A virtual element method for the Steklov eigenvalue problem allowing small edges.

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Abstract

The aim of this paper is to analyze the influence of small edges in the computation of the spectrum of the Steklov eigenvalue problem by a lowest order virtual element method. Under weaker assumptions on the polygonal meshes, which can permit arbitrarily small edges with respect to the element diameter, we show that the scheme provides a correct approximation of the spectrum and prove optimal error estimates for the eigenfunctions and a double order for the eigenvalues. Finally, we report some numerical tests supporting the theoretical results.

Key words: Virtual element method, Steklov eigenvalue problem, error estimates, small edges
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1. Introduction

In this paper we are interested in the approximation by virtual elements of the eigenvalues and eigenfunctions of the Steklov problem which is characterized by the presence of the eigenvalue on the boundary condition. This problem has attracted much attention in recent years due to the important applications in many physical subjects. For instance, it appears in the study of the dynamic of liquids in moving containers, the so called sloshing problem [6, 19, 23]. Also, this problem have interesting applications in inverse scattering [33], among other.

There are several studies on the finite element approximations of the Steklov eigenvalue problem, for example, see [3, 4, 15, 26, 32, 43, 44]. Traditionally, finite element methods rely on triangular (simplicial) and quadrilateral meshes. However, in complex simulations one often encounters general polygonal and polyhedral meshes. In recent years there has been a significant growth in the mathematical and engineering literature in developing numerical methods that can make use of general polytopal meshes; among the large number of papers on this subject, we cite as a minimal sample [7, 9, 20, 25, 41, 42].

The VEM has been introduced in [7] and has been applied successfully in a large range of problems arising from engineering and physics phenomenons; see for instance [1, 2, 8, 10, 12, 14, 18, 21, 34, 40]. Regarding VEM for eigenvalue problems, we mention the following recent works

[22, 24, 27, 28, 35, 36, 37, 38, 39]. In particular, an a priori and a posteriori VEM discretization for the Steklov eigenvalue problem has been presented in [37, 38]. However, the theoretical results and error estimates for the eigenvalues and eigenfunctions were obtained under the standard mesh assumptions introduced in [7], which do not allow to consider meshes containing elements with small edges compared to the element diameter.

In [11, 13, 17] has been recently analyzed the possibility to consider in VEM discretizations arbitrarily small edges with respect to the element diameter. Here, we will follow the VEM approach presented in [11], for the Poisson equation, to write a lowest order virtual scheme for the Steklov eigenvalue problem which permit arbitrarily small edges in the polygonal meshes. This can be useful in adaptive schemes by considering refined meshes as a tool to handle solutions with corner singularities.

More precisely, we will propose a virtual element method of lowest order to solve the Steklov eigenproblem, allowing small edges in the polygons of the mesh. We will consider the continuous variational formulation presented in [37]; however, we will write a different discrete virtual scheme, which is based on a different stabilization bilinear form (see [45]). We will use the so-called Babuška-Osborn abstract spectral approximation theory (see [5]), to show that under weaker assumptions on the polygonal meshes, the resulting virtual element scheme provides a correct approximation of the spectrum and prove optimal order error estimates for the eigenfunctions and a double order for the eigenvalues. In particular, our theoretical estimates fully support meshes with arbitrarily small edges with respect to the element diameter. In addition, we remark that spurious modes were not found for different values of the a scaled stabilization (see in particular Section 5.1 below). Moreover, the present work can be seen as a stepping stone towards the more challenging eigenvalue problems.

The paper is organized as follows: In Section 2, we present the model problem and preliminary results related to the solution operator and eigenfunctions. More precisely, we will establish the spectral characterization of the solution operator, which allows to study the numerical method. Section 3 is dedicated to present the virtual element method. Here we will introduce the assumptions on the mesh. We will present approximation results that will be the key point of our analysis, which will depend on the particular choice of the stabilization form. Section 4, contains the error estimates for the eigenfunctions and a double order for the eigenvalues. Finally, in Section 5 we present some numerical results on different families of polygonal meshes with small edges, in order to confirm the theoretical rates of convergence proved in the paper and to confirm that it is not polluted with spurious modes.

Throughout the article we will use standard notations for Sobolev spaces, norms and seminorms. Moreover, we will denote by C a generic constant independent of the mesh parameter h, which may take different values in different occurrences.

2. The spectral problem

Let $\Omega \subset \mathbb{R}^2$ be a bounded domain with polygonal boundary $\partial\Omega$. Let Γ_0 and Γ_1 be disjoint open subsets of $\partial\Omega$ such that $\partial\Omega = \bar{\Gamma}_0 \cup \bar{\Gamma}_1$ and $|\Gamma_0| \neq 0$. We denote by n the outward unit normal vector to $\partial\Omega$ and by ∂_n the normal derivative.

In what follows, we recall the variational formulation of the Steklov eigenvalue problem proposed in [37]. Also, we summarize some results from this reference.

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The Steklov eigenvalue problem reads as follows: Find $(\lambda, u) \in \mathbb{R} \times H^1(\Omega)$, $u \neq 0$, such that

$$\begin{cases} \Delta u = 0 & \text{in } \Omega, \\ \partial_n u = \begin{cases} \lambda u & \text{on } \Gamma_0, \\ 0 & \text{on } \Gamma_1. \end{cases} \end{cases}$$

where $\partial_n u$ denotes the normal derivative of u. By testing the first equation above with $v \in H^1(\Omega)$ and integrating by parts, we arrive at the following equivalent variational formulation:

Problem 1. *Find $(\lambda, u) \in \mathbb{R} \times H^1(\Omega)$, $u \neq 0$, such that*

$$\int_\Omega \nabla u \cdot \nabla v = \lambda \int_{\Gamma_0} uv \qquad \forall v \in H^1(\Omega).$$

Observe that the left-hand side is not $H^1(\Omega)$-elliptic. A remedy for this is to use a shift argument to rewrite Problem 1 in the following form:

Problem 2. *Find $(\lambda, u) \in \mathbb{R} \times H^1(\Omega)$, $u \neq 0$, such that*

$$\widehat{a}(u, v) = (\lambda + 1)\, b(u, v) \qquad \forall v \in H^1(\Omega),$$

where the bilinear form $\widehat{a} : H^1(\Omega) \times H^1(\Omega) \to \mathbb{R}$ is defined by

$$\widehat{a}(u, v) := a(u, v) + b(u, v) \qquad u, v \in H^1(\Omega),$$

with $a, b : H^1(\Omega) \times H^1(\Omega) \to \mathbb{R}$ defined by

$$a(u, v) := \int_\Omega \nabla u \cdot \nabla v, \qquad b(u, v) := \int_{\Gamma_0} uv \qquad u, v \in H^1(\Omega).$$

All the previous bilinear forms are bounded and symmetric. In addition, the next result, proved in [37, Lemma 2.1], establishes that $\widehat{a}(v, v)$ is $H^1(\Omega)$-elliptic.

Lemma 2.1. *There exists a constant $\alpha > 0$, depending on Ω, such that*

$$\widehat{a}(v, v) \geq \alpha \, \|v\|_{1,\Omega}^2 \qquad \forall v \in H^1(\Omega).$$

Next, we define the solution operator associated with Problem 2:

$$\begin{aligned} T : \ H^1(\Omega) &\longrightarrow H^1(\Omega), \\ f &\longmapsto Tf := w, \end{aligned}$$

where $w \in H^1(\Omega)$ is the unique solution (as a consequence of Lemma 2.1 and the Lax-Milgram Theorem) of the following source problem:

$$\widehat{a}(w, v) = b(f, v) \qquad \forall v \in H^1(\Omega). \tag{2.1}$$

Thus, the linear operator T is well defined and bounded. Also, T is self-adjoint with respect to the inner product $\widehat{a}(\cdot, \cdot)$ in $H^1(\Omega)$ (see [37, Section 2]).

Notice that $(\lambda, u) \in \mathbb{R} \times H^1(\Omega)$ solves Problem 2 (and hence Problem 1) if and only if $Tu = \mu u$ with $\mu \neq 0$ and $u \neq 0$, in which case $\mu := 1/(1 + \lambda)$.

The following additional regularity result for the solution of problem (2.1) and consequently, for the eigenfunctions of T, has been proved in [37, Lemma 2.2].

Lemma 2.2. *i) for all $f \in H^1(\Omega)$, there exist $r \in (1/2, 1]$ and $C > 0$ such that the solution w of problem (2.1) satisfies $w \in H^{1+r}(\Omega)$ and*

$$\|w\|_{1+r,\Omega} \leq C \|f\|_{1,\Omega};$$

ii) if u is an eigenfunction of Problem 1 with eigenvalue λ, there exist $r > 1/2$ and $C > 0$ (depending on λ) such that $u \in H^{1+r}(\Omega)$ and

$$\|u\|_{1+r,\Omega} \leq C \|u\|_{1,\Omega}.$$

Remark 2.1. *The constant $r > 1/2$ is the Sobolev exponent for the Laplace problem with Neumann boundary conditions. If Ω is convex, then $r \geq 1$, whereas, otherwise, $r := \pi/\omega$ with ω being the largest reentrant angle of Ω (see [30]).*

Hence, as a consequence of the compact inclusion $H^{1+r}(\Omega) \hookrightarrow H^1(\Omega)$, T is a compact operator. We have the following spectral characterization for the operator T.

Theorem 2.1. *The spectrum of T decomposes as follows:* $\mathrm{sp}(T) = \{0, 1\} \cup \{\mu_k\}_{k \in \mathbb{N}}$, *where:*

i) $\mu = 1$ is an eigenvalue of T and its associated eigenspace is the space of constant functions in Ω;

ii) $\mu = 0$ is an infinite-multiplicity eigenvalue of T with associated eigenspace is $H^1_{\Gamma_0}(\Omega) := \left\{ q \in H^1(\Omega) : \; q = 0 \text{ on } \Gamma_0 \right\}$;

iii) $\{\mu_k\}_{k \in \mathbb{N}} \subset (0, 1)$ is a sequence of finite-multiplicity eigenvalues of T which converge to 0 and their corresponding eigenspaces lie in $H^{1+r}(\Omega)$.

3. VEM discretization

We will study in this section, the virtual element numerical approximation of the eigenproblem presented in Problem 2, by considering weaker mesh assumptions than the mesh assumptions considered in [37]. We will follow some recent results from [11, 17] for the Poisson problem. With this aim, first we recall the mesh construction.

Let $\{\mathcal{T}_h\}_h$ be a sequence of decompositions of Ω into polygons K. Let h_K denote the diameter of the element K and h the maximum of the diameters of all the elements of the mesh, i.e., $h := \max_{K \in \Omega} h_K$. For $\mathcal{T}_h$ we will consider the following assumption:

- **A1.** There exists $\gamma > 0$ such that, for all meshes $\mathcal{T}_h$, each polygon $K \in \mathcal{T}_h$ is star-shaped with respect to a ball of radius greater than or equal to γh_K.

The next results will be obtained only under assumption **A1.** In particular, we can consider meshes with edges arbitrarily small with respect to the element diameter h_K.

We consider now a simple polygon K, we define

$$\mathbb{B}_1(\partial K) := \left\{ v \in C^0(\partial K) : v|_e \in \mathbb{P}_1(e) \text{ for all edges } e \subset \partial K \right\}.$$

We then consider the finite-dimensional space defined as follows:

$$V^K := \left\{ v \in H^1(K) : \; v|_{\partial K} \in \mathbb{B}_1(\partial K) \text{ and } \Delta v|_K = 0 \right\}.$$

As in [11], we choose the following degrees of freedom: For all $v_h \in V^K$, they are defined as follows:

- values of v_h at the N_K vertices of K.

Next, for every decomposition $\mathcal{T}_h$ of Ω into simple polygons K, we define the global virtual space
$$V_h := \left\{ v \in H^1(\Omega) : \ v|_K \in V^K \right\}.$$

In order to construct the discrete scheme, we need some preliminary definitions. First, we split the bilinear form $\widehat{\boldsymbol{a}}(\cdot, \cdot)$ as follows:
$$\widehat{\boldsymbol{a}}(w, v) = \sum_{K \in \mathcal{T}_h} a^K(w, v) + b(w, v) \qquad w, v \in H^1(\Omega),$$
where
$$a^K(w, v) := \int_K \nabla w \cdot \nabla v \qquad w, v \in H^1(\Omega).$$

Next, for any $K \in \mathcal{T}_h$ and for any sufficiently regular function v, we define first
$$\overline{v} := |\partial K|^{-1} \int_{\partial K} v. \tag{3.1}$$

Now, we define the projector $\Pi^K : V^K \longrightarrow \mathbb{P}_1(K) \subseteq V^K$ for each $v \in V^K$ as the solution of
$$a^K\left(\Pi^K v, q\right) = a^K(v, q) \qquad \forall q \in \mathbb{P}_1(K),$$
$$\overline{\Pi^K v} = \overline{v}.$$

Now, we introduce the following symmetric and semi-positive definite bilinear form on $V^K \times V^K$ (see [45]). For all elements $K \in \mathcal{T}_h$:
$$S^K(w_h, v_h) := h_K \int_{\partial K} \partial_s w_h \partial_s v_h \qquad \forall w_h, v_h \in V^K, \tag{3.3}$$
where ∂_s denotes a derivative along the edge.

Then, set
$$a_h(w_h, v_h) := \sum_{K \in \mathcal{T}_h} a_h^K(w_h, v_h) \qquad w_h, v_h \in V_h,$$
where $a_h^K(\cdot, \cdot)$ is the bilinear form defined on $V^K \times V^K$ by
$$a_h^K(w, v) := a^K\left(\Pi^K w, \Pi^K v\right) + S^K\left(w - \Pi^K w, v - \Pi^K v\right) \qquad w, v \in V^K. \tag{3.4}$$

Now, we introduce the following discrete semi-norm:
$$\|v\|_K^2 := a^K\left(\Pi^K v, \Pi^K v\right) + S^K(v - \bar{v}, v - \bar{v}) \qquad \forall v \in V^K + \mathcal{V}^K, \tag{3.5}$$
where $\mathcal{V}^K \subseteq H^1(K)$ is a subspace of sufficiently regular functions for $S^K(\cdot, \cdot)$ to make sense.

Now, for any sufficiently regular functions, we introduce the following global semi-norms
$$\|v\|^2 := \sum_{K \in \mathcal{T}_h} \|v\|_K^2, \qquad |v|_{1,h}^2 := \sum_{K \in \mathcal{T}_h} \|\nabla v\|_{0,K}^2.$$

It has been proved in [11, Lemma 3.1] that there exist positive constants $C_1, C_2, C3$, independent of h, such that

$$C_1 \|\|v\|\|_K^2 \leq a_h^K(v,v) \leq C_2 \|\|v\|\|_K^2 \quad \forall v \in V^K, \tag{3.6}$$

$$a_h^K(v,v) \leq C3(\|\|v\|\|^2 + |v|_{1,K}^2) \quad \forall v \in V^K. \tag{3.7}$$

In addition, it holds

$$a^K(v,v) \leq C_4 \|\|v\|\|_K^2 \quad \forall v \in V^K, \tag{3.8}$$

$$\|\|p\|\|_K^2 \leq C_5 a^K(p,p) \quad \forall p \in \mathbb{P}_1(K),$$

where C_4, C_5 are independent of h.

Now we are in a position to write the virtual element discretization of Problem 1.

Problem 3. *Find $(\lambda_h, u_h) \in \mathbb{R} \times V_h$, $u_h \neq 0$, such that*

$$a_h(u_h, v_h) = \lambda_h b(u_h, v_h) \qquad \forall v_h \in V_h.$$

We use again a shift argument to rewrite this discrete eigenvalue problem in the following convenient equivalent form.

Problem 4. *Find $(\lambda_h, u_h) \in \mathbb{R} \times V_h$, $u_h \neq 0$, such that*

$$\widehat{\boldsymbol{a}}_h(u_h, v_h) = (\lambda_h + 1) b(u_h, v_h) \qquad \forall v_h \in V_h,$$

where the bilinear form $\widehat{\boldsymbol{a}}_h : V_h \times V_h \to \mathbb{R}$ is defined by

$$\widehat{\boldsymbol{a}}_h(u_h, v_h) := a_h(u_h, v_h) + b(u_h, v_h) \qquad u_h, v_h \in V_h.$$

Clearly $\widehat{\boldsymbol{a}}_h(\cdot, \cdot)$ is symmetric and continuous. In the following result we prove that $\widehat{\boldsymbol{a}}_h(\cdot, \cdot)$ is elliptic in V_h.

Lemma 3.1. *There exists a constant $\beta > 0$, independent of h, such that*

$$\widehat{\boldsymbol{a}}_h(v_h, v_h) \geq \beta \|v_h\|_{1,\Omega}^2 \qquad \forall v_h \in V_h.$$

Proof. From the definition of the bilinear form $\widehat{\boldsymbol{a}}_h(\cdot, \cdot)$, we have that

$$\widehat{\boldsymbol{a}}_h(v_h, v_h) = a_h(v_h, v_h) + b(v_h, v_h)$$
$$= \sum_{K \in \mathcal{T}_h} a_h^K(v_h, v_h) + b(v_h, v_h) \geq \sum_{K \in \mathcal{T}_h} C_1 \|\|v\|\|_K^2 + \|v_h\|_{0,\Gamma_0}^2 \geq C \sum_{K \in \mathcal{T}_h} a^K(v_h, v_h) + \|v_h\|_{0,\Gamma_0}^2$$
$$\geq C|v_h|_{1,\Omega}^2 + \|v_h\|_{0,\Gamma_0}^2 \geq \beta \|v_h\|_{1,\Omega}^2 \qquad \forall v_h \in V_h,$$

where we have used (3.6), (3.8) and the generalized Poincaré inequality. This concludes the proof. $\square$

With this coercivity result at hand, we are in a position to introduce the discrete solution operator

$$T_h : \ H^1(\Omega) \longrightarrow H^1(\Omega),$$
$$f \longmapsto T_h f := w_h,$$

where $u_h \in V_h$ is the solution of the following discrete source problem

$$\widehat{a}_h(w_h, v_h) = b(f, v_h) \qquad \forall v_h \in V_h.$$

Notice that Lemma 3.1 implies that the linear operator T_h is well defined and bounded uniformly with respect to h. Moreover, as in the continuous case, $(\lambda_h, u_h) \in \mathbb{R} \times V_h$ solves Problem 4 (and hence Problem 3) if and only if $T_h u_h = \mu_h u_h$ with $\mu_h \neq 0$ and $u_h \neq 0$, in which case $\mu_h := 1/(1 + \lambda_h)$. Also, $T_h|_{V_h} : V_h \longrightarrow V_h$ is self-adjoint with respect to $\widehat{a}_h(\cdot, \cdot)$.

As a consequence, we have the following spectral characterization for T_h.

Theorem 3.1. *The spectrum of $T_h|_{V_h}$ consists of $M_h := \dim(V_h)$ eigenvalues, repeated according to their respective multiplicities. It decomposes as follows: $\mathrm{sp}(T_h|_{V_h}) = \{0, 1\} \cup \{\mu_{hk}\}_{k=1}^{N_h}$, where:*

i) the eigenspace associated with $\mu_h = 1$ is the space of constant functions in Ω;

ii) the eigenspace associated with $\mu_h = 0$ is $Z_h := V_h \cap H^1_{\Gamma_0}(\Omega) = \{q_h \in V_h : q_h = 0 \text{ on } \Gamma_0\}$;

iii) $\mu_{hk} \subset (0, 1), \; k = 1, \ldots, N_h := M_h - \dim(Z_h) - 1,$ are non-defective eigenvalues repeated according to their respective multiplicities.

4. Convergence and error estimates

In order to prove that the solutions of the discrete problem converge to those of the continuous problem, we will follow the standard procedure for spectral theory for compact operators [5], which consist in showing that T_h converges in norm to T as h tends to zero.

With this end, we begin by proving the following result.

Lemma 4.1. *There exists $C > 0$, independent of h, such that, for all $f \in H^1(\Omega)$, if $w = Tf$ and $w_h = T_h f$, then*

$$\|w - w_h\|_{1,\Omega} \leq C \left(\|w - w_I\|_{1,\Omega} + |w_\pi - w|_{1,h} + \|w - w_I\| + \|w - w_\pi\| \right), \qquad (4.1)$$

for all $w_I \in V_h$ and for all $w_\pi \in L^2(\Omega)$ such that $w_\pi|_K \in \mathbb{P}_1(K) \; \forall K \in \mathcal{T}_h$. In addition

$$\|w_h - w_I\| \leq C \left(\|w - w_I\|_{1,\Omega} + |w_\pi - w|_{1,h} + \|w - w_I\| + \|w - w_\pi\| \right). \qquad (4.2)$$

Proof. Let $w = Tf$ and $w_h = T_h f$. From triangular inequality we have

$$\|w - w_h\|_{1,\Omega} \leq \|w - w_I\|_{1,\Omega} + \|w_I - w_h\|_{1,\Omega}.$$

Our task is to estimate the norms of the right hand side above. To do this, we will consider the arguments on the proof of Lemma 3.1.

Now, for $w_I \in V_h$, we set $v_h := w_h - w_I$ and thanks to Lemma 3.1, the definitions of $a_h^K(\cdot, \cdot)$

(cf. (3.4)) and those of T and T_h, we have

$$\left(\vert\!\vert\!\vert v_h \vert\!\vert\!\vert + \|v_h\|_{0,\Gamma_0}\right)^2 \leq 2\left(\vert\!\vert\!\vert v_h \vert\!\vert\!\vert^2 + \|v_h\|_{0,\Gamma_0}^2\right)$$

$$\leq C\widehat{a}_h(v_h,v_h) = C(\widehat{a}_h(w_h,v_h) - \widehat{a}_h(w_I,v_h))$$

$$= C\left(b(f,v_h) - \sum_{K\in\mathcal{T}_h} a_h^K(w_I,v_h) - b(w_I,v_h)\right)$$

$$= C\Big(b(f,v_h) - b(w_I,v_h)$$

$$- \sum_{K\in\mathcal{T}_h}\left(a_h^K(w_I - w_\pi, v_h) + a^K(w_\pi - w, v_h) + a^K(w,v_h)\right)\Big)$$

$$= C\left(b(w-w_I,v_h) - \sum_{K\in\mathcal{T}_h}\left(a_h^K(w_I - w_\pi, v_h) + a^K(w_\pi - w, v_h)\right)\right).$$

Therefore, from the trace theorem, (3.6) and the boundedness of $a_h^K(\cdot,\cdot)$ ((3.7)) and $a^K(\cdot,\cdot)$, we get

$$\left(\vert\!\vert\!\vert v_h \vert\!\vert\!\vert + \|v_h\|_{0,\Gamma_0}\right)^2 \leq C\Big(\|w - w_I\|_{0,\Gamma_0}\|v_h\|_{0,\Gamma_0}$$

$$+ \sum_{K\in\mathcal{T}_h}\left(C(\vert\!\vert\!\vert w_I - w_\pi \vert\!\vert\!\vert_K + |w_I - w_\pi|_{1,K})\vert\!\vert\!\vert v_h \vert\!\vert\!\vert_K + |w_\pi - w|_{1,K}|v_h|_{1,K}\right)\Big)$$

$$\leq C\left(\|w - w_I\|_{0,\Gamma_0}\|v_h\|_{0,\Gamma_0} + \sum_{K\in\mathcal{T}_h}\left\{C\left(\vert\!\vert\!\vert w_I - w_\pi \vert\!\vert\!\vert_K + |w_\pi - w|_{1,K}\right)\vert\!\vert\!\vert v_h \vert\!\vert\!\vert_K\right\}\right)$$

$$\leq C\left(\|w - w_I\|_{0,\Gamma_0} + \vert\!\vert\!\vert w_I - w_\pi \vert\!\vert\!\vert + |w_\pi - w|_{1,h}\right)\left(\|v_h\|_{0,\Gamma_0} + \vert\!\vert\!\vert v_h \vert\!\vert\!\vert\right).$$

Therefore, we have

$$\vert\!\vert\!\vert v_h \vert\!\vert\!\vert + \|v_h\|_{0,\Gamma_0} \leq \widetilde{C}\left(\|w - w_I\|_{1,\Omega} + \vert\!\vert\!\vert w - w_\pi \vert\!\vert\!\vert + \vert\!\vert\!\vert w - w_I \vert\!\vert\!\vert + |w_\pi - w|_{1,h}\right).$$

Finally, (4.1) follows from the triangular inequality and the generalized Poincaré inequality. Moreover, (4.2) follows from the above estimate. $\qquad\square$

Let us introduce the following approximation result for polynomials in star-shaped domains (see for instance [16]), which is derived by results of interpolation between Sobolev spaces (see for instance [29, Theorem I.1.4]), leading to an analogous result for integer values of s. Moreover, we remark that the result for integer values is stated in [7, Proposition 4.2] and follows from the well establish Scott-Dupont theory (see [16]).

Lemma 4.2. *If assumption* **A1** *is satisfied, then there exists a constant C, depending only on k and γ, such that for every s with $0 \leq s \leq k$ and for every $v \in H^{1+s}(K)$, there exists $v_\pi \in \mathbb{P}_k(K)$ such that*

$$\|v - v_\pi\|_{0,K} + h_K|v - v_\pi|_{1,K} \leq Ch_K^{1+s}\|v\|_{1+s,K}.$$

Now, we have the following approximation result in the virtual space V_h, which follows from [11, Theorem 3.4].

Lemma 4.3. *Under the assumption* **A1**, *then, for each s with $1/2 < s \le 1$, there exist $\widehat{t} > 1/2$ and a constant C, independent of h, such that for every $v \in H^{1+s}(\Omega)$, there exists $v_I \in V_h$ that satisfies*

$$|v - v_I|_{1+t,K} \le C h_K^{s-t} |v|_{1+s,K}, \qquad 0 \le t < \min\{\widehat{t}, s\}, \tag{4.3}$$

$$\|v - v_I\|_{0,K} \le C h_K |v|_{1+s,K}. \tag{4.4}$$

Proof. Estimate (4.3) has been obtained in [11, Theorem 3.4]. To obtain (4.4), with $1/2 < s \le 1$, first we use the Poincaré and the Cauchy-Schwarz inequalities, to obtain (see [13, Remark 4.1]),

$$
\begin{aligned}
\|v - v_I\|_{0,K} &\le C \left(\int_{\partial K} |v - v_I| ds + h_K |v - v_I|_{1,K} \right) \\
&\le C \left(h_K^{1/2} \|v - v_I\|_{0,\partial K} + h_K |v - v_I|_{1,K} \right) \\
&\le C \left(h_K^{1/2} h_K^{1/2} |v|_{1/2,\partial K} + h_K |v - v_I|_{1,K} \right) \\
&\le C \left(h_K |v|_{1,K} + h_K |v - v_I|_{1,K} \right) \\
&\le C h_K |v|_{1+s,K},
\end{aligned}
$$

where we have use an standard approximation estimate in one dimension, since $v_I|_{\partial K}$ corresponds to the standard piecewise linear Lagrange interpolant of v and then $|v|_{1/2,\partial K} \le |v|_{1,K}$. This concludes the proof. $\square$

Now we are in position to establish the convergence in norm of T_h to T as $h \to 0$.

Lemma 4.4. *There exists $r \in (1/2, 1]$ (cf. Lemma 2.2(i)) and $C > 0$, independent of h, such that*

$$\|(T - T_h) f\|_{1,\Omega} \le C h^r \|f\|_{1,\Omega} \qquad \forall f \in H^1(\Omega).$$

Proof. The result follows from Lemma 4.1. In particular, we have to bound the term on the right and side of (4.1). For the first and second terms, using Lemmas 4.3 and 4.2, respectively, we obtain

$$\|w - w_I\|_{1,\Omega} + |w - w_\pi|_{1,h} \le C \sum_{K \in \mathcal{T}_h} h_K^r |w|_{1+r} \le C h^r |w|_{1+r,\Omega}. \tag{4.5}$$

Now, we bound the term $\|w - w_I\|$. To do this task, we invoke the definition of $\|\cdot\|$ given in (3.5), (3.1) and, operating as in the proof of [11, Theorem 4.5] we have

$$
\begin{aligned}
\sum_{K \in \mathcal{T}_h} \|w - w_I\|_K^2 &= \sum_{K \in \mathcal{T}_h} \left\{ a^K \left(\Pi^K (w - w_I), \Pi^K (w - w_I) \right) \right. \\
&\quad \left. + S^K \left((w - w_I) - \overline{(w - w_I)}, (w - w_I) - \overline{(w - w_I)} \right) \right\} \\
&\le C \sum_{K \in \mathcal{T}_h} \left(|\Pi^K (w - w_I)|_{1,K}^2 + S^K (w - w_I, w - w_I) \right) \\
&= C \sum_{K \in \mathcal{T}_h} \left(|w - w_I|_{1,K}^2 + h_K |w - w_I|_{1,\partial K}^2 \right). \tag{4.6}
\end{aligned}
$$

Let σ be such that $1/2 < \sigma < r$, using a scaled trace inequality, we get

$$h_K |w - w_I|_{1,\partial K}^2 \le C \left(|w - w_I|_{1,K}^2 + h^{2\sigma} |w - w_I|_{1+\sigma,K}^2 \right) \le C h_K^{2r} |w|_{1+r,K}^2.$$

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Using the above estimate in (4.6) and Proposition 4.3, we obtain

$$\||w - w_I\|| = \left(\sum_{K \in \mathcal{T}_h} \||w - w_I\||_K^2 \right)^{1/2} \leq C \left(\sum_{K \in \mathcal{T}_h} h_K^{2r} |w|_{1+r,K}^2 \right) \leq Ch^r |w|_{1+r,\Omega}. \qquad (4.7)$$

Similarly, we obtain

$$\||w - w_\pi\|| \leq Ch^r |w|_{1+r,\Omega}.$$

thus, the lemma follows from (4.5)–(4.7) and Lemma 2.2(i). $\qquad \square$

We conclude the analysis of our paper deriving error estimates for our method. In particular, we are going to present error estimates for eigenfunctions and eigenvalues. With this aim, with Lemma 4.4 at hand, we will prove that isolated parts of $\mathrm{sp}(T)$ are approximated by isolated parts of $\mathrm{sp}(T_h)$ (see [31]).

Let $\mu \in (0,1)$ be an isolated eigenvalue of T with multiplicity m and let $\mathcal{E}$ be its associated eigenspace. Then, there exist m eigenvalues $\mu_h^{(1)}, \ldots, \mu_h^{(m)}$ of T_h (repeated according to their respective multiplicities) which converge to μ. From now and on, let $\mathcal{E}_h$ be the discrete subspace associated to $\mathcal{E}$, corresponding to the direct sum of their corresponding associated eigensapaces.

We recall the definition of the *gap* $\widehat{\delta}$ between two closed subspaces $\mathcal{X}$ and $\mathcal{Y}$ of $H^1(\Omega)$:

$$\widehat{\delta}(\mathcal{X}, \mathcal{Y}) := \max\left\{ \delta(\mathcal{X}, \mathcal{Y}), \delta(\mathcal{Y}, \mathcal{X}) \right\}, \quad \text{where} \quad \delta(\mathcal{X}, \mathcal{Y}) := \sup_{x \in \mathcal{X}: \, \|x\|_{1,\Omega}=1} \left(\inf_{y \in \mathcal{Y}} \|x - y\|_{1,\Omega} \right).$$

The following error estimates for the approximation of eigenvalues and eigenfunctions hold true.

Theorem 4.1. *There exists a strictly positive constant C such that*

$$\widehat{\delta}(\mathcal{E}, \mathcal{E}_h) \leq C\gamma_h,$$
$$\left| \mu - \mu_h^{(i)} \right| \leq C\gamma_h, \qquad i = 1, \ldots, m,$$

where

$$\gamma_h := \sup_{f \in \mathcal{E}: \, \|f\|_{1,\Omega}=1} \|(T - T_h)f\|_{1,\Omega}.$$

Proof. As a consequence of Lemma 4.4, T_h converges in norm to T as h goes to zero. Then, the proof follows as a direct consequence of Theorems 7.1 and 7.3 from [5]. $\qquad \square$

The theorem above yields error estimates depending on γ_h. The next step is to show an optimal order estimate for this term.

Theorem 4.2. *There exist $r \in (1/2, 1]$ and a positive constant C such that*

$$\|(T - T_h)f\|_{1,\Omega} \leq Ch^r \|f\|_{1,\Omega} \qquad \forall f \in \mathcal{E},$$

and, consequently,

$$\gamma_h \leq Ch^r.$$

Proof. See [37, Theorem 4.2]. $\qquad \square$

The error estimate for the eigenvalue $\mu \in (0,1)$ of T leads to an analogous estimate for the approximation of the eigenvalue $\lambda = \frac{1}{\mu} - 1$ of Problem 1 by means of the discrete eigenvalues $\lambda_h^{(i)} := \frac{1}{\mu_h^{(i)}} - 1$, $1 \leq i \leq m$, of Problem 3.

We are able to improve the convergence order of Theorem 4.1 for the eigenvalues. The following result shows in fact that the convergence order is double.

Theorem 4.3. *There exist $r \in (1/2, 1]$ and a positive constant C such that*

$$\left| \lambda - \lambda_h^{(i)} \right| \leq Ch^{2r}.$$

Proof. Let u_h be such that $(\lambda_h^{(i)}, u_h)$ is a solution of Problem 3 with $\|u_h\|_{1,\Omega} = 1$. According to Theorems 4.1 and 4.2, there exists a solution (λ, u) of Problem 1 such that

$$\|u - u_h\|_{1,\Omega} \leq Ch^r. \tag{4.8}$$

From the symmetry of the bilinear forms and the facts that $a(u,v) = \lambda b(u,v)$ for all $v \in H^1(\Omega)$ (cf. Problem 1) and $a_h(u_h, v_h) = \lambda_h^{(i)} b(u_h, v_h)$ for all $v_h \in V_h$ (cf. Problem 3), we have

$$a(u - u_h, u - u_h) - \lambda b(u - u_h, u - u_h) = a(u_h, u_h) - \lambda b(u_h, u_h)$$
$$= [a(u_h, u_h) - a_h(u_h, u_h)] - \left(\lambda - \lambda_h^{(i)} \right) b(u_h, u_h),$$

from which we obtain the following identity:

$$\left(\lambda_h^{(i)} - \lambda \right) b(u_h, u_h) = a(u - u_h, u - u_h) - \lambda b(u - u_h, u - u_h) + [a_h(u_h, u_h) - a(u_h, u_h)]. \tag{4.9}$$

The next step is to bound each term on the right hand side above. The first and the second ones are easily bounded from the continuity of $a(\cdot, \cdot)$ and $b(\cdot, \cdot)$, the trace theorem and (4.8) as follows

$$|a(u - u_h, u - u_h)| + \lambda |b(u - u_h, u - u_h)| \leq Ch^{2r}. \tag{4.10}$$

For the last term on the right hand side of (4.9), we consider $u_\pi \in \mathbb{P}_1(K)$ and $u_I \in V_h$ such that Lemmas 4.2 and 4.3 hold true, respectively. Using standard arguments, we have

$$|a_h(u_h, u_h) - a(u_h, u_h)| = \left| \sum_{K \in \mathcal{T}_h} a_h^K (u_h - u_\pi, u_h - u_\pi) - a^K (u_h - u_\pi, u_h - u_\pi) \right|$$
$$\leq \sum_{K \in \mathcal{T}_h} \|u_h - u_\pi\|_K^2 + \sum_{K \in \mathcal{T}_h} |u_h - u_\pi|_{1,K}^2$$
$$= \|u_h - u_\pi\|^2 + |u_h - u_\pi|_{1,h}^2$$
$$\leq C \left(\|u - u_h\|^2 + \|u - u_\pi\|^2 + |u - u_h|_{1,h}^2 + |u - u_\pi|_{1,h}^2 \right)$$
$$\leq C \left(\|u - u_I\|^2 + \|u_h - u_I\|^2 + \|u - u_\pi\|^2 + |u - u_h|_{1,h}^2 + |u - u_\pi|_{1,h}^2 \right)$$
$$\leq C \left(\|u - u_I\|^2 + \|u - u_\pi\|^2 + \|u - u_I\|_{1,\Omega}^2 + |u - u_\pi|_{1,h}^2 + |u_h - u|_{1,\Omega}^2 \right),$$

where we have used (4.2). Now, the terms on the right hand side above can be bounded repeating the argument in the proof of Lemma 4.4 and using the additional regularity result in Lemma 2.2(ii). We get

$$|a_h(u_h, u_h) - a(u_h, u_h)| \leq Ch^{2r}. \tag{4.11}$$

On the other hand, by virtue of Lemma 3.1 and the fact that $\lambda_h^{(i)} \to \lambda$ as h goes to zero, we know that there exists $C > 0$ such that

$$b(u_h, u_h) = \frac{\widehat{\boldsymbol{a}}_h(u_h, u_h)}{\lambda_h^{(i)} + 1} \geq \frac{\beta \|u_h\|_{1,\Omega}^2}{\lambda_h^{(i)} + 1} \geq \frac{\beta}{C} > 0.$$

Finally, the proof follows from (4.9), by using the above estimate together with (4.10) and (4.11).

$\square$

5. Numerical experiments

In the present section we will report some numerical tests in order to asses the performance of the proposed lowest order VEM with meshes allowing small edges. All the reported numerical results have been obtained with a MATLAB code. In order to observe the performance and accuracy of the proposed method, we will consider different computational domains, where the eigenfunctions, on one hand, can be smooth enough and, on the other, can be singular due to the non-convex domains.

For all the tests, we will report the computed eigenvalues for different polygonal meshes and the order of convergence. Our results will be compared with some references and exact solutions in the cases where it is available. In the cases where it is not possible to have a close form of the solution, we will present extrapolated values for the eigenvalues (see (5.13)).

5.1. Square domain: the sloshing problem.

We begin with a convex domain. In this case we consider $\Omega := (0,1)^2$ as computational domain. We fix Γ_0 on the top of the boundary (representing a free surface) and Γ_1 will the rest of the boundary. In Figure 1, we present the physical configuration of the problem.
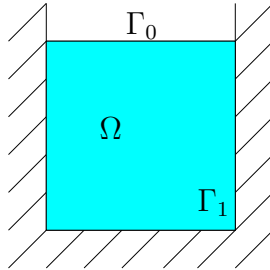

Figure 1: Sloshing in a square domain.

For this problem there are analytical solutions of the form

$$\lambda_n = n\pi \tanh(n\pi), \quad u_n(x,y) = \cos(n\pi x)\sinh(n\pi x), \quad n \in \mathbb{N}. \tag{5.12}$$

In Figure 2, we present plots of the polygonal meshes that we will consider for our tests. We note that the family of polygonal meshes $\mathcal{T}_h^1$ have been obtained by gluing two different polygonal meshes at $y = 0.6$. It can be seen that very small edges compared with the element diameter appears on the interface of the resulting mesh. The second family of polygonal meshes $\mathcal{T}_h^2$ have

been obtained from a triangular mesh with an additional point on each edge as a new degree of freedom which has been moved to a distance h_e^2 from one vertex and $(h_e - h_e^2)$ from the other. We observe that this family satisfy **A1** but fail to satisfy the usual assumption that distance between any two of its vertices is greater than or equal to Ch_K for each polygon, since the length of the smallest edge is h_e^2, while the diameter of the element is bounded above by a multiple of h_e. The refinement level for the meshes will be denoted by N, which corresponds to the number of subdivisions in the abscissae.
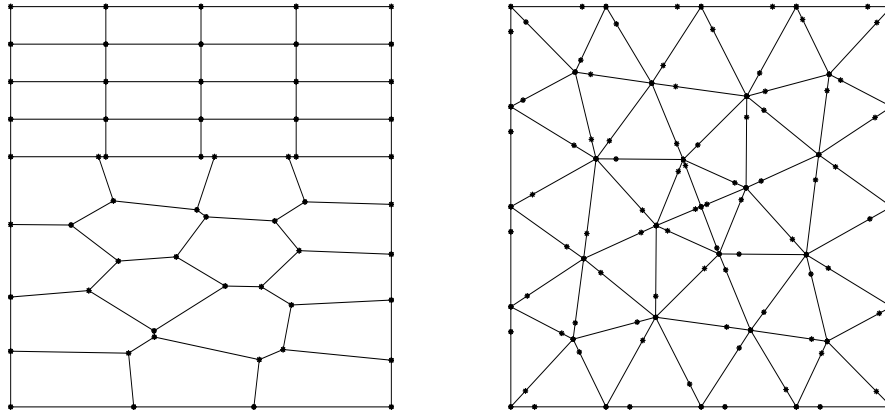

Figure 2: Sample meshes with small edges. From left to right: $\mathcal{T}_h^1$ and $\mathcal{T}_h^2$ for $N = 4$.

In Table 1, we report the first six eigenvalues computed with meshes $\mathcal{T}_h^1$ and $\mathcal{T}_h^2$. The row 'Order' reports the convergence order of the eigenvalues, computed with respect to the exact ones obtained with (5.12), which are presented in the row 'Exact'.

Table 1: Test1. The lowest computed eigenvalues λ_{hi}, $1 \leq i \leq 6$ for different meshes.

$\mathcal{T}_h^1$						
N	λ_{h1}	λ_{h2}	λ_{h3}	λ_{h4}	λ_{h5}	λ_{h6}
8	3.2422	7.1802	12.5152	19.0595	32.2326	46.9310
16	3.1572	6.4936	10.1363	14.2689	19.0754	24.7519
32	3.1366	6.3347	9.5984	12.9787	16.5158	20.2508
64	3.1316	6.2960	9.4679	12.6686	15.9078	19.1953
Order	2.02	2.04	2.05	2.00	2.12	2.12
Exact	3.1299	6.2831	9.4248	12.5664	15.7080	18.8496
$\mathcal{T}_h^2$						
N	λ_{h1}	λ_{h2}	λ_{h3}	λ_{h4}	λ_{h5}	λ_{h6}
8	3.1820	6.7247	10.9616	16.4556	23.3067	31.7699
16	3.1441	6.4043	9.8511	13.6063	17.7749	22.5294
32	3.1336	6.3135	9.5285	12.8170	16.2084	19.7245
64	3.1308	6.2907	9.4503	12.6275	15.8287	19.0608
Order	1.94	1.96	1.98	2.00	2.00	1.99
Exact	3.1299	6.2831	9.4248	12.5664	15.7080	18.8496

The order of convergence is clearly $\mathcal{O}(h^2)$, which is expectable according to Theorem 4.3 and due the smoothness of the eigenfunctions for this configuration of the problem. Moreover, the nature of the meshes and the fact that we are allowing small edges for the polygons, does not affect the order of convergence and no spurious eigenvalues were found.

In the next test, we will study the effects of the stabilization (3.3) in the computation of the spectrum. We will consider the same physical configuration as in the previous test. Since the stabilization depends on the size of the element K (see (3.3)), we will compute the first six eigenvalues for different values h_K^α using the family of meshes $\mathcal{T}_h^2$.

Table 2: Test2. The lowest computed eigenvalues λ_{hi}, $1 \leq i \leq 6$ for different h_K^α, $\alpha = \{1/2, 3/4, 1, 5/4, 3/2\}$ with meshes $\mathcal{T}_h^2$.

h_K^α	N	λ_{h1}	λ_{h2}	λ_{h3}	λ_{h4}	λ_{h5}	λ_{h6}
	8	3.1906	6.8000	11.2387	17.2492	24.8335	34.3717
	16	3.1456	6.4174	9.8977	13.7232	18.0174	22.9781
$h_K^{1/2}$	32	3.1338	6.3154	9.5349	12.8325	16.2400	19.7798
	64	3.1308	6.2909	9.4511	12.6295	15.8327	19.0678
	Order	2.00	2.02	2.04	2.08	2.07	2.06
	Exact	3.1299	6.2831	9.4248	12.5664	15.7080	18.8496
h_K^α	N	λ_{h1}	λ_{h2}	λ_{h3}	λ_{h4}	λ_{h5}	λ_{h6}
	8	3.1875	6.7730	11.1386	16.9596	24.2790	33.4292
	16	3.1451	6.4133	9.8829	13.6861	17.9400	22.8346
$h_K^{3/4}$	32	3.1337	6.3148	9.5331	12.8282	16.2313	19.7645
	64	3.1308	6.2908	9.4509	12.6290	15.8317	19.0662
	Order	1.98	2.00	2.02	2.05	2.04	2.03
	Exact	3.1299	6.2831	9.4248	12.5664	15.7080	18.8496
h_K^α	N	λ_{h1}	λ_{h2}	λ_{h3}	λ_{h4}	λ_{h5}	λ_{h6}
	8	3.1820	6.7247	10.9616	16.4556	23.3067	31.7699
	16	3.1441	6.4043	9.8511	13.6063	17.7749	22.5294
h_E	32	3.1336	6.3135	9.5285	12.8170	16.2084	19.7245
	64	3.1308	6.2907	9.4503	12.6275	15.8287	19.0608
	Order	1.94	1.96	1.98	2.00	2.00	1.99
	Exact	3.1299	6.2831	9.4248	12.5664	15.7080	18.8496
h_K^α	N	λ_{h1}	λ_{h2}	λ_{h3}	λ_{h4}	λ_{h5}	λ_{h6}
	8	3.1728	6.6440	10.6696	15.6472	21.7299	29.0670
	16	3.1420	6.3861	9.7866	13.4455	17.4448	21.9242
$h_K^{5/4}$	32	3.1332	6.3101	9.5170	12.7889	16.1512	19.6248
	64	3.1307	6.2901	9.4483	12.6228	15.8194	19.0444
	Order	1.88	1.90	1.91	1.93	1.92	1.91
	Exact	3.1299	6.2831	9.4248	12.5664	15.7080	18.8496
h_K^α	N	λ_{h1}	λ_{h2}	λ_{h3}	λ_{h4}	λ_{h5}	λ_{h6}
	8	3.1585	6.5223	10.2377	14.5052	19.4815	25.2098
	16	3.1382	6.3532	9.6706	13.1590	16.8635	20.8743
$h_K^{3/2}$	32	3.1323	6.3026	9.4912	12.7263	16.0248	19.4044
	64	3.1305	6.2885	9.4430	12.6098	15.7937	18.9992
	Order	1.81	1.83	1.83	1.83	1.82	1.81
	Exact	3.1299	6.2831	9.4248	12.5664	15.7080	18.8496

We observe from the results of Table 2 that the method converges to the exact eigenvalues with an optimal quadratic order and no spurious eigenvalues were found for any chosen stability parameter h_K^α. We remark that these results are also valid for other type of family polygonal meshes allowing small edges.

5.2. Rotated T domain

In the following test we will consider a non-convex domain which we call *rotated T* an it is defined by $\Omega_T := (-0.5, 0.5) \times (-0.5, 0) \cup (-0.25, 0.25) \times (0, 1)$ with boundary condition $\Gamma_0 = \partial \Omega_T$. This non-convex domain presents two reentrant angles of the same size $\omega = \frac{3\pi}{2}$ (cf. Figure 3), and as a consequence, the eigenfunctions of this problem may present singularities. More precisely, the Sobolev exponent for the eigenfunctions is $2/3$ (cf. Remark 2.1), so that the eigenfunctions will belong to $H^{1+r}(\Omega)$ for all $r < 2/3$, but in general not to $H^{1+\frac{2}{3}}(\Omega)$. Therefore, according to Theorem 4.3, the convergence rate for the eigenvalues should be $|\lambda - \lambda_h| \approx h^{4/3}$.

In Figure 3, we present the meshes that we will consider for this numerical test. We note that the families of polygonal meshes $\mathcal{T}_h^3$, $\mathcal{T}_h^4$ and $\mathcal{T}_h^5$ have been obtained by gluing two different polygonal meshes at $x = 0$. It can be seen that very small edges compared with the element diameter appears on the interface of the resulting meshes.
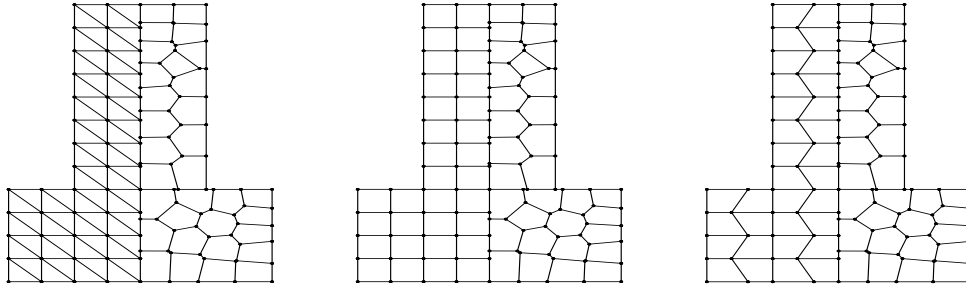

Figure 3: Sample meshes with small edges. From left to right: $\mathcal{T}_h^3$, $\mathcal{T}_h^4$ and $\mathcal{T}_h^5$, for $N = 8$.

In Table 3, we report the computed eigenvalues and the corresponding convergence rates, the last row, that we called 'Extrap.', corresponds to extrapolated values obtained with a least square fitting of the form

$$\lambda_{hi} \approx \lambda_i + C_i h^{\alpha_i}, \tag{5.13}$$

where α_i is the approximated rate of convergence of each λ_i, with $i \in \mathbb{N}$.

Table 3: Test 2. Computed lowest eigenvalues λ_h^i, $1 \leq i \leq 4$, on different polygonal meshes.

$\mathcal{T}_h$	λ_h^i	$N = 16$	$N = 30$	$N = 62$	$N = 130$	Order	Extrap.
$\mathcal{T}_h^3$	λ_h^1	0.5196	0.5157	0.5140	0.5134	1.41	0.5130
	λ_h^2	1.2743	1.2622	1.2570	1.2552	1.48	1.2543
	λ_h^3	2.5567	2.5263	2.5146	2.5111	1.65	2.5096
	λ_h^4	3.1923	3.1556	3.1458	3.1437	2.19	3.1432
$\mathcal{T}_h^4$	λ_h^1	0.5209	0.5163	0.5142	0.5135	1.41	0.5131
	λ_h^2	1.2793	1.2641	1.2577	1.2555	1.51	1.2545
	λ_h^3	2.5659	2.5296	2.5158	2.5115	1.66	2.5098
	λ_h^4	3.2144	3.1616	3.1474	3.1441	2.16	3.1434
$\mathcal{T}_h^5$	λ_h^1	0.5209	0.5163	0.5142	0.5135	1.41	0.5131
	λ_h^2	1.2795	1.2641	1.2577	1.2555	1.52	1.2545
	λ_h^3	2.5663	2.5296	2.5158	2.5115	1.66	2.5098
	λ_h^4	3.2143	3.1616	3.1474	3.1441	2.16	3.1434

We observe from Table 3 that for the first Steklov eigenvalue the method converges with order close to 4/3 which corresponds to the Sobolev regularity for the Steklov problem on Ω_T (non-convex domain). We also note that the method converges larger orders for the rest of the Steklov eigenvalues.

In Figure 4 we present plots for the first four eigenfunctions for the Steklov problem in the *rotated* T domain, computed with $\mathcal{T}_h^5$ and $N = 30$.
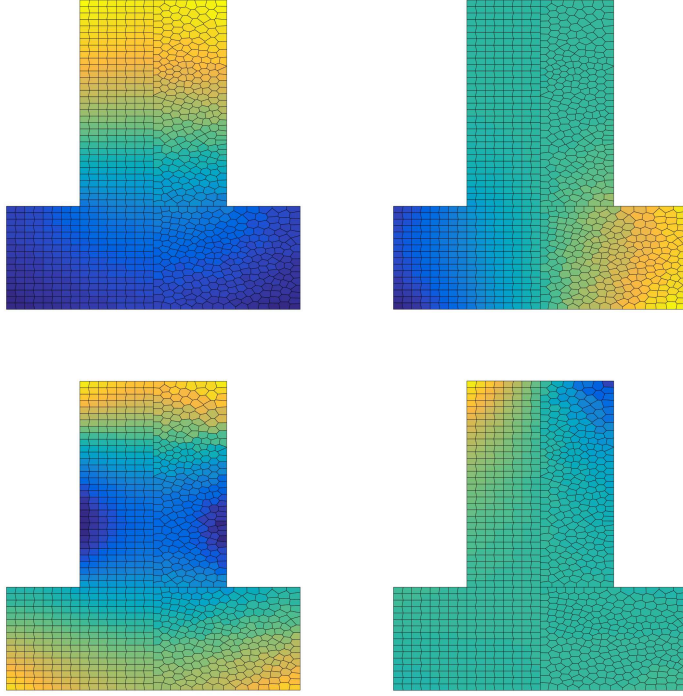
Figure 4: From top left to bottom right, plots of the first four eigenfunctions for the *rotated T* domain, computed with $\mathcal{T}_h^5$.

5.3. L-shaped domain

In this numerical example we test the properties of the proposed method on an L-shaped domain: $\Omega_L := (0,1) \times (0,1) \backslash [0.5, 1) \times [0.5, 1)$ with $\Gamma_0 = \partial\Omega_L$. For this test, we will adopt a refinement with hanging nodes, which implies to consider once again polygons with small edges. More precisely, this test is focused to validate the use of refined meshes as a tool to handle solutions with corner singularities. With this purpose, we have considered two families of meshes, namely: $\mathcal{T}_h^6$ (see upper left picture in Figure 5) and $\mathcal{T}_h^{6,\ell}$. The initial uniform mesh $\mathcal{T}_h^6$ has $N = 32$ elements on each edge and the last one has $N = 128$ elements on each edge.

On the other hand, the mesh $\mathcal{T}_h^{6,\ell}$ is obtained by refining a patch around the re-entrant corner of Ω_L, starting from an initial uniform quadrilateral mesh $\mathcal{T}_h^{6,0}$, which corresponds to the first mesh of $\mathcal{T}_h^6$. The procedure consists in to split each element which belongs to the region:

$$R_\ell := \left\{ (x,y) \in \mathbb{R}^2 : |x - 1/2| \leq \frac{6}{N}2^{1-\ell} \quad \text{and} \quad |y - 1/2| \leq \frac{6}{N}2^{1-\ell} \right\} \cap \overline{\Omega}_L \qquad \ell = 1, 2, \ldots, \widehat{\ell},$$

into three quadrilaterals by connecting the barycenter of the element with the midpoint of each edge, where $\widehat{\ell}$ is the number of meshes to refine, with the convention that $\mathcal{T}_h^{6,0} := \mathcal{T}_h^6$ (the initial mesh with $N = 32$). Note that although this process is initiated with a quadrilateral mesh, the successively created meshes will contain other kind of convex polygons as can be appreciated in Figure 5.
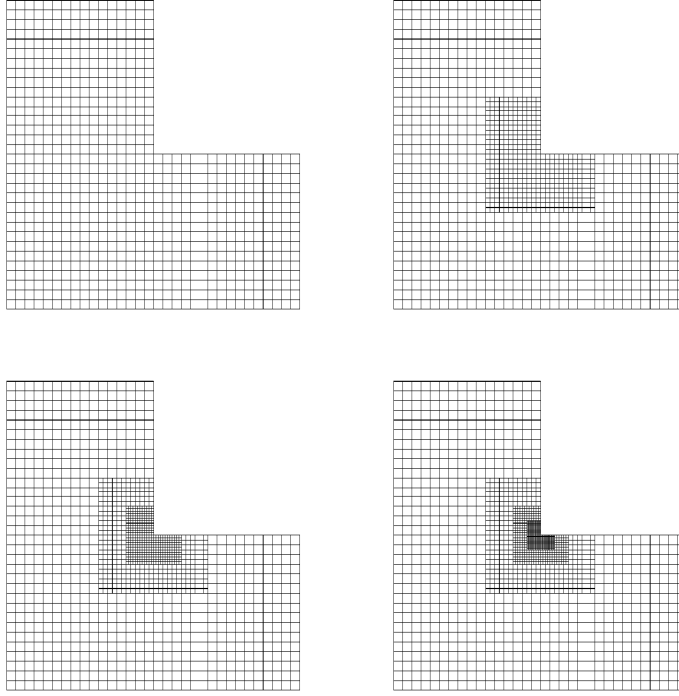
Figure 5: Sample meshes: inicial mesh $\mathcal{T}_h^6$ with $N = 16$ (top left), $\mathcal{T}_h^{6,1}$ (top right), $\mathcal{T}_h^{6,2}$ (bottom left) and $\mathcal{T}_h^{6,3}$ (bottom right).

Table 4: Test 3. Test with an L-shaped domain. Number of degrees of freedom, computed lowest eigenvalue and error, by using uniform square meshes and polygonal meshes with hanging nodes.

$\mathcal{T}_h$	Dofs	λ_h^1	Error
	833	0.78073215782	0.00628166703
$\mathcal{T}_h^6$	3201	0.77689137854	0.00244088775
	12545	0.77539520174	0.00094471094
ref.		0.77445049080	–
$\mathcal{T}_h^{6,0}$	833	0.78073215782	0.00628166703
$\mathcal{T}_h^{6,1}$	1181	0.77728198716	0.00283149637
$\mathcal{T}_h^{6,2}$	1529	0.77598279448	0.00153230369
$\mathcal{T}_h^{6,3}$	1877	0.77548305066	0.00103255987
$\mathcal{T}_h^{6,4}$	2232	0.77528749982	0.00083700903
ref.		0.77445049080	–

Table 4 reports the lowest Steklov eigenvalue computed on an L-shaped domain with the method analyzed in this paper with different polygonal meshes. The table also includes the corresponding 'Errors' which have been obtained against a reference value 'ref.' which corresponds to extrapolated values obtained with a least square fitting on finer uniform meshes.

It can be seen from Table 4 that the reported errors are similar in the last row of each mesh;

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however, the dofs in the case of corner-refined meshes are much less than the case of uniform meshes. Therefore, we conclude that the possibility of using small edges in the polygons of the mesh, allow us easier refinements near edges and/or corners of the domain to handle solutions with corner singularities.

Acknowledgments

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