91	2.01	1.85
3	48	4.49e-02	6.04e-03	6.49e-01	1.65e-01	-	-	-	-
	384	6.89e-03	8.83e-04	9.60e-02	2.70e-02	2.70	2.77	2.76	2.61
	3072	9.13e-04	1.19e-04	1.26e-02	3.75e-03	2.91	2.89	2.93	2.85

Table 2: Rate of convergence and errors of the boundary terms of the error estimator of Example 5.1 with  $\tau = -i$  and  $\tau_n = i$ .

$k$	Nelts	$\eta_1$	$\eta_2$	$r(\eta_1)$	$r(\eta_2)$	$\eta$	$r(\eta)$	eff.
1	48	7.37e+00	9.87e-02	-	-	1.62e+01	-	2.14
	384	3.76e+00	2.53e-02	0.97	1.96	8.79e+00	0.88	1.89
	3072	1.89e+00	6.68e-03	1.00	1.92	4.50e+00	0.97	1.79
	24576	9.43e-01	1.70e-03	1.00	1.97	2.26e+00	0.99	1.76
2	48	3.08e+00	8.23e-01	-	-	4.99e+00	-	3.22
	384	8.55e-01	2.63e-01	1.85	1.64	1.38e+00	1.86	3.20
	3072	2.17e-01	7.26e-02	1.98	1.86	3.48e-01	1.99	3.12
3	48	8.24e-01	3.07e-01	-	-	1.11e+00	-	7.81
	384	1.19e-01	5.55e-02	2.79	2.47	1.65e-01	2.74	7.68
	3072	1.56e-02	7.72e-03	2.94	2.85	2.18e-02	2.92	7.58

Table 3: Rate of convergence and errors of the volumetric terms of the error estimator of Example 5.1 with  $\tau = -i$  and  $\tau_n = i$ . Effectivity index associated to the error estimator.

**Example 5.2.** We continue with the same setting as in Example 5.1, but considering the quasi-periodic solution

$$u_2(x, y, z) := \exp(-i[\kappa_x x + \kappa_y y - \kappa_z(z - 1)]),$$

with  $\kappa_x := \kappa \sin \theta \cos \phi$ ,  $\kappa_y := \kappa \sin \theta \sin \phi$ ,  $\kappa_z := (\kappa^2 - \kappa_x^2 - \kappa_y^2)^{1/2}$ ,  $\theta := \pi/3$  and  $\phi := \pi$ . The boundary conditions on the vertical walls are of quasi-periodic type.

In the history of convergence displayed in Tables 1 and 4, it is observed a rate of convergence of  $k + 1$  for the both unknowns,  $\mathbf{u}$  and  $\mathbf{v}$ , which is better than the predicted results in the Corollary 3.1. Moreover, we include the error of the a posteriori error estimator and its associated rate of convergence, which tends to the expected order  $k$ .

The error indicators and their rates of convergence appear in Tables 2, 3, 5 and 6. As we pointed out before, in this case the continuous embedding (25) holds true for  $\ell \in (0, 1)$ , therefore Corollary 4.1 cannot guarantee reliability of the estimator. However, the effectivity index,  $\text{eff} := \eta/E_h$  reported included in Tables 3 and 6 remains bounded for each polynomial degree.

$k$	Nelts	$\ \mathbf{v} - \mathbf{v}_h\ _{\mathcal{T}_h}$	$\ \mathbf{u} - \mathbf{u}_h\ _{\mathcal{T}_h}$	$\ p - p_h\ _{\mathcal{T}_h}$	$r(\mathbf{v})$	$r(\mathbf{u})$	$r(p)$	$E_h$	$r(E_h)$
1	48	1.37e-01	2.37e-01	7.38e-02	-	-	-	8.09e+00	-
	384	4.06e-02	1.02e-01	3.49e-02	1.76	1.22	1.08	6.00e+00	0.43
	3072	8.00e-03	2.98e-02	7.42e-03	2.34	1.77	2.23	3.32e+00	0.85
	24576	1.46e-03	8.26e-03	1.31e-03	2.46	1.85	2.50	1.69e+00	0.97
2	48	3.28e-02	8.69e-02	9.18e-02	-	-	-	5.08e+00	-
	384	8.52e-03	3.19e-02	1.76e-02	1.95	1.45	2.38	2.34e+00	1.12
	3072	1.05e-03	4.13e-03	2.35e-03	3.02	2.95	2.91	6.38e-01	1.87
3	48	2.89e-02	7.58e-02	4.86e-02	-	-	-	3.57e+00	-
	384	2.18e-03	6.73e-03	3.88e-03	3.73	3.49	3.65	6.52e-01	2.45
	3072	1.42e-04	4.84e-04	2.66e-04	3.94	3.80	3.87	9.02e-02	2.85

Table 4: Rate of convergence and errors of Example 5.2 with  $\tau = -i$  and  $\tau_n = i$ . Error estimator and its rate of convergence.

$k$	Nelts	$\eta_1^\partial$	$\eta_2^\partial$	$\eta_3^\partial$	$\eta_4^\partial$	$r(\eta_1^\partial)$	$r(\eta_2^\partial)$	$r(\eta_3^\partial)$	$r(\eta_4^\partial)$
1	48	6.39e-01	8.73e-01	1.90e+00	5.17e+00	-	-	-	-
	384	3.23e-01	8.58e-01	1.01e+00	7.76e+00	0.98	0.03	0.92	-0.59
	3072	1.44e-01	5.23e-01	3.95e-01	4.97e+00	1.17	0.71	1.35	0.64
	24576	5.61e-02	2.84e-01	1.74e-01	2.74e+00	1.36	0.88	1.18	0.86
2	48	1.94e-01	5.55e-01	1.35e+00	8.83e+00	-	-	-	-
	384	8.99e-02	2.88e-01	7.08e-01	4.59e+00	1.11	0.95	0.93	0.94
	3072	2.52e-02	8.00e-02	2.22e-01	1.22e+00	1.83	1.85	1.68	1.91
3	48	1.73e-01	3.51e-01	2.13e+00	7.16e+00	-	-	-	-
	384	2.60e-02	6.73e-02	3.39e-01	1.73e+00	2.73	2.38	2.65	2.05
	3072	3.64e-03	9.56e-03	4.86e-02	2.50e-01	2.84	2.81	2.80	2.79

Table 5: Rate of convergence and errors of the boundary terms, that appear in the error estimator of Example 5.2, with  $\tau = -i$  and  $\tau_n = i$ .

## 5.2 Adaptive refinement

The adaptive refinement can be carried out following the next steps:

- Solve the variational problem in a coarse mesh.
- Estimate  $\eta_K$ , for each  $K \in \mathcal{T}_h$ .
- Mark each  $\tilde{K} \in \mathcal{T}_h$  such that  $\eta_{\tilde{K}} > \theta \max_{K \in \mathcal{T}_h} \eta_K$ , for  $\theta \in [0, 1]$ .
- Refine the coarse mesh and repeat the algorithm until the established stopping criterion allows it. In this step, we use the free library TetGen integrated with MATLAB, see <https://wias-berlin.de/software/tetgen/>.

In the adaptive procedure, the a posteriori error indicators help to identify the elements of a mesh where the errors are bigger than others. Once those parts are found, the algorithm refine them to generate a new refined mesh, as we will illustrate in the following example.

$k$	Nelts	$\eta_1$	$\eta_2$	$r(\eta_1)$	$r(\eta_2)$	$\eta$	$r(\eta)$	eff.
1	48	9.57e-01	8.48e+00	-	-	1.02e+01	-	1.26
	384	4.09e-01	5.76e+00	1.23	0.56	9.77e+00	0.07	1.63
	3072	1.58e-01	2.88e+00	1.37	1.00	5.78e+00	0.76	1.74
	24576	7.05e-02	1.44e+00	1.17	1.00	3.11e+00	0.89	1.84
2	48	1.21e+00	8.81e+00	-	-	1.26e+01	-	2.48
	384	6.19e-01	3.10e+00	0.97	1.51	5.63e+00	1.16	2.41
	3072	2.63e-01	8.29e-01	1.24	1.90	1.52e+00	1.89	2.38
3	48	2.79e+00	7.57e+00	-	-	1.10e+01	-	3.08
	384	5.19e-01	1.38e+00	2.43	2.46	2.30e+00	2.26	3.53
	3072	7.38e-02	1.99e-01	2.81	2.79	3.32e-01	2.79	3.68

Table 6: Rate of convergence and errors of the volumetric terms of the error estimator of Example 5.2 with  $\tau = -i$  and  $\tau_n = i$ . Effectivity index of the error estimator.

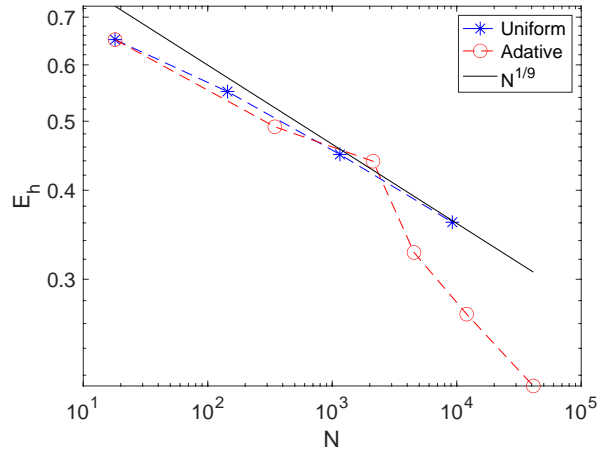


Figure 2: Total error  $E_h$  versus number of elements  $N$  (logarithmic scale) of the approximation of Example 5.3. Uniform and adaptive refinements.

**Example 5.3. (*L-shaped domain*)** With the aim to illustrate the adaptive performance of our HDG scheme, we include an experiment in a *L-shaped domain*  $\Omega := [-1, 1] \times [-1, 1] \times [0, 1] \setminus ([0, 1] \times [-1, 0] \times [0, 1])$  occupied by a material with relative permittivity  $\epsilon := 1$ . As in Section 5 of [14], let us consider the exact solution  $p(x, y, z) := 0$  and  $\mathbf{u}(x, y, z) := \left( \frac{\partial S}{\partial x}, \frac{\partial S}{\partial y}, 0 \right)^T$ , where  $S(r, \theta) := r^{\frac{2n}{3}} \sin\left(\frac{2n\theta}{3}\right)$  is given in terms of cylindrical coordinates  $(r, \theta)$  and  $n$  is a given number. Moreover, as in the above examples, the source term and boundary data were derived from the exact solution. The stabilization parameters satisfies  $|\tau| = |\tau_n| = 1$  and we choose  $n$  such that  $\frac{2n}{3} = t$ .

The adaptive refinement of our domain was carried out for  $k = 1$  and we began with a coarse mesh of 18 elements, in which were marked the tetrahedra  $\widetilde{K}$  that satisfy the adaptive criterion  $\eta_{\widetilde{K}} > \theta \max_{K \in \mathcal{T}_h} \eta_K$ , for  $\theta = 0.1$ , in order to refine them.

Figure 2 depicts the obtained errors versus the number of the elements, when the meshes are uniformly refined and by using adaptive criterion.

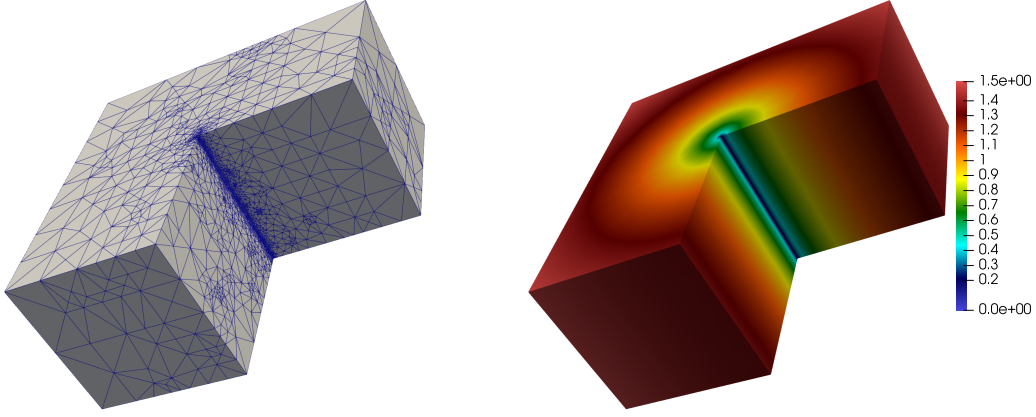


Figure 3: Approximation of the electric field intensity  $|\mathbf{u}_h|$  and corresponding adaptive refined mesh of Example 5.3 with  $k = 1$  and  $N = 41226$ .

## 6 Concluding Remarks

In this contribution, we extend our *a priori* error analysis of the HDG method for Maxwell's equations in heterogeneous media with Dirichlet boundary condition, to a problem with quasi-periodic boundary conditions on the vertical boundaries of the physical domain. Although, for the real problem it is still necessary to consider transmission conditions on the top and bottom of the cell, the obtained theoretical and numerical results allow us to classify our method as suitable for carrying out the numerical approximation of the solution for this type of boundary value problems.

With the aim to strengthen our stability estimates, we develop an *a posteriori* error analysis for the HDG scheme. Based on the confiability and efficiency proofs of the proposed *a posteriori* error estimator, we decide to corroborate the theoretical results by means of some numerical experiments. In them, we use uniformly refined meshes and depict the history of convergence in some tables.

The performance of the adaptive case was showed for the HDG method proposed for the problem with Dirichlet boundary condition [10]. The behavior of the error can be observed in a graph (Figure 2), in which it is compared with the obtained error in the case of uniform refinement.

We expect to carry out the adaptive case, for an HDG method proposed for the problem with quasi-periodic and transmission conditions, by employing periodic meshes.

## A Appendix

### A.1 Helmholtz decomposition

In this appendix we will extend the Helmholtz decomposition given in [21, section 6], for spaces with quasi-periodic conditions. Let us remark that the boundary  $\Gamma = \partial\Omega$  is split in two subsets  $\Gamma_0$  and  $\Gamma_{QP}$  where  $\bar{\Gamma}_0$  and  $\bar{\Gamma}_{QP}$  are compact Lipschitz submanifold of  $\Gamma$  and  $\Omega$  is simply connected. Let  $3 \times 3$  matrix value function  $\omega$  satisfying the following symmetry, boundedness and ellipticity conditions

$$\omega_{ij} = \omega_{ji} \in L^\infty(\Omega) \quad i, j = 1, 2, 3, \quad \sum_{i,j=1}^3 \omega_{ij} \xi_i \xi_j \geq \omega_* \|\boldsymbol{\xi}\|^2 \quad \text{a.e. in } \Omega \quad \forall \boldsymbol{\xi} \in \mathbb{R}^3.$$

**Proposition A.1.** *It holds*

$$\mathbf{L}^2(\Omega) = \nabla \mathbf{H}_{\Gamma_0}^{1,\text{QP}}(\Omega) \oplus \mathbf{H}_{\Gamma_{\text{QP}}}(\text{div}_\omega^0; \Omega)$$

and the subspaces of the right-hand are closed and  $\omega$ -orthogonal in  $\mathbf{L}^2(\Omega)$ , where

$$\mathbf{H}_{\Gamma_0}^{1,\text{QP}}(\Omega) := \left\{ \psi \in \mathbf{H}_{\Gamma_0}^1(\Omega) : \psi|_{\Gamma_2} = e^{i\alpha L} \psi|_{\Gamma_1}, \psi|_{\Gamma_4} = e^{i\beta L} \psi|_{\Gamma_3} \right\}.$$

*Proof.* The proof follows similar lines to those in [21, Proposition 6.1] taking into account that  $\mathbf{H}_{\Gamma_0}^{1,\text{QP}}(\Omega)$  is a closed subspace of  $\mathbf{H}^1(\Omega)$ .  $\square$

## A.2 Proof of Lemma 4.1

In this part we present a sketch of the proof of (7c)–(7d), which is included in Lemma 4.1, by tailoring the arguments employed in the deduction of the properties stated in Proposition 4.5 of [25].

To begin, we recall the definitions of the moments for Nédélec's elements ([35], Definition 5.30), in a tetrahedron  $K$ :

$$\begin{aligned} M_e(\mathbf{w}) &:= \left\{ \int_e (\mathbf{w} \cdot \mathbf{t}_e) \mathbf{q} \, ds : \text{for all } \mathbf{q} \in \mathbf{P}_{k-1}(e) \right\}, \text{ for any edge } e \text{ of } K \\ M_F(\mathbf{w}) &:= \left\{ \frac{1}{\text{area}(F)} \int_F (\mathbf{w} \cdot \mathbf{q}) \, dA : \text{for all } \mathbf{q} \in \mathbf{P}_{k-2}(F) \wedge \mathbf{q} \cdot \mathbf{n} = 0 \right\}, \text{ for any face } F \text{ of } K, \\ M_K(\mathbf{w}) &:= \left\{ \int_K (\mathbf{w} \cdot \mathbf{q}) \, dV : \text{for all } \mathbf{q} \in \mathbf{P}_{k-3}(K) \right\}, \end{aligned}$$

where  $\mathbf{t}_e$  denotes the unit vector in the direction of the edge  $e$ . For a given  $K \in \mathcal{T}_h$ , let  $\{\varphi_{K,e}^j\}$ ,  $\{\varphi_{K,F}^j\}$ ,  $\{\varphi_{K,b}^j\}$  the Lagrange basis functions of  $\mathbf{P}_k(K)$  with respect to the moments for Nédélec's elements. Then, there exists  $\mathbf{w}^c \in \mathbf{V}_h^c$  that satisfies (7c) and can be decomposed as

$$\mathbf{w}^c|_K = \sum_{e \in \mathcal{L}_h(K)} \sum_{j=1}^{N_e} \alpha_{K,e}^j \varphi_{K,e}^j + \sum_{F \in \mathcal{E}_h(K)} \sum_{j=1}^{N_F} \alpha_{K,F}^j \varphi_{K,F}^j + \sum_{j=1}^{N_b} \alpha_{K,b}^j \varphi_{K,b}^j,$$

where  $\mathcal{L}_h(K)$  and  $\mathcal{E}_h(K)$  denote the set of edges and faces of  $K$ , respectively. Here,  $N_e$ ,  $N_F$  and  $N_b$  are the number of basis functions associated to the edges, faces and interior of  $K$ , respectively; and  $\alpha_{K,e}^j$ ,  $\alpha_{K,F}^j$  and  $\alpha_{K,b}^j$  are the coefficients that are uniquely determined.

Based on  $\mathbf{w}^c$ , we build a function in  $\mathbf{V}_h^c$  that also satisfies quasi-periodic conditions. To that end, we just modify the degrees of freedom associated to the edges and faces that belong to  $\Gamma_2$  and  $\Gamma_4$ . More precisely, let  $\mathcal{L}_{\Gamma_j}(K)$  and  $\mathcal{E}_{\Gamma_j}(K)$  denote the set of edges and faces of  $K$ , lying on  $\Gamma_j$ ,  $j = 1, 2, 3$  and  $4$ , respectively. We also write  $\mathcal{L}_{\text{QP}}(K) := \cup_{j=1}^4 \mathcal{L}_{\Gamma_j}(K)$  and  $\mathcal{E}_{\text{QP}}(K) := \cup_{j=1}^4 \mathcal{E}_{\Gamma_j}(K)$ . Let us now recall that we are assuming conformity between the discretizations of the periodic boundaries  $\Gamma_1$ – $\Gamma_2$  and  $\Gamma_3$ – $\Gamma_4$ . Therefore, for an edge  $e_2$  (face  $F_2$ ) belonging to  $\Gamma_2$ , there is an edge  $e_1$  (face  $F_1$ ) belonging to  $\Gamma_1$  “aligned” to  $e_2$  (face  $F_2$ ). Similarly for the periodic boundary  $\Gamma_3$  –  $\Gamma_4$ . On each  $K$  such that



$\overline{K} \cap \Gamma_{\text{QP}} = \emptyset$ , we set  $\mathbf{w}^{\text{QP}} = \mathbf{w}^c$  and, for  $K$  such that  $\overline{K} \cap \Gamma_{\text{QP}} \neq \emptyset$ , we set

$$\begin{aligned} \mathbf{w}^{\text{QP}}|_K := & \sum_{j=1}^{N_b} \alpha_{K,b}^j \varphi_{K,b}^j + \sum_{e \in \mathcal{L}_h(K) \setminus (\mathcal{L}_{\Gamma_2}(K) \cup \mathcal{L}_{\Gamma_4}(K))} \sum_{j=1}^{N_e} \alpha_{K,e}^j \varphi_{K,e}^j + \sum_{F \in \mathcal{E}_h(K) \setminus (\mathcal{E}_{\Gamma_2}(K) \cup \mathcal{E}_{\Gamma_4}(K))} \sum_{j=1}^{N_F} \alpha_{K,F}^j \varphi_{K,F}^j \\ & + \sum_{F_2 \in \mathcal{E}_{\Gamma_2}(K)} \sum_{j=1}^{N_{F_2}} \beta_{K,F_2}^j \varphi_{K,F_2}^j + \sum_{F_4 \in \mathcal{E}_{\Gamma_4}(K)} \sum_{j=1}^{N_{F_4}} \beta_{K,F_4}^j \varphi_{K,F_4}^j \\ & + \sum_{e_2 \in \mathcal{L}_{\Gamma_2}(K)} \sum_{j=1}^{N_{e_2}} \beta_{K,e_2}^j \varphi_{K,e_2}^j + \sum_{e_4 \in \mathcal{L}_{\Gamma_4}(K)} \sum_{j=1}^{N_{e_4}} \beta_{K,e_4}^j \varphi_{K,e_4}^j, \end{aligned}$$

where,

$$\beta_{K,F_2}^j := e^{i\alpha L} \alpha_{K',F_1}^j, \quad \beta_{K,e_2}^j := e^{i\alpha L} \alpha_{K',e_1}^j, \quad \beta_{K,F_4}^j := e^{i\beta L} \alpha_{K',F_3}^j, \quad \beta_{K,e_4}^j := e^{i\beta L} \alpha_{K',e_3}^j \quad (35)$$

and  $K'$  is the “neighbor” of  $K$  across  $\Gamma_{\text{QP}}$ .

We notice that  $\mathbf{w}^{\text{QP}} \in \mathbf{V}_h^c$  since all the degrees of freedom associated to interior edges and faces have remained unchanged. Moreover, the continuity of the Lagrange basis function and the relation (35), between the coefficients, imply that  $\mathbf{w}^{\text{QP}}$  is quasi-periodic. Hence,

$$\begin{aligned} (\mathbf{w}^c - \mathbf{w}^{\text{QP}})|_K = & \sum_{F_2 \in \mathcal{E}_{\Gamma_2}(K)} \sum_{j=1}^{N_{F_2}} (\alpha_{K,F_2}^j - \beta_{K,F_2}^j) \varphi_{K,F_2}^j + \sum_{F_4 \in \mathcal{E}_{\Gamma_4}(K)} \sum_{j=1}^{N_{F_4}} (\alpha_{K,F_4}^j - \beta_{K,F_4}^j) \varphi_{K,F_4}^j \\ & + \sum_{e_2 \in \mathcal{L}_{\Gamma_2}(K)} \sum_{j=1}^{N_{e_2}} (\alpha_{K,e_2}^j - \beta_{K,e_2}^j) \varphi_{K,e_2}^j + \sum_{e_4 \in \mathcal{L}_{\Gamma_4}(K)} \sum_{j=1}^{N_{e_4}} (\alpha_{K,e_4}^j - \beta_{K,e_4}^j) \varphi_{K,e_4}^j \end{aligned}$$

and by using (35), we obtain

$$\begin{aligned} \int_K |\mathbf{w}^c - \mathbf{w}^{\text{QP}}|^2 \lesssim h_K \bigg( & \sum_{F_2 \in \mathcal{E}_{\Gamma_2}(K)} \sum_{j=1}^{N_{F_2}} (\alpha_{K,F_2}^j - e^{i\alpha L} \alpha_{K',F_1}^j)^2 + \sum_{F_4 \in \mathcal{E}_{\Gamma_4}(K)} \sum_{j=1}^{N_{F_4}} (\alpha_{K,F_4}^j - e^{i\beta L} \alpha_{K',F_3}^j)^2 \\ & + \sum_{e_2 \in \mathcal{L}_{\Gamma_2}(K)} \sum_{j=1}^{N_{e_2}} (\alpha_{K,e_2}^j - e^{i\alpha L} \alpha_{K',e_1}^j)^2 + \sum_{e_4 \in \mathcal{L}_{\Gamma_4}(K)} \sum_{j=1}^{N_{e_4}} (\alpha_{K,e_4}^j - e^{i\beta L} \alpha_{K',e_3}^j)^2 \bigg). \end{aligned}$$

Then, taking into account the above estimate and the fact that for a function  $\mathbf{w}$ , the tangential trace

on a face  $F$  is uniquely determined by the degrees of freedom  $M_F(\mathbf{w})$  and  $M_e(\mathbf{w})$ , we have that

$$\begin{aligned}
\int_K |\mathbf{w}^c - \mathbf{w}^{\text{QP}}|^2 &\lesssim h_K \left( \sum_{F_2 \in \mathcal{E}_{\Gamma_2}(K)} \int_{F_2} |\mathbf{n}^+ \times (\mathbf{w}^c - \mathbf{w}^{\text{QP}})|^2 + \sum_{F_4 \in \mathcal{E}_{\Gamma_4}(K)} \int_{F_4} |\mathbf{n}^+ \times (\mathbf{w}^c - \mathbf{w}^{\text{QP}})|^2 \right. \\
&\quad \left. + \sum_{e_2 \in \mathcal{L}_{\Gamma_2}(K)} \int_{\mathcal{L}_{\Gamma_2}(K)} |\mathbf{n}^+ \times (\mathbf{w}^c - \mathbf{w}^{\text{QP}})|^2 + \sum_{e_4 \in \mathcal{L}_{\Gamma_4}(K)} \int_{\mathcal{L}_{\Gamma_4}(K)} |\mathbf{n}^+ \times (\mathbf{w}^c - \mathbf{w}^{\text{QP}})|^2 \right) \\
&\lesssim h_K \left( \sum_{F_2 \in \mathcal{E}_{\Gamma_2}(K)} \int_{F_2} |\mathbf{n}^+ \times \mathbf{w}^c + (\mathbf{n}^- \times e^{i\alpha L} \mathbf{w}^c)|_{K', F_1}|^2 \right. \\
&\quad + \sum_{F_4 \in \mathcal{E}_{\Gamma_4}(K)} \int_{F_4} |\mathbf{n}^+ \times \mathbf{w}^c + (\mathbf{n}^- \times e^{i\beta L} \mathbf{w}^c)|_{K', F_3}|^2 \\
&\quad + \sum_{e_2 \in \mathcal{L}_{\Gamma_2}(K)} \int_{e_2} |\mathbf{n}^+ \times \mathbf{w}^c + (\mathbf{n}^- \times e^{i\alpha L} \mathbf{w}^c)|_{K', e_1}|^2 \\
&\quad \left. + \sum_{e_4 \in \mathcal{L}_{\Gamma_4}(K)} \int_{e_4} |\mathbf{n}^+ \times \mathbf{w}^c + (\mathbf{n}^- \times e^{i\beta L} \mathbf{w}^c)|_{K', e_3}|^2 \right) \\
&= h_K \left( \sum_{F_2 \in \mathcal{E}_{\Gamma_2}(K)} \int_{F_2} \llbracket \mathbf{w}^c \rrbracket_{\text{QP}} + \sum_{F_4 \in \mathcal{E}_{\Gamma_4}(K)} \int_{F_4} \llbracket \mathbf{w}^c \rrbracket_{\text{QP}} \right. \\
&\quad \left. + \sum_{e_2 \in \mathcal{L}_{\Gamma_2}(K)} \int_{e_2} \llbracket \mathbf{w}^c \rrbracket_{e_2} + \sum_{e_4 \in \mathcal{L}_{\Gamma_4}(K)} \int_{e_4} \llbracket \mathbf{w}^c \rrbracket_{e_4} \right).
\end{aligned}$$

Therefore, we deduce that

$$\|\mathbf{w}^c - \mathbf{w}^{\text{QP}}\|_{\mathcal{T}_h} \lesssim \|h^{1/2} \llbracket \mathbf{w}^c \rrbracket_{\text{QP}}\|_{\Gamma_{\text{QP}}} = \|h^{1/2} \llbracket \mathbf{w} \rrbracket_{\text{QP}}\|_{\Gamma_{\text{QP}}}.$$

The last equality since  $\gamma_t(\mathbf{w}) = \gamma_t(\mathbf{w}^c)$  on  $\Gamma_{\text{QP}}$ .

Finally, (7c) follows by adding and subtracting  $\mathbf{w} \in \mathbf{V}_h$  in  $\|\mathbf{w}^c - \mathbf{w}^{\text{QP}}\|_{\mathcal{T}_h}$ , applying the triangle inequality together with the above expression and (7a). The estimate (7d) is obtained using the inverse inequality  $\|\nabla \times (\mathbf{w} - \mathbf{w}^{\text{QP}})\|_{\mathcal{T}_h} \lesssim h^{-1} \|\mathbf{w} - \mathbf{w}^{\text{QP}}\|_{\mathcal{T}_h}$  and (7c).

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**Author contributions:** As a convention, the names of the authors are alphabetically order. All authors contributed equally in this article.

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